Quasi-linear PDEs (III)

Conservation laws, shock dynamics and weak solutions

Conservation laws

A conservation law has the general form:

$$\frac{\partial}{\partial t}T(x,t) + \frac{\partial}{\partial x}X(x,t) = 0$$

where T(x,t) is the density of the conserved quantity and X(x,t) is the associated flux.

Integrating with respect to x, the conservation law can be expressed in the following integral form:

$$\frac{\partial}{\partial t} \int_{x_1}^{x_2} T(x,t) \, dx = -X(x,t) \Big|_{x=x_1}^{x_2}$$

i.e., the rate of change of the density over an interval depends only on the flux through its end points

If
$$X(x_2,t)=X(x_1,t)$$
 then $\int_a^b T(x,t) dx = \text{const. conserved quantity}$

Examples

1) Linearized KdV equation: $u_t + u_{xxx} = 0$ (1)

This equation is already in the form of conservation law:

$$(u)_{t} + (u_{xx})_{x} = 0, \quad T_{1} = u, \quad X_{1} = u_{xx}$$

$$\int_{-\infty}^{+\infty} T_{1} dx = \int_{-\infty}^{+\infty} u \, dx = \text{mass} = \text{const.};$$

Also, from Parseval's theorem, linear dispersive equations with real $\omega(k)$ conserve the energy [Can you show this?]

Indeed, multiplying (1) by u we find:

$$(u^{2})_{t} + \left(uu_{xx} - \frac{1}{2}u_{x}^{2}\right)_{x} = 0, \quad T_{2} = u^{2}, \quad X_{2} = uu_{xx} - \frac{1}{2}u_{x}^{2}$$

$$\int_{-\infty}^{+\infty} T_{2}dx = \int_{-\infty}^{+\infty} u^{2}dx = \text{energy} = \text{const.}$$

Examples – cont.

2) Schrödinger equation: $i\psi_t + \frac{1}{2}\psi_{xx} - V(x)\psi = 0$ (2)

Multiplying (2) by $\overline{\psi}$, its c.c. by ψ , and adding, we find:

$$(\left|\psi\right|^2)_t + \left(\frac{i}{2}(\overline{\psi}\psi_x - \psi\overline{\psi}_x)\right)_x = 0, \quad T = \left|\psi\right|^2,$$

$$\int_{-\infty}^{+\infty} |\psi|^2 dx = \text{const.}, \quad X = \frac{i}{2} (\overline{\psi} \psi_x - \psi \overline{\psi}_x) = \text{current}$$

3) Hopf equation: $u_t + uu_x = 0$, (3)

$$(u)_t + \left(\frac{1}{2}u^2\right)_x = 0, \quad T = u, \quad X = \frac{1}{2}u^2,$$

Additional comments on the Hopf equation

Consider the Hopf equation: $u_t + uu_x = 0$, u(x,0) = f(x) and assume that u(x,t) represents a density; then:

$$M_{x_1,x_2} = \int_{x_1}^{x_2} u(x,t) dx$$
: total mass in $x \in [x_1,x_2]$

Using the conservation law and its integral form we obtain:

$$(u)_{t} + \left(\frac{1}{2}u^{2}\right)_{x} = 0 \Rightarrow \frac{d}{dt} \int_{x_{1}}^{x_{2}} u dx = \underbrace{\frac{dM_{x_{1}, x_{2}}}{dt}}_{x_{1}} = \underbrace{\frac{1}{2}u^{2}(x_{1}, t) - \frac{1}{2}u^{2}(x_{2}, t)}_{x_{2}}$$

rate of change of mass

net mass / flux through the endpoints

E.g., in the traffic flow problem: u(x,t) = traffic density;Rate of change of # of vehicles in $[x_1,x_2] = \{ \text{# of vehicles entering } x_1 \} - \{ \text{# of vehicles leaving at } x_2 \}$

Additional comments on the Hopf equation

Assume that the initial data, f(x), has a finite mass:

$$u(x,0) = f(x), \quad \left| \int_{-\infty}^{+\infty} f(x,t) \, dx \right| < \infty$$

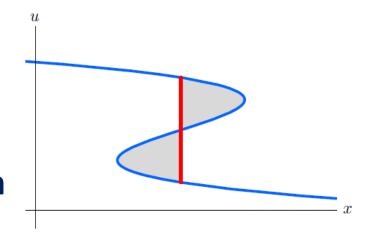
i.e., $f(x) \rightarrow 0$ rapidly as $x \rightarrow \infty$. Then,

$$\int_{-\infty}^{+\infty} u(x,t) dx = \int_{-\infty}^{+\infty} u(x,0) dx = \int_{-\infty}^{+\infty} f(x) dx = \text{const.}$$

i.e., mass remains constant - and is equal to its initial value

What happens in the case of a shock, where u(x,t) displays a discontinuity?

Equal Area Rule: it ensures that the total mass of the shock wave solution remains constant



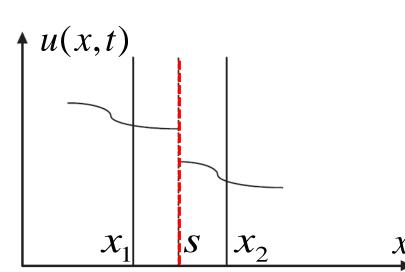
Shock waves and conservation laws

- We wish to take the solution further in time, beyond t = t_B, but do not want multi-valued solutions for physical and mathematical reasons
- Discontinuities, i.e., shocks, can be introduced by considering the Hopf equation as coming from the above mentioned conservation law and its corresponding integral form:

$$u_t + \left(\frac{1}{2}u^2\right)_x = 0 \Rightarrow \frac{d}{dt} \int_{x_1}^{x_2} u(x,t) dx + \frac{1}{2} \left[u^2(x_2,t) - u^2(x_1,t)\right] = 0$$

This equation can support a shock wave since it is an **integral relation**.

Assume that between two points x_1 and x_2 we have a discontinuity that can change in time, x = s(t)



Rankine-Hugoniot (RH) condition (I)

Then, we rewrite the integral form of the conservation law as:

$$\frac{d}{dt} \left[\int_{x_1}^{s(t)} u(x,t) dx + \int_{s(t)}^{x_2} u(x,t) dx \right] + \frac{1}{2} \left[u^2(x_2,t) - u^2(x_1,t) \right] = 0$$

Let:
$$\begin{cases} x_1 = s(t) - \varepsilon \\ x_2 = s(t) + \varepsilon \end{cases} \text{ with } \varepsilon > 0.$$

Next, using Leibnitz integral rule we obtain:

$$u(s,t)\frac{ds}{dt} - u(s-\varepsilon,t)\frac{ds}{dt} + \int_{s-\varepsilon}^{s} u_t(x,t)dt$$

$$+ u(s+\varepsilon,t)\frac{ds}{dt} - u(s,t)\frac{ds}{dt} + \int_{s}^{s+\varepsilon} u_t(x,t)dt$$

$$+ \frac{1}{2} \left[u^2(s+\varepsilon,t) - u^2(s-\varepsilon,t) \right] = 0$$

Rankine-Hugoniot (RH) condition (II)

Thus:
$$\frac{ds}{dt} \left[u(s+\varepsilon,t) - u(xs-\varepsilon,t) \right] + \int_{s-\varepsilon}^{s} u_t dt + \int_{s}^{s+\varepsilon} u_t dt + \int_{s$$

In the limit
$$\varepsilon \to 0$$
:

Hence:

$$\frac{ds}{dt} \Big[u(x^{-}, t) - u(x^{+}, t) \Big] + \frac{1}{2} \Big[u^{2}(x^{+}, t) - u^{2}(x^{-}, t) \Big] = 0 \Longrightarrow$$

$$\left[\frac{ds}{dt} = \frac{1}{2} \left[u(x^+, t) + u(x^-, t) \right] = \frac{1}{2} (u^+ + u^-), \quad u^{\pm} = u(x^{\pm}, t)$$

speed of the shock in terms of the jump discontinuities

Generalization of the RH condition

Consider the Hopf equation: $u_t + c(u)u_x = 0$

$$u_t + c(u)u_x = 0$$

and assume that F is the **antiderivative** of c(u), i.e., F'(u) = c(u)

Then, the Hopf equation can be written as the conservation law:

$$u_t + \frac{\partial}{\partial x} (F(u)) = 0$$

In this case, the **Rankine-Hugoniot condition** take the form:

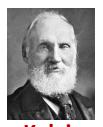
$$\frac{ds}{dt} = \frac{F(u_+, t) - F(u_-, t)}{u_+ - u_-}$$

$$s'(t)[u] = [F(u)]$$
 Jump condition

where [g] denotes the jump of g along a discontinuity

Rankine-Hugoniot condition - history

- They are named in recognition of work carried out by William Rankine (Scottish) in 1870 and Pierre Henri Hugoniot (French) in 1887
- They were originally found by Sir George Stokes (Irish) in 1848 and Bernhard Riemann (German) in 1860
- Lord Kelvin (Irish) and Lord Rayleigh (English) criticized Stokes' work.



Kelvin Rayleigh







P. Hugoniot





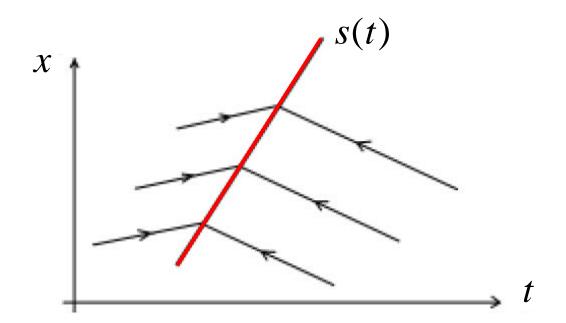


B. Riemann

■ Stokes thought that he was wrong and deleted that part when his collected works were published. The missing part was restored in 1966

RH condition and weak solutions (I)

- The RH condition (also referred to as shock condition or jump condition), are used to avoid multi-valued behavior in the solution, which would otherwise occur after characteristics cross
- We are interested in finding weak (or generalized) solutions featuring only essential discontinuities: the discontinuity curve x = s(t) is essential if characteristics from each side of x = s(t) intersect on s(t) as t grows.



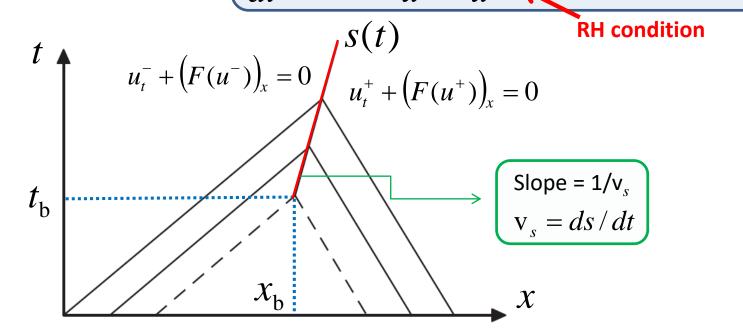
RH condition and weak solutions (II)

To be more specific, consider the Hopf equation: $u_t + (F(u))_v = 0$

Then, a weak solution of the Hopf equation, valid for $t \ge t_h$, is:

$$u = \begin{cases} u^{-}, & \text{for } (x,t) \text{ on the } left \text{ of } s(t) \\ u^{+} & \text{for } (x,t) \text{ on the } right \text{ of } s(t) \end{cases}$$

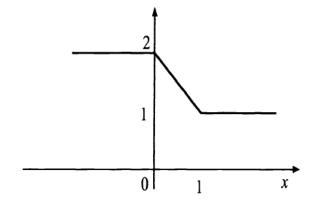
with
$$\underline{s(t)}$$
 satisfying the ODE:
$$\frac{ds}{dt} = \frac{F(u^+, t) - F(u^-, t)}{u^+ - u^-}, \quad s(t_b) = x_b$$



Revisiting a previous example

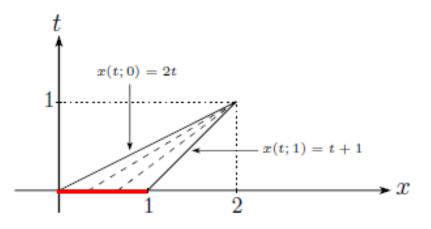
Consider the IVP: $u_t + u u_x = 0$, u(x,0) = f(x), $x \in \mathbb{R}$

$$f(x) = \begin{cases} 2, & x < 0 \\ 2 - x, & 0 \le x \le 1 \\ 1, & x > 1 \end{cases}$$



Recall that $t_b = 1$ (and $x_b = 2$) and the solution reads:

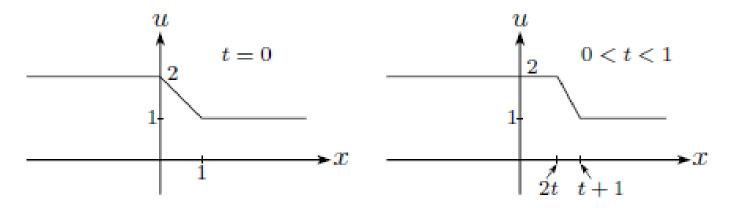
$$u(x,t) = \begin{cases} 2, & x < 2t \\ \frac{2-x}{1-t}, & 2t \le x \le t+1 \\ 1, & x > t+1 \end{cases}$$



Hence, at $t = t_b = 1$ the solution becomes discontinuous

Revisiting a previous example – cont.

In particular, the solution has the form:



and for $t = t_b = 1$ the solution reads:

$$u(x,t=1) = \begin{cases} 2, & x < 2 \\ 1, & x > 2 \end{cases}$$

Hence, for $t > t_b = 1$, no classical solution exists

Nevertheless, we can construct a weak solution as follows

Constructing the weak solution

Observe that:
$$u = \begin{cases} u^{-} = 2, & \text{for } (x, t) \text{ on the } left \text{ of } s(t) \\ u^{+} = 1 & \text{for } (x, t) \text{ on the } right \text{ of } s(t) \end{cases}$$

with
$$\underline{s(t)}$$
 satisfying the ODE: $\frac{ds}{dt} = \frac{F(u^+, t) - F(u^-, t)}{u^+ - u^-}$, $s(t_b) = x_b$

Here:
$$F(u) = \frac{1}{2}u^2$$

$$\frac{ds}{dt} = \frac{F(u^+, t) - F(u^-, t)}{u^+ - u^-}$$

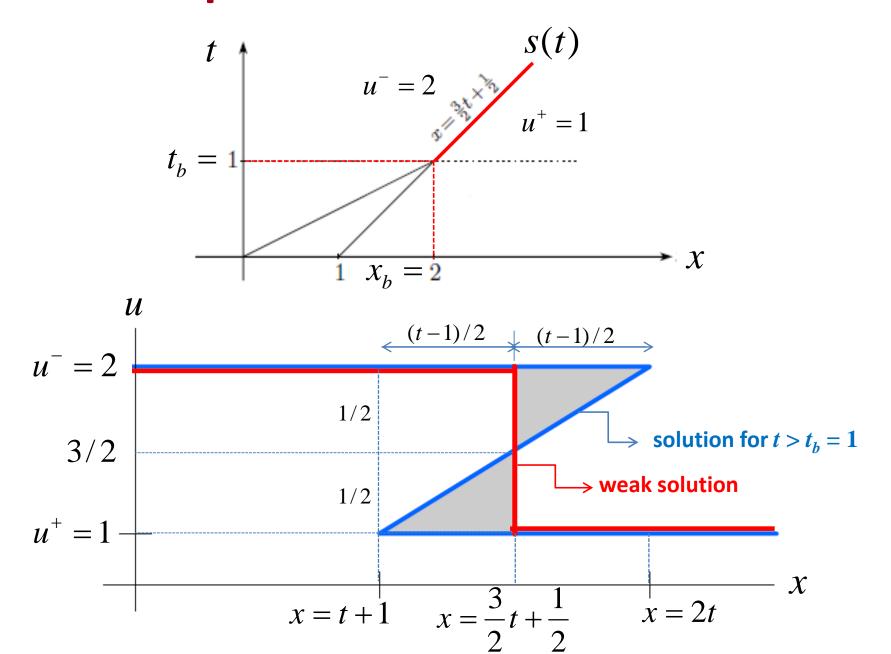
$$\Rightarrow \frac{ds}{dt} = \frac{1}{2}(u^+ + u^-) = \frac{1}{2}(1 + 2) = \frac{3}{2}$$
RH condition

Hence: $\frac{ds}{dt} = \frac{3}{2} \Rightarrow s(t) = \frac{3}{2}t + x_0$ $s(t_b) = x_b \Rightarrow s(1) = 2$ $\Rightarrow s(t) = \frac{3}{2}t + \frac{1}{2}$

$$\Rightarrow s(t) = \frac{3}{2}t + \frac{1}{2}$$

for the usual Hopf equation

The xt-plane and the weak solution



The generalized solution

Concluding, a generalized solution of the considered IVP is:

$$u(x,t) = \begin{cases} u_{classical}(x,t), & \text{for } t < t_b = 1 \\ u_{weak}(x,t) & \text{for } t \ge t_b = 1 \end{cases}$$

 \blacksquare The classical solution for t < 1 reads:

$$u_{classical}(x,t) = \begin{cases} 2, & x < 2t \\ \frac{2-x}{1-t}, & 2t \le x \le t+1 \\ 1, & x > t+1 \end{cases}$$

■ The weak solution for $t \ge 1$ reads:

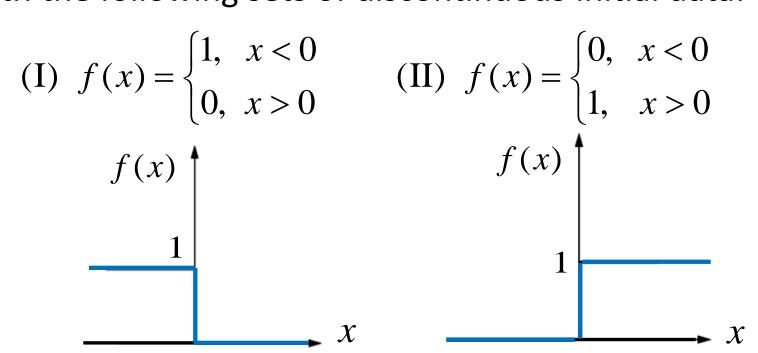
$$u_{weak}(x,t) = \begin{cases} 2, & \text{for } x < \frac{3}{2}t + \frac{1}{2} \\ 1, & \text{for } x > \frac{3}{2}t + \frac{1}{2} \end{cases}$$

Riemann problems

A Riemann problem is an initial value problem for a hyperbolic PDE (or a system thereof) in which the initial data is piecewise constant with a discontinuity

Examples

Consider the IVP: $u_t + u u_x = 0$, u(x,0) = f(x), $x \in R$, t > 0 with the following sets of discontinuous initial data:

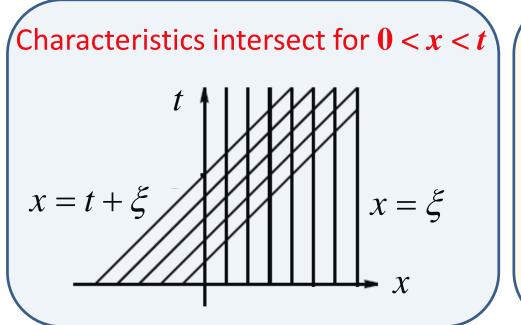


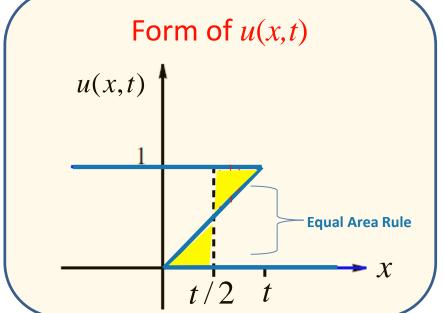
Riemann problem (I)

In this case, the initial data is already the form of a shock wave. Indeed: $\frac{dx}{dx}$

$$\frac{dx}{dt} = u, \ x(0) = \xi; \quad \frac{du}{dt} = 0, \ u(0) = f(\xi)$$

lead to:
$$x = f(\xi)t + \xi$$
; $u(x,t) = f(\xi) = \begin{cases} 1, & \xi < 0 \text{ or } x < t \\ 0, & \xi > 0 \text{ or } x > 0 \end{cases}$





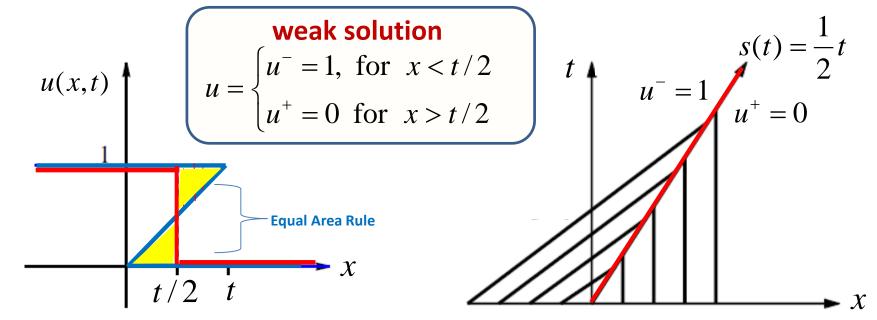
Riemann problem (I) – cont.

Weak solution:
$$u = \begin{cases} u^- = 1, & \text{for } (x, t) \text{ on the } left \text{ of } s(t) \\ u^+ = 0 & \text{for } (x, t) \text{ on the } right \text{ of } s(t) \end{cases}$$

with
$$s(t)$$
 satisfying the ODE: $\frac{ds}{dt} = \frac{1}{2}(u^+ + u^-), \quad s(0) = 0$

 $\frac{ds}{dt} = \frac{1}{2}(u^{+} + u^{-}) = \frac{1}{2}(0+1) = \frac{1}{2} \Longrightarrow s(t) = \frac{1}{2}t$

RH condition



Riemann problem (II)

In this case, we again have:

$$\frac{dx}{dt} = u, \ x(0) = \xi; \quad \frac{du}{dt} = 0, \ u(0) = f(\xi)$$

and the characteristics are of the form:

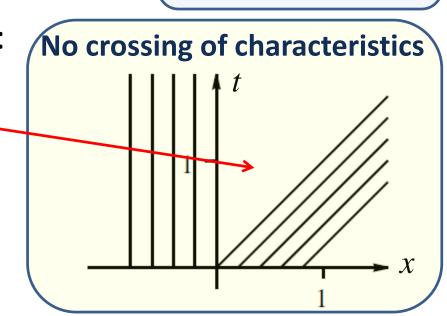
$$x = f(\xi)t + \xi; \quad u(x,t) = f(\xi) = \begin{cases} 0, & \xi < 0 \\ 1, & \xi > 0 \end{cases} \Rightarrow \begin{cases} x = \begin{cases} \xi, & \xi < 0 \\ t + \xi, & \xi < 0 \end{cases}$$

However, we still have a problem: there exists a region on which there is not enough information!

Question:

f(x)

How should we define the solution in this region?



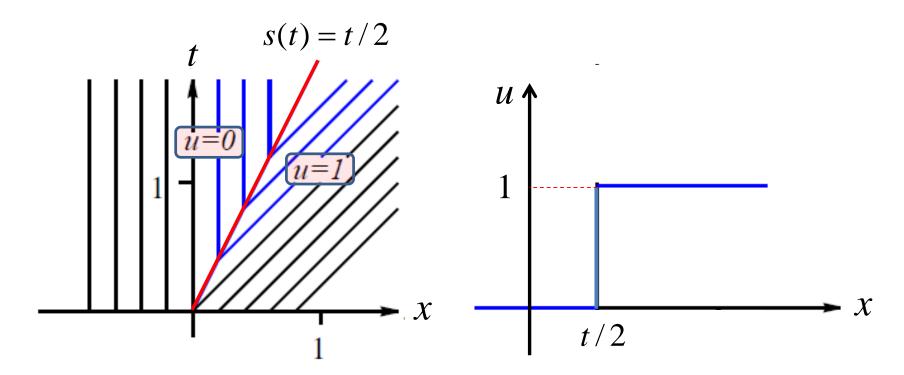
Riemann problem (II) – cont.

One possibility:

A possible **weak solution** of the problem is: $u = \begin{cases} 0, & \text{for } x < t/2 \\ 1, & \text{for } x > t/2 \end{cases}$

$$u = \begin{cases} 0, & \text{for } x < t/2 \\ 1, & \text{for } x > t/2 \end{cases}$$

This is composed by classical solutions on either side of the curve of discontinuity s(t)=t/2. Furthermore, this solution satisfies the RH condition along the curve of discontinuity.



Riemann problem (II) – cont.

Another possibility:

Another possible weak solution of the problem can be found upon filling the wedge 0 < x < t with another, similarity solution, of the Hopf equation. Such a similarity solution is of the form:

$$u(x,t) = t^n g(\eta), \ \eta = xt^m$$

Observing that the Hopf equation $u_t + u u_x = 0$ is invariant under the transformations $\underline{x} \mapsto \lambda x, \ t \mapsto \lambda t$, a simple calculation leads to:

$$n=0, \quad m=-1, \quad g=\frac{x}{t}$$

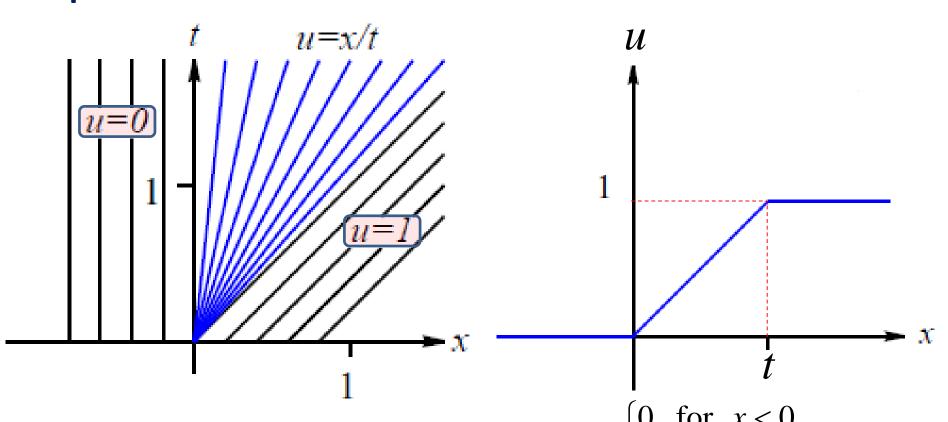
Hence, another solution of the problem is the continuous function:

$$u = \begin{cases} 0, & \text{for } x < 0 \\ \frac{x}{t}, & \text{for } 0 < x < t \\ 1, & \text{for } x > t \end{cases}$$
This weak solution is called a rarefaction wave

Riemann problem (II) – cont.

xt-plane and characteristics

The form of the solution



Notice the "fan" at x = 0

Recall:
$$u = \begin{cases} 0, & \text{for } x < 0 \\ \frac{x}{t}, & \text{for } 0 < x < t \\ 1, & \text{for } x > t \end{cases}$$

The Lax entropy condition

There exist at least **two solutions** of the Riemann problem (II), with the same initial data and hence **the solution is not unique**.

Question: which one of these solutions is physically meaningful?

For our initial data, the wave is higher to the right. Consequently, we expect the part of the wave to the right to move faster. Hence, physically, we do not want to allow for the 1st solution. Instead, we accept the 2nd one as a physically more realistic solution.

It can be proved that there exists a unique weak discontinuous solution of the Cauchy problem which satisfies the following inequality on the curve of discontinuity:

$$c(u^{-}) > s'(t) > c(u^{+})$$

Lax entropy condition

Criterion for a unique weak discontinuous solution

The Lax entropy condition – cont.

$$c(u^{-}) > s'(t) > c(u^{+})$$

- This condition states that the wave speed just behind the shock is greater than the wave speed just ahead of it. In other words, the wave behind the shock catches up to the wave ahead of it.
- ■This entropy criterion is a special case of the **second law of** thermodynamics: entropy *increases across a shock*.
- **Geometrically,** Lax entropy condition can be stated as follows: The characteristics originating on either side of the discontinuity curve, when continued in the direction of increasing *t*, intersect the curve of discontinuity.
- For every nonlinear IVP there exists a unique weak solution defined $\forall t \geq 0$ with only shock as a discontinuity. The **proof** is fairly difficult and was provided by **Lax (1973)**.