El xoure Sajer nis yearur Karésaan $|\Psi_A(t)\rangle = C_A(t)|\downarrow_N\rangle + C_2(t)|\uparrow_{M-1}\rangle = |A\rangle$ $\langle \hat{S}_{+} \hat{S}_{-} \rangle = |\varsigma_{1}(t)|^{2} \\ \langle \hat{S}_{-} \hat{S}_{+} \rangle = |\varsigma_{1}(t)|^{2} \\ \rangle \Rightarrow \langle \hat{S}_{+} \hat{S}_{-} \rangle + \langle \hat{S}_{-} \hat{S}_{+} \rangle = 1$ $\langle \hat{a}^{\dagger} \hat{a} \rangle + \langle \hat{s}_{\dagger} \hat{s}_{-} \rangle = n$ $\langle \hat{S}_{+} \hat{a}^{\dagger} \rangle = \phi$ $\langle \hat{S}_{+} \hat{\alpha} \rangle = \hat{S}_{+} (t) \hat{S}_{+} (t) \sqrt{n}$ $\langle \hat{S}_{-} \hat{a}^{\dagger} \rangle = G_{(t)}^{*} G_{(t)} \sqrt{n}$ < ŝ. à>=0

$$\begin{aligned} \left| \Psi_{h}(t) \right\rangle &= c_{1}(t) \left| \psi_{h}(t) \right\rangle \\ &= c_{1}(t) \left| \psi_{h}(t) \right\rangle \\ &= H_{1}(t) \\ &= H_{2}(t) \left| \psi_{h}(t) \right\rangle \\ &= H_{2}(t) \\ &= H_{2}$$

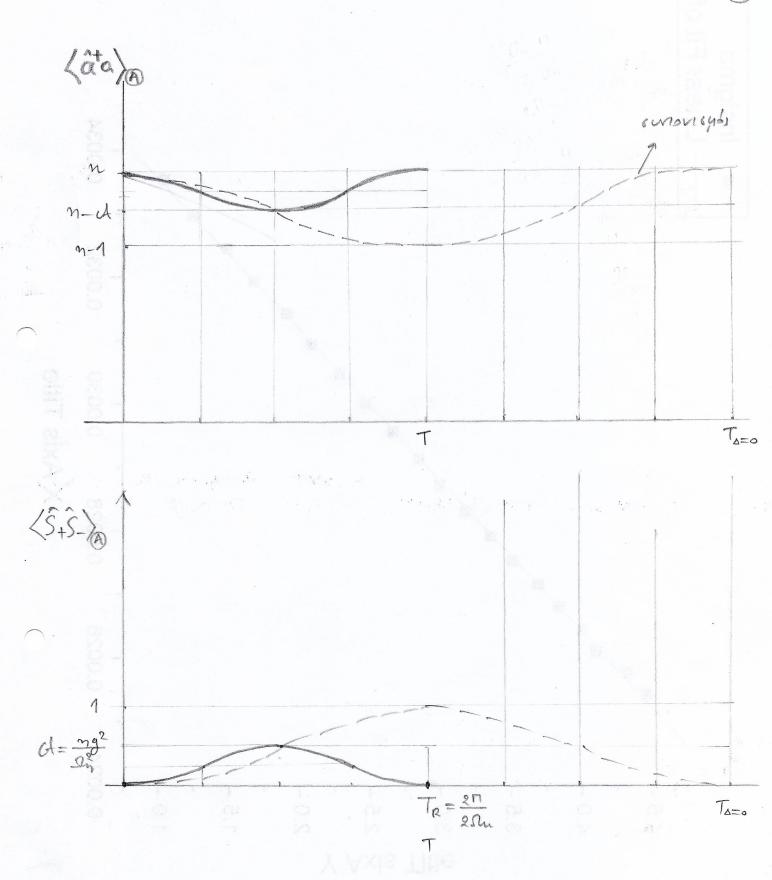
$$|A_{pa}| |G_{lt}|^{2} = \frac{mg^{2}}{\Omega_{n}^{2}} \sin^{2}(\Omega_{nt}t) \qquad |G_{lt}|^{2} = 1 - |G_{lt}|^{2} = \dots$$

$$\left(\hat{a}^{\dagger}\hat{a}\right)_{B} = m - \frac{mg^{2}}{\Omega_{n}^{2}} \sin^{2}(\Omega_{nt}t) \qquad \left(\hat{s}_{+}\hat{s}_{-}\right)_{B} = \frac{mg^{2}}{\Omega_{n}^{2}} \sin^{2}(\Omega_{nt}t)$$

$$\cos 2x = \cos^{2} x - \sin^{2} x = 1 - 2\sin^{2} x \Rightarrow \sin^{2} x = \frac{1 - \cos 2x}{2}$$

$$A = 0 \Rightarrow dr = 1$$
$$T_{R} = \frac{2\pi}{\Omega_{R}}$$

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$$i \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} = \begin{pmatrix} mw & gA\bar{h}_{1} \\ gA\bar{h}_{1} & \Omega + (m-A)w \end{pmatrix} \begin{pmatrix} G \\ c_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \begin{pmatrix} G \\ G \\ c_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{2} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{x}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{z}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{z}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{z}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{z}(k) = \vec{v} \begin{pmatrix} \dot{c}_{1} \\ \dot{c}_{1} \end{pmatrix} \stackrel{(c)}{\Rightarrow} \vec{$$

$$\begin{split} \begin{split} & \left(\lambda_{1} = \mathcal{H}_{n} - \mathcal{Q}_{1}\right) \qquad A \vec{\upsilon}_{n} = \lambda_{n} \vec{\upsilon}_{n} \Rightarrow \begin{pmatrix} \omega & \partial \\ \partial & \mathcal{Q} \end{pmatrix} \begin{pmatrix} \upsilon_{n} \\ \upsilon_{2n} \end{pmatrix} = (\mathcal{H}_{n} - \mathcal{Q}_{1}) \begin{pmatrix} \upsilon_{n} \\ \upsilon_{2n} \end{pmatrix} = \partial \mathcal{U}_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{1}) \cup \mathcal{U}_{n} \Rightarrow \partial \mathcal{U}_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{n} - \omega) \cup \mathcal{U}_{nn} \\ & \partial \cup_{nn} + \mathcal{Q} \cup_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{1}) \cup \mathcal{U}_{2n} \Rightarrow \partial \mathcal{U}_{nn} = (\mathcal{H}_{n} - \mathcal{Q}_{n} - \mathcal{Q}_{1}) \cup \mathcal{U}_{2n} \\ & \partial \mathcal{U}_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{1} - \omega) (\mathcal{H}_{n} - \mathcal{Q}_{1} - \mathcal{Q}_{1}) \cup \mathcal{U}_{2n} \\ & \partial \mathcal{U}_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{1} - \omega) (\mathcal{H}_{n} - \mathcal{Q}_{1} - \mathcal{Q}_{1}) \cup \mathcal{U}_{2n} \\ & \partial \mathcal{U}_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{1} - \omega) (\mathcal{H}_{n} - \mathcal{Q}_{1} - \mathcal{Q}_{1}) \cup \mathcal{U}_{2n} \\ & \partial \mathcal{U}_{2n} = (\mathcal{H}_{n} - \mathcal{Q}_{1} - \omega) (\mathcal{H}_{n} - \mathcal{Q}_{1} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{1}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{Q}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{U}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{U}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{U}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_{2n} - \mathcal{U}_{2n}) = \partial \\ & \partial \mathcal{U}_{2n} = (\mathcal{U}_$$

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$$\begin{split} & \delta u_1 a \delta d_1 \quad \forall \sigma \quad \forall_{22} \quad y noper va \quad \hat{u} val \quad \delta u \delta d_1 note \quad n.x. \quad U_{22} = 1 \\ & g U_{12} = (H_1 + \Omega_1 - Q) \cdot 1 = \frac{w + \Omega_2 - 2\Omega}{2} + \Omega_1 = \frac{w - \Omega}{2} + \Omega_1 \\ & U_{12} = \frac{\Delta + 2\Omega_1}{2g} \\ & U_{12} = \frac{\Delta + 2\Omega_1}{2g} \\ & U_{2} = \frac{\Delta + 2\Omega_1}{2g} \\ & 1 \end{split}$$

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$$\vec{x}(t) = \sigma_1 \vec{v}_1 e^{-i\lambda_1 t} + \sigma_2 \vec{v}_2 e^{-i\lambda_2 t}$$

$$\vec{X}(t) = \begin{bmatrix} G_1(t) \\ G_2(t) \end{bmatrix} = \begin{bmatrix} \sigma_1 & \underline{\Delta} - 2\Omega_1 & e^{-i(H_1 - \Omega_1)t} \\ 2g & e^{-i(H_1 - \Omega_1)t} \\ \sigma_2 - 1 & e^{-i(H_1 - \Omega_1)t} \\ \sigma_2 - 1 & e^{-i(H_1 - \Omega_1)t} \end{bmatrix} = \begin{bmatrix} \sigma_1 & \underline{\Delta} - 2\Omega_1 & e^{-i(H_1 + \Omega_1)t} \\ \sigma_2 - 1 & e^{-i(H_1 - \Omega_1)t} \\ \sigma_2 - 1 & e^{-i(H_1 - \Omega_1)t} \end{bmatrix}$$

APXILEE ETNOHLEE G(0) = 1 $C_2(0) = 0 =)$

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$${}^{''}A_{pa} \left({}_{2}(t) = -\frac{9}{2\Omega_{1}} \right) = -\frac{9}{2\Omega_{1}} \left(+\frac{9}{2\Omega_{1}} \right) = -\frac{9}{2\Omega_{1}} \left($$

$$(g(t)) = \frac{9}{2\Omega_1} \stackrel{\text{iH}_{h}t}{e} \stackrel{i\Omega_1t}{e} \stackrel{\text{i}\Omega_1t}{e} \stackrel{\text{-iH}_{h}t}{e} \stackrel{-i\Omega_1t}{e} \stackrel{\text{-i}\Omega_1t}{e} \stackrel{\text{-i}\Omega_1t}{$$

$$C_2(t) = \frac{9}{2R_1} e^{-iH_1t} \left\{ -\cos(R_1t) - i\sin(R_1t) + \cos(R_1t) - i\sin(R_1t) \right\}$$

$$(\zeta_{1}t) = \frac{9}{2\Omega_{A}} e^{itH_{A}t} (-2i) \sin(\Omega_{A}t) = e^{-i\frac{\omega+\Omega}{2}t} \left\{ -i\frac{9}{\Omega_{A}} \sin(\Omega_{A}t) \right\}$$

$$\frac{|\zeta_{1}(t)|^{2}}{|\Omega_{1}|^{2}} = \frac{g^{2}}{|\Omega_{1}|^{2}} \operatorname{Shu}^{2}(\Omega_{1}(t)) = 1 - \frac{g^{2}}{|\Omega_{1}|^{2}} (1 - \omega^{2}(\Omega_{1}(t))) = 1 - \frac{g^{2}}{|\Omega_$$

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$$|C_1(t)|^2 = \frac{(\Delta^2)}{4} + \frac{g^2}{\Omega_1^2} \cos^2(\Omega_1 t)$$

 $\Omega_1^2 = \Omega_1^2$

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$$A = \begin{bmatrix} mw & g\sqrt{n} \\ g\sqrt{n} & \Omega + (m-1)w \end{bmatrix}$$
 kar $det (A - \lambda I) = 0 = 0$
$$mw - \lambda & g\sqrt{n} \\ g\sqrt{n} & \Omega + (m-1)w - \lambda \end{bmatrix} = 0$$

$$= \sum (mw - \lambda) \left[\Omega + (m-1)w - \lambda \right] - mg^{2} = 0$$

$$\lambda^{2} - \lambda \left[\Omega + (m-1)w + mw \right] + mw \left[\Omega + (m-1)w \right] - mg^{2} = 0$$

$$\Delta' = \left[\Omega + (m-1)w + mw \right]^{2} - 4mw \left[\Omega + (m-1)w \right] - mg^{2} \right)$$

$$\Delta' = \left[\Omega + (m-1)w + mw \right]^{2} - 4mw \left[\Omega + (m-1)w \right] + 4mg^{2}$$

$$\Delta' = \left[\Omega + (m-1)w - mw \right]^{2} + 4mg^{2} > 0$$

$$\lambda_{21} = \frac{\left[\Omega + (m-1)w + mw \right] \pm \sqrt{\left[\Omega + (m-1)w - mw \right]^{2} + 4mg^{2}}}{2}$$

$$\lambda_{2,1} = \frac{\Omega + (m-1)w + mw}{2} \pm \sqrt{\left[\frac{\Omega + (m-1)w - mw}{2} \right]^{2} + mg^{2}}}{2}$$

$$\lambda_{2,1} = \frac{\Omega + (m-1)w + mw}{2} \pm \sqrt{\left[\frac{\Omega + (m-1)w - mw}{2} \right]^{2} + mg^{2}}}{2}$$

$$\frac{2}{\lambda_{2,1} = Hn \pm \Omega n} = \frac{1}{H_n} \left(\frac{2}{2}\right)^2 + ng^2$$

$$\int \Omega_n = \sqrt{\left(\frac{\Delta}{2}\right)^2 + ng^2}$$

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$$\begin{split} & \left(\sum_{n=+\infty}^{\infty} -\Omega_{n}\right) \quad A\vec{v}_{1} = \sum_{n} \vec{v}_{n} \Rightarrow \begin{pmatrix} mw & g\vec{v}_{n} \\ g\vec{v}_{n} & \Omega_{n} + g\vec{v}_{n} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} = (H_{n-}\Omega_{n}) \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} -\Omega_{n} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} -\Omega_{n} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{nq} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{2q} \end{pmatrix} \begin{pmatrix} U_{nq} \\ U_{nq} \end{pmatrix} \begin{pmatrix}$$

$$\begin{split} \widehat{\lambda_{2}} &= H_{u} + \Omega_{u} \qquad A \overrightarrow{u_{2}} = \lambda_{2} \overrightarrow{u_{2}} = \partial_{z} \left(\begin{matrix} m\omega & g fu_{1} \\ g fu_{1} & \Omega_{+}(m-n)\omega \end{matrix} \right) \left(\begin{matrix} U_{12} \\ U_{22} \end{matrix} \right) = \left(H_{u} + \Omega_{u} \right) \left(\begin{matrix} U_{12} \\ U_{22} \end{matrix} \right) = \left(H_{u} + \Omega_{u} \right) \left(\begin{matrix} U_{12} \\ U_{22} \end{matrix} \right) = \left(H_{u} + \Omega_{u} \right) \left(\begin{matrix} U_{12} \\ U_{22} \end{matrix} \right) = \left(H_{u} + \Omega_{u} \right) \left(\begin{matrix} U_{12} \\ U_{12} \end{matrix} \right) = \left(H_{u} + \Omega_{u} - m\omega \right) \left(\begin{matrix} U_{12} \\ U_{12} \end{matrix} \right) = \left(H_{u} + \Omega_{u} - m\omega \right) \left(\begin{matrix} U_{12} \\ U_{12} \end{matrix} \right) = \left(H_{u} + \Omega_{u} - m\omega \right) \left(\begin{matrix} U_{12} \\ U_{12} \end{matrix} \right) = \left(H_{u} + \Omega_{u} - m\omega \right) \left(\begin{matrix} U_{12} \\ U_{12} \end{matrix} \right) = \left(H_{u} + \Omega_{u} - m\omega \right) \left(H_{u} + \Omega_{u} - \left[\Omega + (m-n)\omega \right] \right) \\ g fu_{1} & U_{22} \end{matrix} = \left(H_{u} + \Omega_{u} - m\omega \right) \left(H_{u} + \Omega_{u} - \left[\Omega + (m-n)\omega \right] \right) \\ \left(U_{12} = 0 \end{matrix} \right) \qquad H_{u} + \Omega_{u} - m\omega \right) \left(H_{u} + \Omega_{u} - \left[\Omega + (m-n)\omega \right] \right) \\ \left(U_{12} = 0 \end{matrix} \right) \qquad H_{u} + \Omega_{u} = -\frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\Omega - \omega}{2} + \Omega_{u} = -\frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\Omega - \omega}{2} + \Omega_{u} = -\frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_{u} \\ &= \frac{\omega - \Omega}{2} + \Omega_{u} = \frac{\Delta}{2} + \Omega_$$

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$$\vec{x}(t) = \sigma_1 \vec{v}_1 e^{-i\lambda_1 t} + \sigma_2 \vec{v}_2 e^{-i\lambda_2 t}$$

$$\vec{x}(t) = \begin{bmatrix} G(t) \\ G(t) \\ G(t) \end{bmatrix} = \sigma_1 \begin{bmatrix} \frac{\Delta - 2\Omega_n}{2\eta n} \\ 1 \end{bmatrix} e^{-i(H_n - \Omega_n)t} e^{-i(H_n - \Omega_n)t} \\ e^{-i(H_n - \Omega_n)t} e^{-i(H_n + \Omega_n)t} e^{-i(H_n + \Omega_n)t} \\ \eta \end{bmatrix}$$

$$Papxinde Sindhiker C_1(0) = 1 \quad C_2(0) = 0$$

$$\sigma_1 - \frac{\Delta - 2\Omega_n}{2\eta n} + \sigma_2 - \frac{\Delta + 2\Omega_n}{2\eta n} = 1 \\ \eta \end{bmatrix} =) \sigma_1 - \frac{\Delta - 2\Omega_n - \Delta - 2\Omega_n}{2\eta n} = 1$$

$$\sigma_1 + \sigma_2 = 0 \implies \sigma_2 = -\sigma_1 \qquad \Rightarrow \sigma_1 - \frac{-4\Omega_n}{2\eta n} = 1 =) \sigma_1 - \frac{-9N_n}{2\Omega_n} = -\sigma_2$$

$$C_2(t) = \frac{-9N_n}{2\Omega_n} e^{-i(H_n - \Omega_n)t} + \frac{9N_n}{2\Omega_n} e^{-i(H_n + \Omega_n)t} + \frac{-i(H_n + \Omega_n)t}{2\Omega_n} =) c_2(t) = \frac{9N_n}{2\Omega_n} e^{-i(H_n t} [e^{i\Omega_n t} - e^{i\Omega_n t}] =) c_2(t) = \frac{9N_n}{2\Omega_n} e^{-i(H_n t)}$$

$$\left|\zeta_{2}(t)\right|^{2} = \frac{mg^{2}}{\Omega_{\eta}^{2}} \sin^{2}(\Omega_{\eta}t)$$