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ΣΤΟΙΧΕΙΑ ΘΕΩΡΙΑΣ ΠΑΙΓΝΙΩΝ ΚΑΙ ΛΗΨΗΣ ΑΠΟΦΑΣΕΩΝ

ΒΑΣΙΚΕΣ ΕΝΝΟΙΕΣ ΚΑΙ ΟΡΙΣΜΟΙ

Παναγιώτης Μερτικόπουλος

Εθνικό και Καποδιστριακό Πανεπιστήμιο Αθηνών

Τμήμα Μαθηματικών



Χειμερινό Εξάμηνο, 2023–2024



Overview & basic information

- Playing with pure strategies
- B Playing with mixed strategies

4 Nash's theorem

6 Potential games



Welcome to SEP19: Topics in Game Theory

"The study of rational decision-making"

- Instructors: Panayotis Mertikopoulos ►
- Meeting times: Mondays 09:00-13:00 ►
- e-class: https://eclass.uoa.gr/courses/MATH806/ ►
- Sessions: Focus on general theory with some deep dives / practical sessions (TBD) ►
- **Grading scheme:** split between end-of-term project (50%) and final (50%) ►



Course overview

Rough breakdown of the course:

1. Part 1: Basic elements of game theory

- Basic notions: Nash equilibrium, dominated strategies,...
- Basic notions: Nash equilibrium, dominated strategies,...
- Game classes: potential games, congestion games, price of anarchy,...
- Game dynamics: replicator dynamics, exponential weights,...

2. Part 2: Multi-armed bandits and online optimization

- Bandits and regret: regret minimization,...
- Algorithms: Hedge, EXP3,...
- Online convex optimization: regret, convexification,...
- Algorithms: leader-following policies, gradient / mirror descent,...

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Why game theory?

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Example 1: A game of roads



A beautiful morning commute in Chicago

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The price of congestion

In the US alone, congestion cost \$305 billion in 2017 (\approx 1.6% of GDP)

➡ source: INRIX

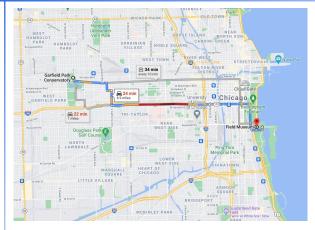
- Lost productivity
- Fuel waste
- Environmental impact, quality of life,...

Introduction and basic exam 000000000 Playing with pure strategie 000000000 aying with mixed strategies 0000000 Nash's theore

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Game of roads



The city of Chicago

- ▶ 2,700,000 people
- 1,261,000 daily trips
- 933 nodes
- 2950 edges
- 870,000 o/d pairs
- ▶ $\approx 2 \times 10^{16}$ paths

A very large game!

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Example 2: Spot the fake

Which person is real?





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Example 2: Spot the fake

Which person is real?





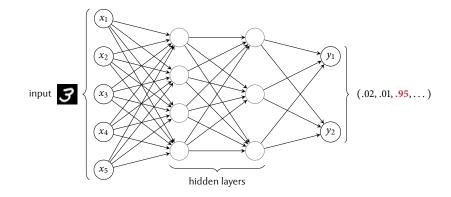
Spoiler: https://thispersondoesnotexist.com

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Nash's the 00000 Potential games 00000 References

Neural networks

The workhorse of deep learning:



The deep learning revolution: breaking the human perception barrier (2010's)

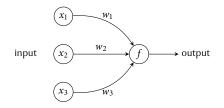
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es Nash's 000 Potential games

Neurons

The atoms of any deep learning architecture are its neurons:



- Input could be binary {0,1} or real (e.g., average intensity of image)
- Inputs weighed with weight coefficients w_i
- Neuron **activates** on value of $f(\sum_i w_i x_i)$

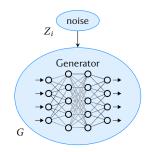
Examples

- 1. Perceptron: binary inputs, step function activation
- 2. Sigmoid neuron: real inputs, tanh activation
- 3. **ReLU:** real inputs, rectified linear activation $(f(z) = [z]_+)$

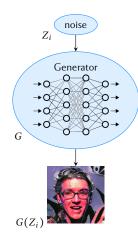
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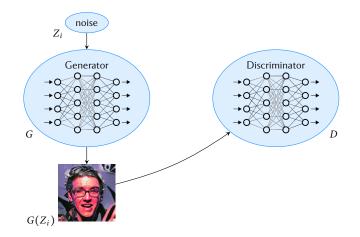
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Nash's theore

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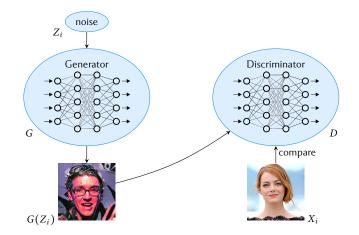
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Nash's theore

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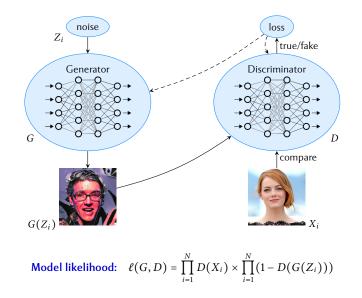
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Nash's theore

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The schematics of GANs



11/49

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laying with pure strategie

laying with mixed strategies

Nash's the

Potential games

G

GAN training

How to find good generators (G) and discriminators (D)?

Discriminator: maximize (log-)likelihood estimation

 $\max_{D\in\mathcal{D}}\,\log\ell(G,D)$

Generator: minimize the resulting divergence

 $\min_{G \in \mathcal{G}} \max_{D \in \mathcal{D}} \log \ell(G, D)$

A (very complex) zero-sum game!

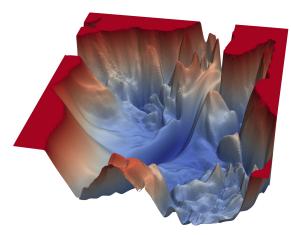
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Nash's the 00000 tential games 0000



Training landscape

A deep learning loss landscape



• Easier problem: find a needle in a haystack

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Playing with pure strategie 000000000 aying with mixed strategies 0000000 Nash's theore

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The game does not always work out:



➡ A StyleGAN after 8 days of training at Nvidia headquarters (!!!)

iew & basic information	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies	Nash's theorem 000000	Potential games 00000	

Questions we'll try to answer

1. How should we model player interactions?

- Urban traffic ≠ transit systems ≠ packet networks ≠ ...
- Rational agents ≠ humans ≠ AI algorithms ≠ ...
- Competition ≠ congestion ≠ coordination ≠ ...

2. What is a desired operational state?

- Social optimum \neq equilibrium \neq ...
- Static (equilibrium, social optimum) ≠ Bayesian ≠ online (regret) ≠ ...

3. How to compute it?

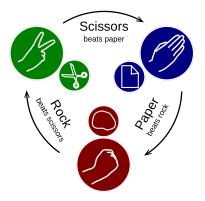
- Calculation ≠ learning ≠ implementation
- Informational constraints: feedback, bounded rationality, uncertainty, ...

Introduction and basic examples

Playing with pure strategie: 0000000000 aying with mixed strategies 0000000 Nash's theo 000000 tential games



Let's play a game



What would you play? How can we model this game mathematically?

ew & basic information 000000000000	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies	Nash's theorem 000000	Potential games 00000	
Let's play a aa	ume, formally					

- ▶ **Players:** "1" and "2"
- Actions associated to each player: $A_i = \{R, P, S\}, i = 1, 2$
- Payoff matrix (win: \$1; lose -\$1; tie \$0):

$$A = \begin{array}{c|cccc} R & P & S \\ \hline R & 0 & -1 & 1 \\ P & 1 & 0 & -1 \\ S & -1 & 1 & 0 \end{array}$$

Payoff functions:

- $u_1: \mathcal{A}_1 \times \mathcal{A}_2 \rightarrow \mathbb{R}$ given by $u_1(\mathsf{R}, \mathsf{R}) = 0, u_1(\mathsf{R}, \mathsf{P}) = -1, ...$
- $u_2: \mathcal{A}_1 \times \mathcal{A}_2 \rightarrow \mathbb{R}$ given by $u_2(\mathbb{R}, \mathbb{R}) = 0, u_2(\mathbb{R}, \mathbb{P}) = 1, ...$



Some basics

What's in a game?

A *game in normal form* is a collection of three basic elements:

- 1. A set of **players** \mathcal{N}
- 2. A set of *actions* (or *pure strategies*) A_i per player $i \in \mathcal{N}$
- 3. An ensemble of *payoff functions* $u_i: \mathcal{A} \equiv \prod_i \mathcal{A}_j \to \mathbb{R}$ per player $i \in \mathcal{N}$



Some basics

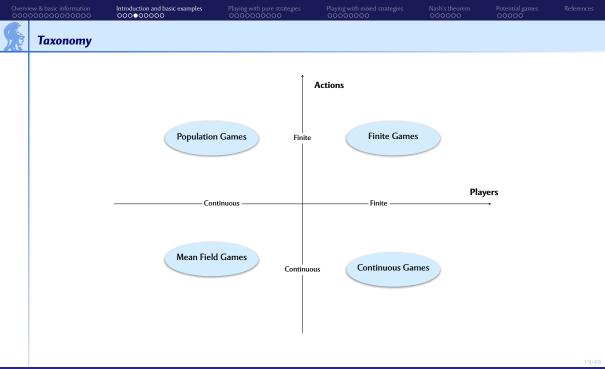
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Important:

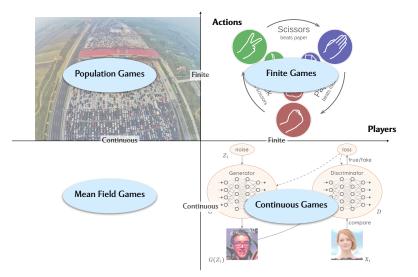
- Player set: atomic vs. nonatomic
- Action sets: finite vs. continuous; shared vs. individual; ... ►
- B **NB:** do not mix game classes!



Introduction and basic examples 000000000



Taxonomy



Playing with pure strategie 0000000000 laying with mixed strategies

Nash's theo

Potential games

References



What's in a game?

Definition (Finite games)

A *finite game in normal form* is a collection of the following primitives:

- A finite set of *players* $\mathcal{N} = \{1, \dots, N\}$
- A finite set of *actions* (or *pure strategies*) A_i for each player $i \in N$
- A *payoff function* $u_i: \mathcal{A} := \prod_j \mathcal{A}_j \to \mathbb{R}$ for each player $i \in \mathcal{N}$

A game with primitives as above will be denoted as $\Gamma \equiv \Gamma(\mathcal{N}, \mathcal{A}, u)$.

Some notes:

- ▶ "Normal form" ~> difference with "extensive form" games (Chess, Go,...)
- ▶ Handy shorthands: $(a_1, \ldots, a_i, \ldots, a_N) \leftarrow (a_i; a_{-i})$ and $\mathcal{A}_{-i} = \prod_{j \neq i} \mathcal{A}_j$

Playing with pure strategies

aying with mixed strategies

Nash's the

Potential games

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The Prisoner's Dilemma

Bonnie and Clyde are captured by the authorities and put in separate cells:

- If both betray each other, they both serve 2 years in prison
- If Bonnie betrays but Clyde remains silent, Bonnie goes free and Clyde serves 3 years
- ▶ If Bonnie remains silent but Clyde betrays, Bonnie serves 3 years and Clyde goes free
- If neither betrays the other, they both serve 1 year

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The Prisoner's Dilemma

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- If Bonnie remains silent but Clyde betrays, Bonnie serves 3 years and Clyde goes free
- If neither betrays the other, they both serve 1 year

Normal form representation:

- Players: $\mathcal{N} = \{B, C\}$
- Actions: $A_B = A_C = \{ betray, silent \}$
- Payoff bimatrix:

$B\downarrow \ C \rightarrow$	betray	silent
betray	(-2, -2)	(0, -3)
silent	(-3, 0)	(-1, -1)

Introduction and basic examples 000000000



https://www.youtube.com/watch?v=S0qjK3TWZE8

- If both players steal, they both get nothing ۲
- If one player steals and the other splits, the one who steals gets everything ۲
- If both players split, they split the prize ►

Do you split or steal?



Split or steal?

https://www.youtube.com/watch?v=S0qjK3TWZE8

- If both players steal, they both get nothing
- If one player steals and the other splits, the one who steals gets everything
- If both players split, they split the prize

Do you split or steal?

Normal form representation:

- Players: $\mathcal{N} = \{A, B\}$
- Actions: $A_A = A_B = \{ \text{split}, \text{steal} \}$
- Payoff bimatrix:

$A\downarrow \ B \rightarrow$	split	steal
split	(\$6800,\$6800)	(0, \$13600)
steal	(\$13600,0)	(0, 0)

Playing with pure strategies 0000000000 Playing with mixed strategies

Nash's the 00000 otential games

The battle of the sexes

Robin and Charlie want to go out for the evening:

- Robin prefers to go to a movie
- Charlie prefers to go to the theater
- They both prefer being together instead of alone

The battle of the sexes

Robin and Charlie want to go out for the evening:

- Robin prefers to go to a movie
- Charlie prefers to go to the theater
- They both prefer being together instead of alone

Normal form representation:

- Players: $\mathcal{N} = \{R, C\}$
- Actions: $A_R = A_C = \{\text{movie, theater}\}$
- Payoff bimatrix:

$R\downarrow \ C \rightarrow$	movie	theater
movie	(3,2)	(0, 0)
theater	(0, 0)	(2,3)



Robin and Charlie arrive at an uncontrolled intersection:

- If they both drive through, they crash
- If they both yield, they may wait forever
- If one yields and the other drives through, the latter loses less time



Robin and Charlie arrive at an uncontrolled intersection:

- If they both drive through, they crash
- If they both yield, they may wait forever
- If one yields and the other drives through, the latter loses less time

Normal form representation:

- Players: $\mathcal{N} = \{R, C\}$
- Actions: $A_R = A_C = \{ drive, yield \}$
- Payoff bimatrix:

$R\downarrow \ C \rightarrow$	drive	yield
drive	(-100, -100)	(2,1)
yield	(1,2)	(0, 0)



2 Playing with pure strategies

B Playing with mixed strategies

4 Nash's theorem

6 Potential games

Playing with pure strategies

laying with mixed strategies

s Nash's th

Potential gan 00000 References

Dominated strategies

Sometimes, an action may yield consistently suboptimal payoffs

Definition (Dominated strategies)

1. A strategy $a_i \in A_i$ is **strictly dominated** by $a'_i \in A_i$ if

```
u_i(a_i; a_{-i}) < u_i(a'_i; a_{-i}) for all a_{-i} \in \mathcal{A}_{-i}
```

2. A strategy $a_i \in A_i$ is **weakly dominated** by $a'_i \in A_i$ if

 $u_i(a_i; a_{-i}) \leq u_i(a'_i; a_{-i})$ for all $a_{-i} \in \mathcal{A}_{-i}$

and $u_i(a_i; a_{-i}) < u_i(a'_i; a_{-i})$ for some $a_{-i} \in \mathcal{A}_{-i}$.

Notation:

- a_i is strictly dominated by $a'_i: a_i < a'_i$
- a_i is weakly dominated by $a'_i: a_i \leq a'_i$

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Playing with pure strategies

laying with mixed strategie:)00000000 Nash's the 0000C Potential games

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Examples, revisited

The prisoner's dilemma:

$R\downarrow \ C \rightarrow$	betray	silent
betray	(-2, -2)	(0, -3)
silent	(-3,0)	(-1, -1)

Split or steal:

$R\downarrow \ C \rightarrow$	split	steal
split	(\$6800,\$6800)	(0, \$13600)
steal	(\$13600,0)	(0, 0)

Battle of the sexes:

$R\downarrow \ C \rightarrow$	movie	theater
movie	(3,2)	(0,0)
theater	(0, 0)	(2,3)

ew & basic inform 00000000000	Introduction	n and basic examples	Playing witl 000●00	opure strategies	Playing with mixed st	Nash's theorem 000000	Potential games 00000	
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Iteratively dominated strategies

A larger game:

ew & basic information 000000000000	Introduction and basic examples	Playing with pure strategies 000●000000	Playing with mixed strategies	Nash's theorem 000000	Potential games 00000	
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Iteratively dominated strategies

A larger game:

(9,4)	(5,3)	(3,2)
(0, 1)	(4,6)	(6,0)
(2,1)	(3,5)	(2,4)

Definition

- 1. A strategy is called *iteratively dominated* if it becomes dominated after successive elimination of dominated strategies.
- 2. A game is called *dominance-solvable* if the successive elimination of dominated strategies leads to a singleton.

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Playing with pure strategies

aying with mixed strategies

Nash's theon 000000 Potential games

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Best responses

What if only the strategy of the opposing player(s) is known?

Definition (Best responses)

The strategy $a_i^* \in A_i$ is a **best response** to $a_{-i} \in A_{-i}$ if

$$u_i(a_i^*; a_{-i}) \ge u_i(a_i; a_{-i}) \quad \text{for all } a_i \in \mathcal{A}_i$$

or, equivalently, if

```
a_i^* \in \operatorname{arg\,max}_{a_i \in \mathcal{A}_i} u_i(a_i; a_{-i}).
```

```
The set-valued function BR_i: \mathcal{A}_{-i} \Rightarrow \mathcal{A}_i given by
```

$$BR_i(a_{-i}) = \arg\max_{a_i \in \mathcal{A}_i} u_i(a_i; a_{-i})$$

is called the **best-response correspondence**.

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aying with mixed strategies 0000000

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Examples

The prisoner's dilemma:

$R\downarrow \ C \rightarrow$	betray	silent
betray	(-2, -2)	(0, -3)
silent	(-3, 0)	(-1, -1)

Split or steal:

$R\downarrow \ C \rightarrow$	split	steal
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steal	(\$13600,0)	(0, 0)

Battle of the sexes:

$R\downarrow \ C \rightarrow$	movie	theater
movie	(3,2)	(0,0)
theater	(0, 0)	(2,3)

Dominated strategies and best responses

Some more examples of best responses

(9,4)	(5,3)	(3,2)
(0, 1)	(4,6)	(6,0)
(2,1)	(3,5)	(2,8)

Dominated strategies and best responses

Some more examples of best responses

(9,4)	(5,3)	(3,2)
(0, 1)	(4,6)	(6,0)
(2,1)	(3,5)	(2,8)

Best responses cannot contain dominated strategies

Dominated strategies and best responses

Some more examples of best responses

(9,4)	(5,3)	(3,2)
(0, 1)	(4,6)	(6,0)
(2,1)	(3,5)	(2,8)

Best responses cannot contain dominated strategies

● What about weakly dominated strategies?

Playing with pure strategies

laying with mixed strategies

Nash's the 00000 otential games



Nash equilibrium

Equilibrium: best-responding to each other's actions

Definition (Nash equilibrium)

An action profile $a^* = (a_1^*, ..., a_N^*)$ is a **Nash equilibrium** if

 $a_i^* \in BR_i(a_{-i}^*)$ for all $i \in \mathcal{N}$

or, equivalently, if

 $u_i(a_i^*; a_{-i}^*) \ge u_i(a_i; a_{-i}^*)$ for all $a_i \in \mathcal{A}_i$ and all $i \in \mathcal{N}$.

Intuition:

- Stability: no player has an incentive to deviate
- Unilateral resilience: stable against individual player deviations, not multi-player ones

ntroduction and basic exa

Playing with pure strategies

aying with mixed strategies

Nash's th

Potential games 00000 References

Examples, revisited

The prisoner's dilemma:

$R\downarrow \ C \rightarrow$	betray	silent
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$R\downarrow \ C \rightarrow$	split	steal
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Battle of the sexes:

$R\downarrow \ C \rightarrow$	movie	theater
movie	(3,2)	(0,0)
theater	(0, 0)	(2,3)

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Playing with pure strategies

aying with mixed strategies 0000000 Nash's theore

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RPS, revisited

How about Rock-Paper-Scissors?

	R	Р	S
R	0	-1	1
Р	1	0	-1
S	-1	1	0



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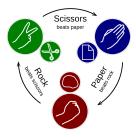
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RPS, revisited

How about Rock-Paper-Scissors?

	R	Р	S
R	0	-1	1
Р	1	0	-1
S	-1	1	0



Nash equilibria don't always exist!

33/49

	ew & basic information	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies ●0000000	Nash's theorem 000000	Potential games 00000	
X	Outline						
	Overview &						

- Playing with pure strategies
- Output: Base of the strategies of the strateg

4 Nash's theorem

6 Potential games

Playing with mixed strategies 0000000

Mixed strategies

Instead of playing pure strategies, players could **mix** their actions:

- Mixed strategy of player $i \in \mathcal{N}$: probability distribution x_i on \mathcal{A}_i
- Notation: x_{ia_i} = prob. that player *i* selects $a_i \in A_i$
- **Strategy space** of player *i*: ►

$$\mathcal{X}_i \coloneqq \Delta(\mathcal{A}_i) = \left\{ x_i \in \mathbb{R}^{\mathcal{A}_i} : x_{ia_i} \ge 0 \text{ and } \sum_{a_i \in \mathcal{A}_i} x_{ia_i} = 1 \right\}$$

• $\Delta(\mathcal{A}_i) \sim \text{simplex spanned by } \mathcal{A}_i$

Support of x_i : actions that are played with positive probability under x_i ►

$$\operatorname{supp}(x_i) \coloneqq \{a_i \in \mathcal{A}_i : x_{ia_i} > 0\}$$

 x_i is **pure** when supp (x_i) is a singleton, i.e.,

$$supp(x_i) = \{a_i\}$$
 for some $a_i \in \mathcal{A}_i$

Origin of the term "pure strategies"

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Playing with pure strategie 0000000000 Playing with mixed strategies

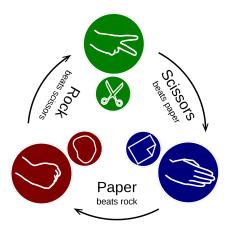
Nash's th 00000 tential games



RPS, revisited

Playing with mixed strategies:

• Players: $\mathcal{N} = \{1, 2\}$



	ew & basic information 000000000000	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies 00●00000	Nash's theorem 000000	Potential games 00000	
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(R)

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(S)

- ▶ Players: *N* = {1, 2}
- Actions: $A_i = \{R, P, S\}$

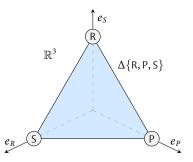
 Overview & basic information
 Introduction and basic examples
 Playing with pure strategies
 Playing with mixed strategies
 Nash's theorem
 Potential games
 References

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 RPS, revisited

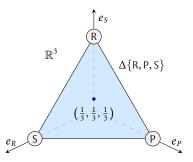
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- Players: $N = \{1, 2\}$
- Actions: $A_i = \{R, P, S\}$
- Mixed strategy space: $\mathcal{X}_i = \Delta\{\mathsf{R},\mathsf{P},\mathsf{S}\}$

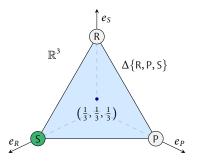


Playing with mixed strategies 0000000 **RPS**, revisited

- Players: $\mathcal{N} = \{1, 2\}$
- Actions: $A_i = \{R, P, S\}$
- Mixed strategy space: $\mathcal{X}_i = \Delta \{R, P, S\}$ ►
- Choose mixed strategy $x_i \in \mathcal{X}_i$



- Players: $N = \{1, 2\}$
- Actions: $A_i = \{R, P, S\}$
- Mixed strategy space: $\mathcal{X}_i = \Delta\{R, P, S\}$
- Choose mixed strategy $x_i \in \mathcal{X}_i$
- Choose action $a_i \sim x_i$



When all players mix their actions:

- Each player $i \in \mathcal{N}$ uses a mixed strategy $x_i \in \mathcal{X}_i$
- ▶ Prob. of selecting the action profile $a = (a_1, ..., a_N) \in \mathcal{A} = \prod_i \mathcal{A}_i$:

$$x_{a_1,\ldots,a_N}=\prod\nolimits_{j\in\mathcal{N}}x_{ja_j}$$

Prob. of selecting $a_{-i} \in \mathcal{A}_{-i}$:

$$x_{-i;a_{-i}} = \prod_{j \neq i} x_{ja_j}$$

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Prob. of selecting $a_{-i} \in \mathcal{A}_{-i}$:

$$x_{-i;a_{-i}} = \prod_{j \neq i} x_{ja_j}$$

Mixed strategy profile:

$$x = (x_1, \ldots, x_N) \in \mathcal{X} \coloneqq \prod_{i \in \mathcal{N}} \mathcal{X}_i$$

Mixed strategy profile of i's opponents:

$$x_{-i} = (x_1, \ldots, x_i, \ldots, x_N) \in \mathcal{X}_{-i} \coloneqq \prod_{j \neq i} \mathcal{X}_j$$

NB: $\mathcal{X} = \prod_j \Delta(\mathcal{A}_j) \neq \Delta(\prod_j \mathcal{A}_j) = \Delta(\mathcal{A})$

mixed vs. correlated strategies

Expected payoffs under mixed strategies:

Expected payoff to a player under a mixed strategy profile:

$$u_i(x) = \sum_{a_1 \in \mathcal{A}_1} \cdots \sum_{a_N \in \mathcal{A}_N} x_{1,a_1} \cdots x_{N,a_N} u_i(a_1,\ldots,a_N)$$

or, in terms of other players' strategies:

$$u_{i}(x_{i}; x_{-i}) = \sum_{a_{i} \in \mathcal{A}_{i}} \sum_{a_{-i} \in \mathcal{A}_{-i}} x_{ia_{i}} x_{-i;a_{-i}} u_{i}(a_{i}; a_{-i})$$

• Expected payoff to a pure strategy under a mixed strategy profile:

$$v_{ia_i}(x) \coloneqq u_i(a_i; x_{-i}) = \sum_{a_{-i} \in \mathcal{A}_{-i}} x_{-i;a_{-i}} u_i(a_i; a_{-i})$$

Expected payoffs

Expected payoffs under mixed strategies:

• Expected payoff to a player under a mixed strategy profile:

$$u_i(x) = \sum_{a_1 \in \mathcal{A}_1} \cdots \sum_{a_N \in \mathcal{A}_N} x_{1,a_1} \cdots x_{N,a_N} u_i(a_1,\ldots,a_N)$$

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$$u_{i}(x_{i}; x_{-i}) = \sum_{a_{i} \in \mathcal{A}_{i}} \sum_{a_{-i} \in \mathcal{A}_{-i}} x_{ia_{i}} x_{-i;a_{-i}} u_{i}(a_{i}; a_{-i})$$

• **Expected payoff to a pure strategy** under a mixed strategy profile:

$$v_{ia_i}(x) \coloneqq u_i(a_i; x_{-i}) = \sum_{a_{-i} \in \mathcal{A}_{-i}} x_{-i;a_{-i}} u_i(a_i; a_{-i})$$

Mixed payoff vectors:

$$v_i(x) = (v_{ia_i}(x))_{a_i \in \mathcal{A}_i} = (u_i(a_i; x_{-i}))_{a_i \in \mathcal{A}_i}$$

SO

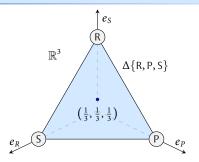
$$u_i(x) = \langle v_i(x), x_i \rangle$$

NB: u_i is **linear** in x_i ; v_{ia_i} and v_i are **independent** of x_i

iew & basic information	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies 00000€00	Nash's theorem 000000	Potential games 00000	

Go-to example: Rock-Paper-Scissors

- Players: $N = \{1, 2\}$
- Actions: $A_i = \{R, P, S\}$
- Mixed strategies: $x_i \in \mathcal{X}_i$

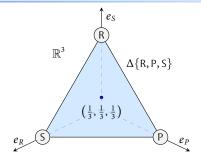


	iew & basic information 0000000000000	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies 00000●00	Nash's theorem	Potential games 00000	
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Go-to example: Rock-Paper-Scissors

Playing with mixed strategies:

- Players: $N = \{1, 2\}$
- Actions: $A_i = \{R, P, S\}$
- Mixed strategies: $x_i \in \mathcal{X}_i$



Mixed strategy payoffs:

$$u_{1}(x_{1}, x_{2}) = x_{1,R}x_{2,R} \cdot (0) + x_{1,R}x_{2,P} \cdot (-1) + x_{1,R}x_{2,S} \cdot (1) + x_{1,P}x_{2,R} \cdot (1) + x_{1,P}x_{2,P} \cdot (0) + x_{1,P}x_{2,S} \cdot (-1) + x_{1,S}x_{2,R} \cdot (-1) + x_{1,S}x_{2,P} \cdot (1) + x_{1,S}x_{2,S} \cdot (0) = x_{1,R}(x_{2,S} - x_{2,P}) + x_{1,P}(x_{2,R} - x_{2,S}) + x_{1,S}(x_{2,P} - x_{2,R}) = x_{1}^{T}Ax_{2} u_{2}(x_{1}, x_{2}) = -u_{1}(x_{1}, x_{2})$$

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Playing with pure strategie

Playing with mixed strategies

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Mixed extensions

Definition (Mixed extension of a finite game)

The *mixed extension* of a finite game $\Gamma = \Gamma(\mathcal{N}, \mathcal{A}, u)$ is the *continuous* game $\Delta(\Gamma)$ with

- Players $i \in \mathcal{N} = \{1, \dots, N\}$
- Actions $x_i \in \mathcal{X}_i = \Delta(\mathcal{A}_i)$ per player $i \in \mathcal{N}$
- Payoff functions $u_i: \mathcal{X} \to \mathbb{R}, i \in \mathcal{N}$

Notes:

- Continuous game: game with continuous action spaces (here X_i instead of A_i)
- **Context:** when clear, we will not distinguish between Γ and $\Delta(\Gamma)$

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'laying with pure strategie: 0000000000 Playing with mixed strategies

Nash's th

Potential games

References

Mixed best responses

Extending the notion of best-responding to mixed strategies

Definition (Mixed best responses)

The mixed strategy $x_i^* \in \mathcal{X}_i$ is a **best response** to the mixed profile $x_{-i} \in \mathcal{X}_{-i}$ if

$$u_i(x_i^*; x_{-i}) \ge u_i(x_i; x_{-i}) \quad \text{for all } x_i \in \mathcal{X}_i$$

or, equivalently, if

$$x_i^* \in \operatorname{arg\,max}_{x_i \in \mathcal{X}_i} u_i(x_i; x_{-i}) = \operatorname{arg\,max}_{x_i \in \mathcal{X}_i} \langle v_i(x), x_i \rangle$$

As before, we write $BR_i(x_{-i}) = \arg \max_{x_i \in \mathcal{X}_i} u_i(x_i; x_{-i})$.

Notes:

• Structure: BR_i (x_{-i}) is always a face of \mathcal{X}_i

● Why?

Notation: rely on context to distinguish between pure / mixed best responses

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Nash's theorem

Reference



Overview & basic information

- Playing with pure strategies
- 3 Playing with mixed strategies

4 Nash's theorem

6 Potential games

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Playing with pure strategies

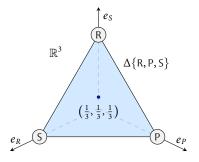
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Go-to example: Rock-Paper-Scissors

- ▶ Players: *N* = {1, 2}
- Actions: $A_i = \{R, P, S\}$
- Mixed strategies: $x_i^* \in \mathcal{X}_i$



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Playing with pure strategies

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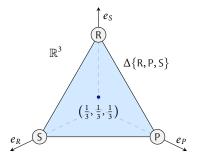
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Go-to example: Rock-Paper-Scissors

Playing with mixed strategies:

- Players: $N = \{1, 2\}$
- Actions: $A_i = \{R, P, S\}$
- Mixed strategies: $x_i^* \in \mathcal{X}_i$



Mixed strategy payoffs when $x_1^* = x_2^* = (1/3, 1/3, 1/3)$:

$$u_1(x_1^*, x_2^*) = \frac{1}{3} \left(\frac{1}{3} - \frac{t}{3} \right) + \frac{1}{3} \left(\frac{1}{3} - \frac{t}{3} \right) + \frac{1}{3} \left(\frac{1}{3} - \frac{t}{3} \right) = 0 = u_2(x_1^*, x_2^*)$$

ntroduction and basic exam

laying with pure strategies

laying with mixed strategies

Nash's theorem

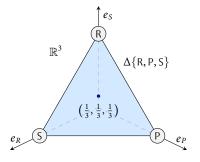
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Go-to example: Rock-Paper-Scissors

Playing with mixed strategies:

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- Actions: $A_i = \{R, P, S\}$
- Mixed strategies: $x_i^* \in \mathcal{X}_i$



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In fact:

$$u_1(x_1, x_2^*) = 0 = u_2(x_1^*, x_2)$$
 for all $x_1 \in \mathcal{X}_1, x_2 \in \mathcal{X}_2$

so

 $x_1^* \in BR_1(x_2^*)$ and $x_2^* \in BR_2(x_1^*)$

ntroduction and basic exam

Playing with pure strategies

laying with mixed strategies

Nash's theorem 000000

otential games



Nash equilibrium in mixed strategies

Extending the notion of equilibrium to mixed strategies

Definition (Nash equilibrium)

A strategy profile $x^* = (x_1^*, \dots, x_N^*)$ is a **Nash equilibrium** if

 $x_i^* \in \mathrm{BR}_i(x_{-i}^*)$ for all $i \in \mathcal{N}$

or, equivalently, if

 $u_i(x_i^*; x_{-i}^*) \ge u_i(x_i; x_{-i}^*)$ for all $x_i \in \mathcal{X}_i$ and all $i \in \mathcal{N}$.

Notes:

- Unilateral stability: ceteris paribus, no player has an incentive to deviate
- If x^* is pure \implies pure Nash equilibrium
- ▶ If ">" instead of "≥" for $x_i \neq x_i^* \implies$ strict Nash equilibrium
- **Prove:** x^* is strict \iff BR_i (x^*_{-i}) is a singleton for all $i \in \mathcal{N}$

otherwise "mixed"



Nash's theorem

RPS admits a Nash equilibrium in mixed strategies - is this always the case?

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Nash's theorem

RPS admits a Nash equilibrium in mixed strategies - is this always the case?

Theorem (Nash, 1950)

Every finite game admits a Nash equilibrium in mixed strategies.

Notes:

- Support: Nash's theorem does not specify the support or other properties
- Oddness: generically odd number of equilibria
- Index: generically, if m pure equilibria, at least m 1 mixed equilibria

Wilson (1971)
Ritzberger (1994)

Overview & basic information		Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies	Nash's theorem 0000●0	Potential games 00000	
X	Proof, Part I						

Skeleton of the proof:

• Introduce collective best-response correspondence BR: $X \Rightarrow X$ given by

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BR(x) = (BR_i(x_{-i}))_{i=1,\ldots,N}
```

• x^* is a Nash equilibrium $\iff x^* \in BR(x^*)$

Overview & basic information		Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies	Nash's theorem 0000●0	Potential games 00000	
No.	Proof, Part I						

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▶ Introduce collective best-response correspondence BR: $X \Rightarrow X$ given by

 $BR(x) = (BR_i(x_{-i}))_{i=1,\ldots,N}$

- ► x^* is a Nash equilibrium $\iff x^* \in BR(x^*)$
- Invoke Kakutani's fixed-point theorem for set-valued functions.

Theorem (Kakutani, 1941)

Let C be a nonempty compact convex subset of \mathbb{R}^d , and let $F: C \Rightarrow C$ be a set-valued function such that:

- (P1) F(x) is nonempty, closed and convex for all $x \in C$
- (P2) *F* is **upper hemicontinuous** at all $x \in C$, i.e., $\tilde{x} \in F(x)$ whenever $x_t \to x$ and $\tilde{x}_t \to \tilde{x}$ for sequences $x_t \in C$ and $\tilde{x}_t \in F(x_t)$.

Then there exists some $x^* \in C$ such that $x^* \in F(x^*)$.

➡ Upper hemicontinuity ↔ closed graph

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laying with pure strategi

Playing with mixed strategi 00000000

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➡ Why?

Proof, Part II

Verify the conditions of Kakutani's theorem for $C \leftarrow X$ and $F \leftarrow BR$:

(P1) BR(x) is a face of \mathcal{X} , so it is nonempty, closed and convex

(P2) Argue by contradiction

- Suppose there exist sequences $x_t, \tilde{x}_t \in \mathcal{X}, t = 1, 2, \dots$, such that $x_t \to x, \tilde{x}_t \to \tilde{x}$ and $\tilde{x}_t \in BR(x_t)$, but $\tilde{x} \notin BR(x)$.
- ▶ Then there exists a player $i \in \mathcal{N}$ and a deviation $x'_i \in \mathcal{X}_i$ such that

$$u_i(x'_i; x_{-i}) > u_i(\tilde{x}_i; x_{-i})$$

But since $\tilde{x}_{i,t} \in BR(x_{-i,t})$ by assumption, we also have:

$$u_i\bigl(x_i';x_{-i,t}\bigr) \leq u_i\bigl(\tilde{x}_{i,t};x_{-i,t}\bigr)$$

Since $x_t \rightarrow x$, $\tilde{x}_t \rightarrow \tilde{x}$ and u_i is continuous, taking limits gives

 $u_i(x'_i; x_{-i}) \leq u_i(\tilde{x}_i; x_{-i})$

which contradicts our original assumption.



Overview & basic information

- Playing with pure strategies
- B Playing with mixed strategies

4 Nash's theorem

5 Potential games

Potential games and best responses

Going back to pure strategies:

- ► In single-player games: Nash equilibria (maximizers) trivially exist
- In multi-player games: not true

Bridge between single- and multi-player settings?

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Potential games and best responses

Going back to pure strategies:

- In single-player games: Nash equilibria (maximizers) trivially exist ►
- In multi-player games: not true

Bridge between single- and multi-player settings?

Definition (Potential games; Monderer & Shapley, 1996)

A finite game $\Gamma \equiv \Gamma(\mathcal{N}, \mathcal{A}, u)$ is a **potential game** if there exists a function $\Phi: \mathcal{A} \to \mathbb{R}$ such that

$$u_i(a'_i; a_{-i}) - u_i(a_i; a_{-i}) = \Phi(a'_i; a_{-i}) - \Phi(a_i; a_{-i})$$

for all $a, a' \in \mathcal{A}$ and all $i \in \mathcal{N}$.

Potential games

Potential games and best responses

Going back to pure strategies:

- In single-player games: Nash equilibria (maximizers) trivially exist
- In multi-player games: not true

Bridge between single- and multi-player settings?

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$$u_i(a_i';a_{-i}) - u_i(a_i;a_{-i}) = \Phi(a_i';a_{-i}) - \Phi(a_i;a_{-i})$$

for all $a, a' \in \mathcal{A}$ and all $i \in \mathcal{N}$.

Examples

- Battle of the sexes
- Congestion games (more later...)

Overview & basic information		Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies	Nash's theorem 000000	Potential games OO●OO	
X	Basic propert	ies					

Existence of equilibria:

• Any *global maximizer* $a^* \in \arg \max \Phi$ of Φ is a pure Nash equilibrium

Existence of equilibria:

- Any *global maximizer* $a^* \in \arg \max \Phi$ of Φ is a pure Nash equilibrium
- Any **unilateral maximizer** $a^* \in \mathcal{A}$ of Φ is a pure Nash equilibrium
- Unilateral maximizers:

 $\Phi(a^*) \ge \Phi(a_i; a_{-i}^*)$ for all $a_i \in \mathcal{A}_i$ and all $i \in \mathcal{N}$

Existence of equilibria:

- Any *global maximizer* $a^* \in \arg \max \Phi$ of Φ is a pure Nash equilibrium
- Any **unilateral maximizer** $a^* \in \mathcal{A}$ of Φ is a pure Nash equilibrium
- Unilateral maximizers:

 $\Phi(a^*) \ge \Phi(a_i; a_{-i}^*)$ for all $a_i \in \mathcal{A}_i$ and all $i \in \mathcal{N}$

When is a game a potential one?

Proposition

 Γ is a potential game if and only if

 $\nabla_{x_i} v_i(x) = \nabla_{x_i} v_j(x)$ for all $x \in \mathcal{X}$ and all $i, j \in \mathcal{N}$

where $v_i(x) = (u_i(a_i; x_{-i}))_{a_i \in A_i}$ is the mixed payoff vector of player $i \in \mathcal{N}$.

Overview & basic information	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies	Nash's theorem 000000	Potential games 00000	

Best-response dynamics

A natural updating process:

- Players may choose a new action at each t = 1, 2, ...
- Players best-respond if this strictly increases their payoff

Definition (Best-response dynamics)

The **best-response dynamics** are defined by the recursion

$$a_{i_t,t+1} \begin{cases} \in BR_{i_t}(a_{-i_t,t}) & \text{if } a_{i_t,t} \notin BR_{i_t}(a_{-i_t,t}) \\ = a_{i_t,t} & \text{otherwise} \end{cases}$$

where i_t is any player that updates at stage t.

Notes:

- Simultaneous: all players update simultaneously
- Iterative: players update in a round robin fashion
- Randomized: random subset of players updates at any given stage

(BRD)

ew & basic information 000000000000	Introduction and basic examples	Playing with pure strategies	Playing with mixed strategies 00000000	Nash's theorem 000000	Potential games 0000●	



Convergence

Does (BRD) converge?

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Convergence

Does (BRD) converge?

X No - and different modes of updating don't help



Playing with pure strategi 0000000000 Playing with mixed strategie 00000000

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Convergence

Does (BRD) converge?

✗ No − and different modes of updating don't help



But good convergence properties in potential games:

Proposition (Monderer & Shapley, 1996)

Let Γ be a finite potential game. Then the iterative version of (BRD) converges to a pure Nash equilibrium after finitely many steps.

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Convergence

Does (BRD) converge?

X No - and different modes of updating don't help

Think RPS

But good convergence properties in potential games:

Proposition (Monderer & Shapley, 1996)

Let Γ be a finite potential game. Then the iterative version of (BRD) converges to a pure Nash equilibrium after finitely many steps.

Notes:

Simple proof: potential before and after an update is ►

 $\Phi(a_i^+; a_{-i}) - \Phi(a_i; a_{-i}) = u_i(a_i^+; a_{-i}) - u_i(a_i; a_{-i}) > 0$

whenever $a_i^+ \neq a_i \implies$ no action profile is visited twice \implies the process stops

► Iterative vs. simultaneous: the distinction matters, simultaneous (BRD) may cycle

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