

Σχολιανωτικές λαρνάκες - Διαδ. ΡοέςΆσκ 1

Βρείτε τις επώνυμες λαρνάκες των εργαλείων  $\delta, \pi \in \mathcal{D}(\mathbb{R}^2)$ :

$$(a) \xi = y \frac{\partial}{\partial y}$$

Άναρτ.  $\xi_1 = 0, \xi_2 = y = p \circ \text{id} = p \xi_2$

$$\dot{\alpha} = \xi_0 \alpha \Leftrightarrow \left\{ \begin{array}{l} \alpha'_1(t) = \xi_1(\alpha_1(t), \alpha_2(t)) \\ \alpha'_2(t) = \xi_2(\alpha_1(t), \alpha_2(t)) \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \alpha'_1(t) = 0 \\ \alpha'_2(t) = \alpha_2(t) \end{array} \right\} \Leftrightarrow$$

$$\Leftrightarrow \left\{ \begin{array}{l} \alpha_1(t) = c_1 \\ \alpha_2(t) = c_2 e^t \end{array} \right\} \Leftrightarrow \tilde{\alpha}(t) = (c_1, c_2 e^t) \Leftrightarrow$$

$$\Leftrightarrow \alpha(t) = \text{id}_{\mathbb{R}^2}^{-1} \circ \tilde{\alpha}(c_1, c_2 e^t) = (c_1, c_2 e^t)$$

Πιλ. αρχ. σημ.  $(x, y)$  πρέπει  $\alpha(0) = (x, y) = (c_1, c_2)$ .

$$\boxed{\alpha_{(x,y)}(t) = (x, y e^t)}$$

$$(b) \xi = x \frac{\partial}{\partial x} + 2y \frac{\partial}{\partial y}$$

Άναρτ.  $\xi_1 = x = p \circ \text{id} = p \xi_1, \xi_2 = 2y = 2p \circ \xi_2$

$$\dot{\alpha} = \xi_0 \alpha \Leftrightarrow \left\{ \begin{array}{l} \alpha'_1(t) = \alpha_1(t) \\ \alpha'_2(t) = 2\alpha_2(t) \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \alpha_1(t) = c_1 e^t \\ \alpha_2(t) = c_2 e^{2t} \end{array} \right\} \Leftrightarrow$$

$$\Leftrightarrow \tilde{\alpha}(t) = \alpha(t) = (c_1 e^t, c_2 e^{2t})$$

Πιλ. αρχ. σημ.  $\alpha(0) = (x, y) \Leftrightarrow c_1 = x, \wedge c_2 = y$

$$\boxed{\alpha_{(x,y)}(t) = (x e^t, y e^{2t})}$$

(2)

$$(8) \eta = y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \quad | \quad \eta_1 = y = \text{pr}_2, \quad \eta_2 = x = \text{pr}_1$$

$$\dot{\alpha} = \eta \circ \alpha \Leftrightarrow \begin{cases} \alpha'_1(t) = \alpha'_2(t) \\ \alpha'_2(t) = \alpha'_1(t) \end{cases} \Rightarrow \begin{cases} \alpha''_1(t) = \alpha''_2(t) \\ \alpha''_2(t) = \alpha''_1(t) \end{cases}$$

$$\Rightarrow \begin{cases} \alpha_1(t) = c_1 e^t + c_2 e^{-t} \\ \alpha_2(t) = c_1 e^t - c_2 e^{-t} \end{cases} \Rightarrow$$

$$\Rightarrow \tilde{\alpha}(t) = \alpha(t) = (c_1 e^t + c_2 e^{-t}, c_1 e^t - c_2 e^{-t}).$$

$\alpha_1, \alpha_2$  apx. und  $\alpha(0) = (x, y) \Rightarrow$

$$\Rightarrow \begin{cases} c_1 + c_2 = x \\ c_1 - c_2 = y \end{cases} \Rightarrow \begin{cases} c_1 = \frac{x+y}{2} \\ c_2 = \frac{x-y}{2} \end{cases} \Rightarrow$$

$$\Rightarrow \boxed{\alpha(t) = \left( \frac{x+y}{2} e^t + \frac{x-y}{2} e^{-t}, \frac{x+y}{2} e^t - \frac{x-y}{2} e^{-t} \right)}.$$

Max 2:  $(x, y) = (0, 0) \Rightarrow \alpha(t) \equiv (0, 0) = \text{stet.}$

Aufgabe 2

Zu  $M = \mathbb{R}^2 \setminus \{(0,0)\}$  spezielle Vektorfelder. Zu

$$\xi = \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

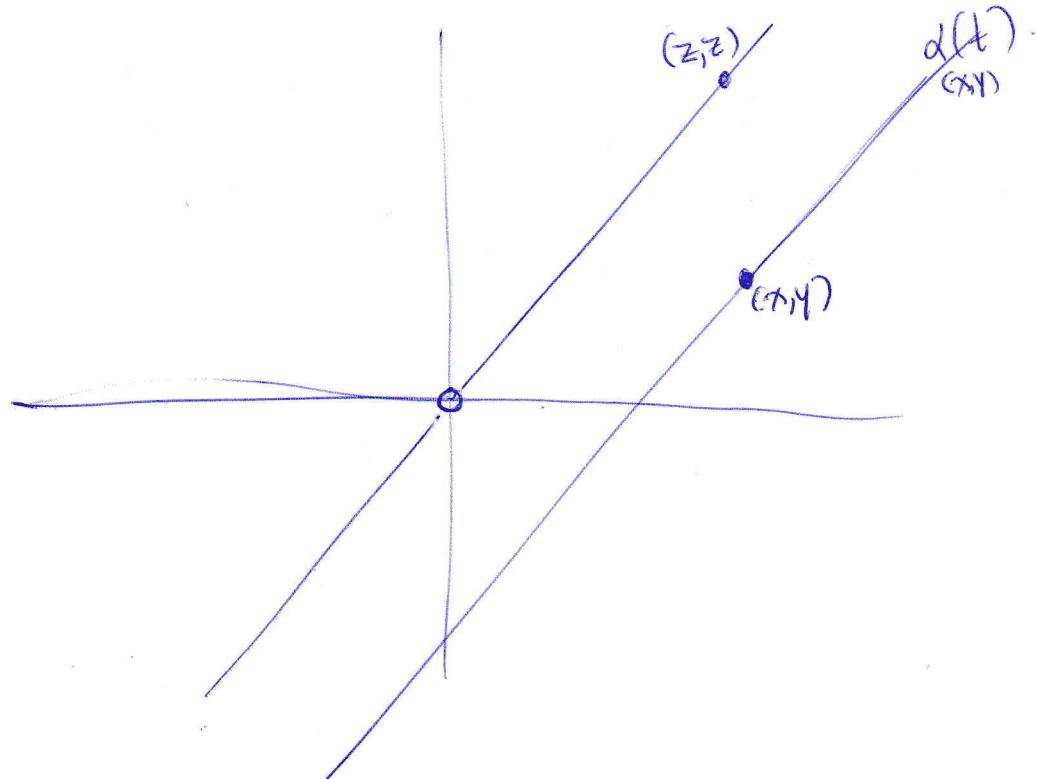
Einen Vektorfelder,

$$\text{Anmerkung: } \xi_1 = 1 = \xi_2$$

$$\dot{x} = \xi_0 \omega \Leftrightarrow \begin{cases} \alpha'_1(t) = 1 \Leftrightarrow \alpha_1(t) = t + c_1 \\ \alpha'_2(t) = 1 \Leftrightarrow \alpha_2(t) = t + c_2 \end{cases} \Rightarrow \tilde{\alpha}(t) = \alpha(t) = (t + c_1, t + c_2)$$

$$\alpha(0) = (x, y) \Leftrightarrow (c_1, c_2) = (x, y). \quad \text{Ansatz:}$$

$$\boxed{\alpha_{(x,y)}(t) = (x+t, y+t)}$$



$\forall (x,y) \in M \quad x \neq y \quad \alpha_{(x,y)}(t) \text{ ist stetig f\"ur alle } t \in \mathbb{R}.$

Wegen  $x = y \quad \alpha_{(x,x)}(t) \text{ ist stetig f\"ur alle } t \in \mathbb{R}.$

Aek 3

$$\dot{\alpha} = \xi \circ \alpha, \quad \text{N so } \overset{\cdot}{f \circ \alpha} = \xi(f) \circ \alpha$$

$$f: M \rightarrow \mathbb{R}$$

Ario S.

$$\overset{\cdot}{f \circ \alpha}(t) = Tf \circ T\alpha \circ \frac{d}{dt}(t) = Tf \circ \dot{\alpha}(t) = Tf \circ \xi \circ \alpha(t) =$$

$$= Tf(\xi_{\alpha(t)}) \equiv \underbrace{\overline{id} \circ Tf(\xi)}_{\alpha(t)} \stackrel{\oplus}{=} \xi_{\alpha(t)}(f) =$$

$$\begin{aligned} &= \xi(f)(\alpha(t)) = \\ &= \xi(f) \circ \alpha(t). \end{aligned}$$

Stew:  $v \in T_x M, f: M \rightarrow \mathbb{R} \Rightarrow T_x f(v) \equiv v(f).$

$$T_x f(v) \in T_{f(x)} \mathbb{R} \Rightarrow T_x f(v) \equiv \overline{id} \circ T_x f(v) =$$

$$= D(f \circ \bar{\varphi}^{-1})(\varphi(x))(\bar{\varphi}(v))$$

$$= D(f \circ \bar{\varphi}^{-1})(\varphi(x))((\varphi \circ \alpha)'(0))$$

$$= D(f \circ \alpha)(0)(1) = (f \circ \alpha)'(0) =$$

$$= v(f).$$

$$\begin{array}{ccc} T_x M & \xrightarrow{T_x f} & T_{f(x)} \mathbb{R} \\ \bar{\varphi} \downarrow & & \downarrow \overline{id} \\ \mathbb{R}^m & \longrightarrow & \mathbb{R} \\ D(f \circ \bar{\varphi}^{-1})(\varphi(x)) & & \end{array}$$

Aufgabe 5

$\Sigma \in \mathcal{X}(\mathbb{R})$     $\Sigma = x^2 \frac{d}{dx}$    Ns so  $\Sigma$  ist ein Tensor der wir bei einer Transformation von  $\Sigma$  zu  $\Sigma'$  erhalten.

Antwort:

$\Sigma$  ist eine quadratische Form:  $\Sigma = x^2 = \text{pr}_x^2 = \text{id}^2$ . (D.h.  $\Sigma(t) = t^2$ ).

$$\alpha = \Sigma \circ \alpha \Leftrightarrow \alpha'_1(t) \equiv \alpha'(t) = \Sigma_1(\alpha_1(t)) = \Sigma_1(\alpha_1(t)) = \alpha_1(t)^2.$$

$$\Sigma(t) = -t^2 \frac{d}{dt} \Big|_t$$

$$\alpha'(t) = -(\alpha_1(t))^2 \Rightarrow \boxed{\alpha(t) = \frac{1}{t+c}} \Rightarrow \alpha'(t) = -\left(\frac{1}{t+c}\right)^2$$

$$\alpha(0) = s = \frac{1}{c} \Rightarrow c = \frac{1}{s}.$$

$$\alpha_s(t) = \frac{1}{t+\frac{1}{s}} = \frac{s}{1+ts} \quad \text{bei der Aktion für } t = -\frac{1}{s}.$$

$$\Theta(t, s) = \frac{s}{1+ts} \quad \text{für alle } \Theta(\xi) = \{ (t, s) \in \mathbb{R}^2 : ts \neq -1 \}$$

A&K. 6

$$\Theta: \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2: \Theta(t, (x, y)) = ((2 + \sin y)t + x, y).$$

Ns o  $\Theta$  pon kai va speize tis aitierogrizous jenizopas.

Anoös.

(1)  $\Theta$  diaqopigikn.

$$\Theta(0, (x, y)) = ((2 + \sin y) \cdot 0 + x, y) = (x, y).$$

$$\Theta(t, \Theta(s, (x, y))) = \Theta(t, (\underbrace{(2 + \sin y)s + x}_{x'}, y)) =$$

$$= ((2 + \sin y)t + x', y) =$$

$$= ((2 + \sin y)t + (2 + \sin y)s + x, y) =$$

$$= ((2 + \sin y)(t + s) + x, y) =$$

$$= \Theta(t + s, (x, y)).$$

Aeta einai diaqopirkj proj.

(2) Av  $\xi$  o aitierogrizous jenizopas, wste

$$\xi_{(x,y)} = \dot{\Theta}_{(x,y)}(0) = T_0 \Theta_{(x,y)}\left(\frac{d}{dt}|_0\right) \in T_{(x,y)} \mathbb{R}^2$$

Tnologizoume zo  $\overline{id}_{\mathbb{R}^2}(\xi_{(x,y)})$ , xrhsimopoiwras  
zo fteratethiki diaqopika

$$\frac{d}{dt}|_0 \in T_0 \mathbb{R} \xrightarrow{T_0 \Theta_{(x,y)}} T_{(x,y)} \mathbb{R}^2 \ni \xi_{(x,y)}$$

$$\overline{id}_{\mathbb{R}^2} \downarrow \qquad \qquad \qquad \downarrow \overline{id}_{\mathbb{R}^2}$$

$$\mathbb{R} \longrightarrow \mathbb{R}^2$$

$$D\Theta_{(x,y)}(id_{\mathbb{R}}(0))$$

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$$\overline{\text{id}}_{\mathbb{R}^2}(\xi_{(x,y)}) = \overline{\text{id}}_{\mathbb{R}^2} \circ T_0 \theta_{(x,y)} \left( \frac{d}{dt} \Big|_0 \right) =$$

$$= D\theta_{(x,y)}(\text{id}_{\mathbb{R}}(0)) \circ \overline{\text{id}}_{\mathbb{R}} \left( \frac{d}{dt} \Big|_0 \right) =$$

$$= D\theta_{(x,y)}(0)(1) = \theta'_{(x,y)}(0) =$$

$$= (2 + \sin y, 0) \Rightarrow$$

$$\Rightarrow \xi_{(x,y)} = \overline{\text{id}}_{\mathbb{R}^2}^{-1}(2 + \sin y, 0) =$$

$$= (2 + \sin y) \cdot \overline{\text{id}}_{\mathbb{R}^2}^{-1}(1, 0) =$$

$$= (2 + \sin y) \frac{\partial}{\partial x_1} \Big|_{(x,y)}$$