

ΚΕΦ. 5

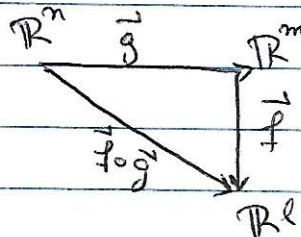
ΠΕΡΙΕΧΟΜΕΝΑ

- Ⓐ Κανόνες της Αλυσίδας / Αλυσίδα ή Παραγώγιση / Διαφ. σύνθεσης
Θ. Μέγιστη Τιμή Δ.Α. 2 συναρτήσεων
(βλ. θ. ευδιαμέσων τμηών)
- Ⓑ Θ. Αντιστροφή
- Ⓒ Θ. Πεπλεγμένης Συναρτήσεων
- Ⓓ Εφ. Εφαπτομένη, εφ. Επίπεδο

ΕΦΑΡΜΟΓΕΣ ΤΟΥ ΔΙΑΦΟΡΙΚΟΥ (ΚΕΦ. 5+6)

Ⓐ $f: A(\subseteq \mathbb{R}^n) \rightarrow \mathbb{R}^l$, f είναι C^1 θ: Μαθημα

$\Rightarrow \frac{\partial f}{\partial x_i}, i=1,2,\dots,n$



26/10/20

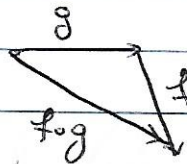
είναι συνεχείς στο A

Τι ζητάμε;

? Αν η \vec{g} διαφορίσιμη, \vec{f} διαφορίσιμη είναι η $\vec{f} \circ \vec{g}$?
 ? Διαφορίσιμη? Ποιο είναι το διαφωρικό της $\vec{f} \circ \vec{g}$?

Τι συμβαίνει για $n=m=l=1$;

Εάν $g: \mathbb{R} \rightarrow \mathbb{R}$, $\exists g'(x_0)$ ($x_0 \in \mathbb{R}$)
 $f: \mathbb{R} \rightarrow \mathbb{R}$, $\exists f'(g(x_0))$. Τότε



i) Υπάρχει η $(f \circ g)'(x_0)$ *

ii) $(f \circ g)'(x_0) = f'(g(x_0)) \cdot g'(x_0)$

• $d(f \circ g)(x_0): \mathbb{R} \rightarrow \mathbb{R}$, Γραμμική
 με "νιπιακά" $((f \circ g)'(x_0))$ ①

• $dg(x_0): \mathbb{R} \rightarrow \mathbb{R}$, Γραμμική
 με "νιπιακά" $(g'(x_0))$ ②

• $df(g(x_0)): \mathbb{R} \rightarrow \mathbb{R}$, Γραμμική
 με "νιπιακά" $(f'(g(x_0)))$ ③

Από την * έχουμε

$$d(f \circ g)(x_0) = df(g(x_0)) \circ dg(x_0)$$

\downarrow ①
 \downarrow ②
 \downarrow ③

$(f \circ g)'(x_0)$
 $f'(g(x_0))$
 $g'(x_0)$

Θεώρημα (Αλυσίδας - Διαφορίων - Σύνθεσης Συναρτ.)

Έστω $\vec{g}: A \rightarrow \mathbb{R}^m$, $\vec{x}_0 \in A$ και $\exists d\vec{g}(\vec{x}_0)$
 όπου $\vec{x}_0 \in A (\subseteq \mathbb{R}^n)$.

Επιπλέον θεωρούμε $\vec{f}: B (\subseteq \vec{g}(A)) \rightarrow \mathbb{R}^l$ και
 $\exists d\vec{f}(\vec{g}(\vec{x}_0))$. Τότε

i) Υπάρχει το $d(\vec{f} \circ \vec{g})(\vec{x}_0)$
 $d(\vec{f} \circ \vec{g})(\vec{x}_0) = d\vec{f}(\vec{g}(\vec{x}_0)) \circ d\vec{g}(\vec{x}_0)$

συνταξ
 Jacobi

ii) $J_{\vec{f} \circ \vec{g}}(\vec{x}_0) = J_{\vec{f}}(\vec{g}(\vec{x}_0)) \cdot J_{\vec{g}}(\vec{x}_0)$

Αποδ. \rightarrow Παράδειγμα (είναι διαδικαστική)

ΚΑΝΟΝΑΣ ΑΛΥΣΙΔΑΣ

$$\vec{g} = (g_1, g_2, \dots, g_m), \quad \vec{x}_0 \in A (\subseteq \mathbb{R}^n)$$

$$\vec{f} = (f_1, f_2, \dots, f_l)$$

$$\vec{h} = \vec{f} \circ \vec{g} : A (\subseteq \mathbb{R}^n) \rightarrow \mathbb{R}^l \quad \vec{h} = \vec{f} \circ \vec{g}$$

$$\vec{h} = (h_1, h_2, \dots, h_l)$$

Γράφουμε την (ii) (του θεωρήματος)

$$\begin{pmatrix} \frac{\partial h_1}{\partial x_1} & \frac{\partial h_1}{\partial x_2} & \dots & \frac{\partial h_1}{\partial x_n} \\ \vdots & \vdots & & \vdots \\ \frac{\partial h_l}{\partial x_1} & \frac{\partial h_l}{\partial x_2} & \dots & \frac{\partial h_l}{\partial x_n} \end{pmatrix} (\vec{x}_0) = \begin{pmatrix} \frac{\partial f_1}{\partial t_1} & \frac{\partial f_1}{\partial t_2} & \dots & \frac{\partial f_1}{\partial t_m} \\ \vdots & \vdots & & \vdots \\ \frac{\partial f_l}{\partial t_1} & \frac{\partial f_l}{\partial t_2} & \dots & \frac{\partial f_l}{\partial t_m} \end{pmatrix} \begin{pmatrix} \frac{\partial g_1}{\partial x_1} & \dots & \frac{\partial g_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial g_m}{\partial x_1} & \dots & \frac{\partial g_m}{\partial x_n} \end{pmatrix} (\vec{g}(\vec{x}_0))$$

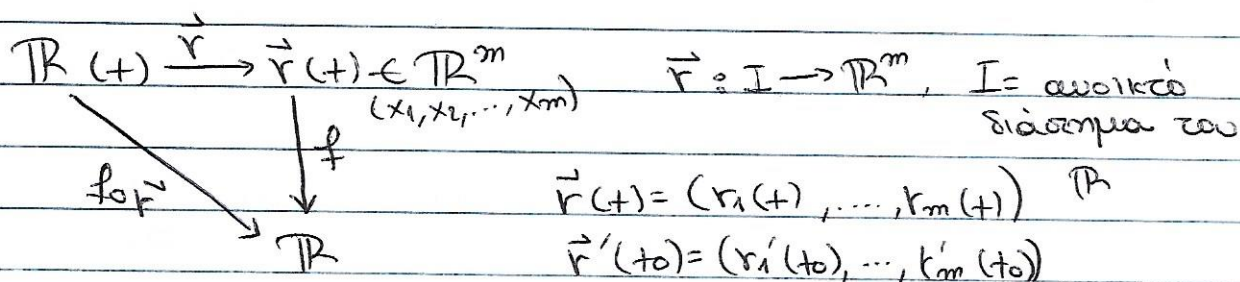
$$\frac{\partial h_1}{\partial x_1}(\vec{x}_0) = \frac{\partial f_1}{\partial t_1} \frac{\partial g_1}{\partial x_1} + \frac{\partial f_1}{\partial t_2} \frac{\partial g_2}{\partial x_1} + \dots + \frac{\partial f_1}{\partial t_m} \frac{\partial g_m}{\partial x_1} =$$

$$= \sum_{k=1}^m \frac{\partial f_1}{\partial t_k}(\vec{g}(\vec{x}_0)) \cdot \frac{\partial g_k}{\partial x_1}(\vec{x}_0)$$

Γενικά $\frac{\partial h_i}{\partial x_j}(\vec{x}_0) = \sum_{k=1}^m \frac{\partial f_k(\vec{g}(\vec{x}_0))}{\partial x_k} \cdot \frac{\partial g_k(\vec{x}_0)}{\partial x_j}, \quad i=1,2,\dots,l$
 $j=1,2,\dots,m$

Ειδική Περίπτωση!!

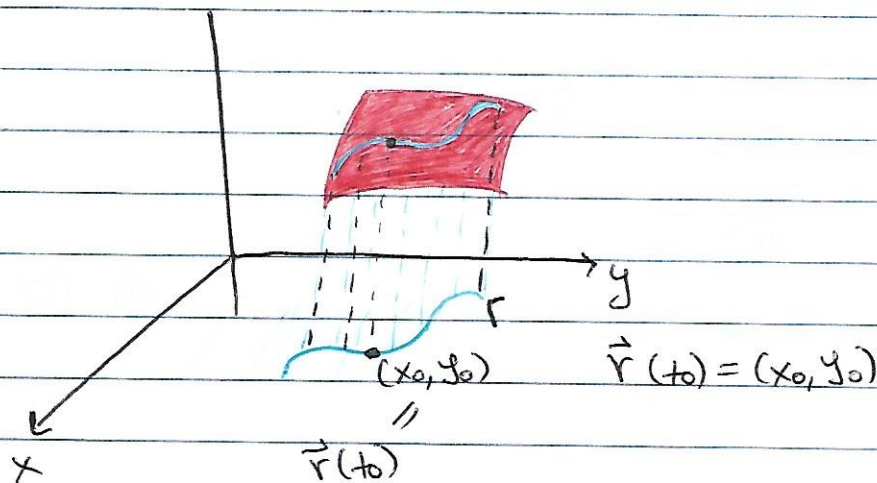
$m=1, \quad m \geq 2, \quad l=1$



$\nabla f(\vec{r}(t_0)) = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_m} \right) (\vec{r}(t_0))$

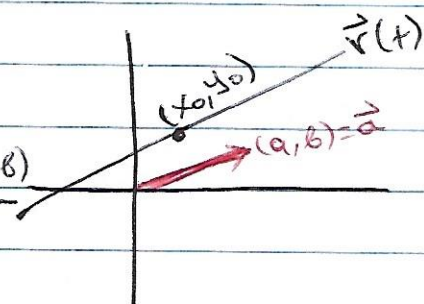
Τότε κανόνας Αλυσίδας δίνει:

$\frac{d(f \circ \vec{r})}{dt}(t_0) = \nabla f(\vec{r}(t_0)) \cdot \vec{r}'(t_0)$



• Για $\vec{r}(t) = (x_0, y_0) + t(a, b), \quad \|(a, b)\| = 1$

$\frac{d(f \circ \vec{r})}{dt} \Big|_{t=0} = \lim_{t \rightarrow 0} \frac{f(x_0 + ta, y_0 + tb) - f(x_0, y_0)}{t}$



$= D_{\vec{a}} f(x_0, y_0) = \nabla f(x_0, y_0) \cdot (a, b)$

ΑΣΚΗΣΕΙΣ

$$1) f(u, v) = (u+v, u \cdot v) \quad \begin{cases} f_1(u, v) = u+v \\ f_2(u, v) = u \cdot v \end{cases}$$

$$g(x, y) = (x^2 + y^2, x^3, x+y) \quad \begin{cases} g_1(x, y) = x^2 + y^2 \\ g_2(x, y) = x^3 \\ g_3(x, y) = x+y \end{cases}$$

$$\vec{h} = \vec{g} \circ \vec{f} \quad (= h_1, h_2, h_3)$$

$$\begin{array}{ccc} (u, v) & \xrightarrow{\vec{f}} & \mathbb{R}^2(x, y) \\ & \searrow & \downarrow \vec{g} \\ & & \mathbb{R}^3 \end{array}$$

\vec{h}

$$\text{Να υπολ. } \frac{\partial h_1}{\partial u}, \frac{\partial h_3}{\partial v}$$

κατ' ερώτησιν κατ' με τον Αλγόριθμο

Λύση

$$\begin{aligned} \vec{h}(u, v) &= \vec{g}(u+v, u \cdot v) = \\ &= ((u+v)^2 + u^2 v^2, (u+v)^3, (u+v) + uv) \end{aligned}$$

$$h_1(u, v) = (u+v)^2 + u^2 v^2$$

$$h_3(u, v) = u+v + uv$$

$$\frac{\partial h_1}{\partial u} = 2(u+v) + 2u \cdot v^2 \quad (1)$$

$$\frac{\partial h_3}{\partial v} = 1+u \quad (1)$$

Ισχύει (1), (2)

κατ' ερώτησιν Αλγόριθμο

$$\frac{\partial h_1}{\partial u} = \frac{\partial g_1}{\partial x} \cdot \frac{\partial f_1}{\partial u} + \frac{\partial g_1}{\partial y} \cdot \frac{\partial f_2}{\partial u}$$

$$= 2x \Big|_{(u+v, uv)} \cdot 1 + 2y \Big|_{(u+v, uv)} \cdot v = 2(u+v) + 2uv^2 \quad (2)$$

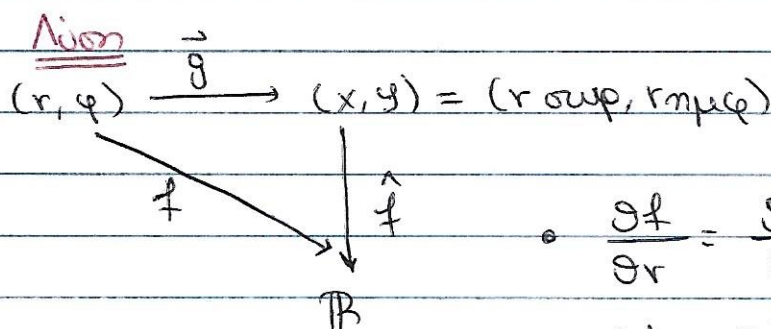
$$\begin{aligned} \circ \frac{\partial h_3}{\partial v} &= \frac{\partial g_3}{\partial x} \frac{\partial f_1}{\partial u} + \frac{\partial g_3}{\partial y} \frac{\partial f_2}{\partial v} = \\ &= 1 \cdot 1 + 1 \cdot u = 1 + u \quad (2') \end{aligned}$$

λοξίσε η λύσεις των (1'), (2')

|| *As gives εφέακμον σε Ασκήσεις με Επαλήθευση ||
 || τω κούρα της Αποδείας. ||

2) $\hat{f}: \mathbb{R}^2 \rightarrow \mathbb{R}$ διαφ. $\vec{g}(r, \varphi) = (r \cdot \sigma \omega \varphi, r \cdot \mu \mu \varphi)$
 $f = \hat{f} \circ \vec{g}$, $f(r, \varphi) = \hat{f}(r \cdot \sigma \omega \varphi, r \cdot \mu \mu \varphi)$

$$\text{ΝΔΟ } \|\nabla \hat{f}\|^2 = \left(\frac{\partial \hat{f}}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial \hat{f}}{\partial \varphi}\right)^2$$



$$\begin{aligned} \circ \frac{\partial f}{\partial r} &= \frac{\partial \hat{f}}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial \hat{f}}{\partial y} \frac{\partial y}{\partial r} \\ \frac{\partial f}{\partial r} &= \frac{\partial \hat{f}}{\partial x} \cdot (\sigma \omega \varphi) + \frac{\partial \hat{f}}{\partial y} \cdot (\mu \mu \varphi) \quad (1) \end{aligned}$$

$$\circ \frac{\partial f}{\partial \varphi} = \frac{\partial \hat{f}}{\partial x} \frac{\partial x}{\partial \varphi} + \frac{\partial \hat{f}}{\partial y} \frac{\partial y}{\partial \varphi} (=)$$

$$\frac{\partial f}{\partial \varphi} = \frac{\partial \hat{f}}{\partial x} \cdot (-r \cdot \mu \mu \varphi) + \frac{\partial \hat{f}}{\partial y} (r \cdot \sigma \omega \varphi) \quad (2)$$

$$\begin{aligned} \left(\frac{\partial f}{\partial r}\right)^2 + \frac{1}{r^2} \cdot \left(\frac{\partial f}{\partial \varphi}\right)^2 &= \left(\frac{\partial \hat{f}}{\partial x}\right)^2 (\sigma \omega^2 \varphi + \mu \mu^2 \varphi) + \left(\frac{\partial \hat{f}}{\partial y}\right)^2 (\mu \mu^2 \varphi + \sigma \omega^2 \varphi) = \\ &= \|\nabla \hat{f}\|^2 \end{aligned}$$

(Απόδειξη Συμμεταθετών: $\hat{f}(x, y) \equiv f(r \sigma \omega \varphi, r \mu \mu \varphi)$)

3) $a \cdot b \neq 0$ και $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$\mu \in \mathbb{R}$ $a \cdot f_x + b \cdot f_y = 0$ (*)

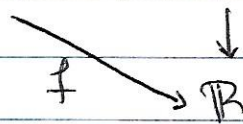
N.A.O. , $f(x,y) = g(bx-ay)$

(Υποδ. $u = bx - ay, v = bx + ay$)

$(x,y) \xrightarrow{g} (u = bx - ay, v = bx + ay)$

Μον

$f = \hat{g} \circ \hat{f}$



$\frac{\partial f}{\partial x} = \frac{\partial \hat{f}}{\partial u} \cdot \frac{\partial (bx-ay)}{\partial x} + \frac{\partial \hat{f}}{\partial v} \cdot \frac{\partial (bx+ay)}{\partial x}$

$= \frac{\partial \hat{f}}{\partial u} \cdot b + \frac{\partial \hat{f}}{\partial v} \cdot b$

$f_x = \frac{\partial \hat{f}}{\partial u} \cdot b + \frac{\partial \hat{f}}{\partial v} \cdot b$

(*)

$f_y = \frac{\partial \hat{f}}{\partial u} \cdot (-a) + \frac{\partial \hat{f}}{\partial v} \cdot a$

$0 = 2ab \frac{\partial \hat{f}}{\partial v}$

άρα $\frac{\partial \hat{f}}{\partial v} = 0, \forall u \in \mathbb{R}$

$\hat{f}(u,v) = g(u)$

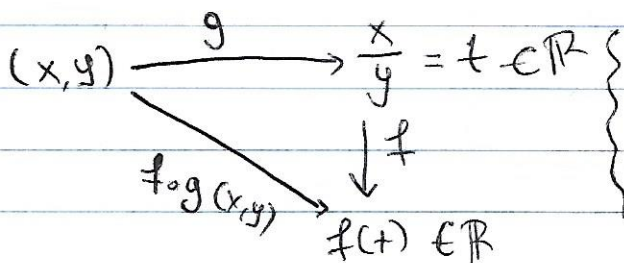
$f(x,y) = g(bx-ay)$

(Για $a=3, b=2, \text{ort. } 20, 2, 5$)

4) i) $z(x,y) = f(\frac{x}{y})$ NAO $\frac{\partial z}{\partial x} + y \cdot \frac{\partial z}{\partial y} = 0$

ii) $z(x,y) = f(\frac{x+y}{x-y})$ NAO $\frac{\partial z}{\partial x} + y \cdot \frac{\partial z}{\partial y} = 0$

i) Μον



Εκουμε ού



$f = f \circ g(x,y) \in \mathbb{R}$

$$\frac{\partial z}{\partial y} = f' \left(\frac{x}{y} \right) \cdot \left(\frac{1}{y} \right)$$

$$\frac{\partial z}{\partial y} = f' \left(\frac{x}{y} \right) \cdot \left(-\frac{1}{y^2} \right)$$

$$\underline{x \cdot 2x} + y \cdot 2y = \frac{x}{y} f' \left(\frac{x}{y} \right) + x \cdot \left(-\frac{1}{y^2} \right) \cdot f' \left(\frac{x}{y} \right) = 0$$

ii) Ανάλυση

5) $f: \mathbb{R}^n \setminus \{\vec{0}\} \rightarrow \mathbb{R}$, $f(t\vec{x}) = t^\alpha f(\vec{x})$
 $t > 0$, $\vec{x} \neq \vec{0}$ και $f = \text{διαφορίσιμη}$

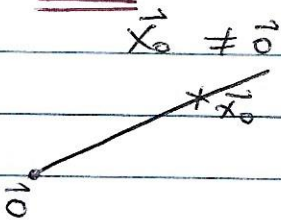
Η f καθεύεται α-τάξης ομογενούς

N. Δο. $\vec{x} \cdot \nabla f(\vec{x}) = \alpha \cdot f(\vec{x})$

Εξίσωση Euler

(π.χ. $m=2$, $(x \cdot \frac{\partial f}{\partial x} + y \cdot \frac{\partial f}{\partial y} = \alpha f)$)

Λύση



$$\vec{r}(t) = t \vec{x}_0 \rightarrow \begin{cases} \vec{r}(0) = \vec{0} \\ \vec{r}(1) = \vec{x}_0 \\ \vec{r}(t) = \vec{x}_0 \end{cases}$$

$g = f \circ \vec{r}$

① $\frac{d}{dt} (f \circ \vec{r})(t) = \nabla f(\vec{r}(t)) \cdot \vec{r}'(t)$

$g'(1) = \nabla f(\vec{x}_0) \cdot \vec{x}_0$

② $\frac{d}{dt} g(t) = \frac{d}{dt} (f(t\vec{x}_0)) = \frac{d}{dt} (t^\alpha f(\vec{x}_0)) =$
 $= \alpha \cdot t^{\alpha-1} \cdot f(\vec{x}_0)$

$g'(1) = \alpha \cdot f(\vec{x}_0)$ Άρα έχουμε ότι
 $\nabla f(\vec{x}) \cdot \vec{x} = \alpha \cdot f(\vec{x})$

1) ΟΡΙΣΜΟΙ μόνο κατά (αρχαία μαθηματικά)

2) ΑΣΚΗΣΕΙΣ

Σχόλια

i) Ισχύει και το αντίστροφο. Αν $\nabla f(\vec{x}) \cdot \vec{x} = a f(\vec{x})$
 $\Rightarrow f$ ομογενής α-τάξης

ii) Οι συναρτήσεις της ασκ. 4 είναι ομογενής
0-τάξης

$$f(tx, ty) = f\left(\frac{tx}{t}, \frac{ty}{t}\right) = f\left(\frac{x}{y}\right) = f(x, y)$$

$$f(tx, ty) = t^0 \cdot f(x, y)$$