

Prerequisites

Almost essential

Firm: Basics

The Firm: Optimisation

MICROECONOMICS

Principles and Analysis

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Overview...

*Approaches to
the firm's
optimisation
problem*

Firm: Optimisation

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graph TD; A[Firm: Optimisation] --- B[The setting]; A --- C[Stage 1: Cost Minimisation]; A --- D[Stage 2: Profit maximisation];
```

The setting

Stage 1: Cost
Minimisation

Stage 2: Profit
maximisation

The optimisation problem

- We want to set up and solve a standard optimisation problem.
- Let's make a quick list of its components.
- ... and look ahead to the way we will do it for the firm.

The optimisation problem

- Objectives ***-Profit maximisation?***
- Constraints ***-Technology; other***
- Method ***- 2-stage optimisation***

Construct the objective function

- Use the information on prices...

w_i

- price of input i

p

- price of output

- ...and on quantities...

z_i

- amount of input i

q

- amount of output

- ...to build the objective function



The firm's objective function

- Cost of inputs: $\sum_{i=1}^m w_i z_i$ • Summed over all m inputs

- Revenue: pq • Subtract Cost from Revenue to get

- Profits: $pq - \sum_{i=1}^m w_i z_i$

Optimisation: the standard approach

- Choose q and \mathbf{z} to maximise

$$\Pi := pq - \sum_{i=1}^m w_i z_i$$

- ...subject to the production constraint...

$$q \leq \phi(\mathbf{z})$$


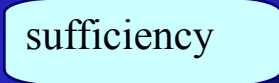
- Could also write this as $\mathbf{z} \in Z(q)$

- ..and some obvious constraints:

$$q \geq 0 \quad \mathbf{z} \geq \mathbf{0}$$

- You can't have negative output or negative inputs

A standard optimisation method

- If ϕ is differentiable...
- Set up a Lagrangean to take care of the constraints
- Write down the First Order Conditions (FOC) 
- Check out second-order conditions 
- Use FOC to characterise solution

$$L(\dots)$$

$$\frac{\partial}{\partial \mathbf{z}} L(\dots) = 0$$

$$\frac{\partial^2}{\partial \mathbf{z}^2} L(\dots)$$

$$\mathbf{z}^* = \dots$$

Uses of FOC

- First order conditions are crucial
- They are used over and over again in optimisation problems.
- For example:
 - Characterising efficiency.
 - Analysing “Black box” problems.
 - Describing the firm's reactions to its environment.
- More of that in the next presentation
- Right now a word of caution...

A word of warning

- We've just argued that using FOC is useful.
 - But sometimes it will yield ambiguous results.
 - Sometimes it is undefined.
 - Depends on the shape of the production function ϕ .
- You have to check whether it's appropriate to apply the Lagrangean method
- You may need to use other ways of finding an optimum.
- Examples coming up...

A way forward

- We could just go ahead and solve the maximisation problem
- But it makes sense to break it down into two stages
 - The analysis is a bit easier
 - You see how to apply optimisation techniques
 - It gives some important concepts that we can re-use later
- The first stage is “minimise cost for a given output level”
 - If you have fixed the output level $q...$
 - ...then profit max is equivalent to cost min.
- The second stage is “find the output level to maximise profits”
 - Follows the first stage naturally
 - Uses the results from the first stage.
- We deal with stage each in turn

Overview...

*A fundamental
multivariable
problem with a
brilliant solution*

Firm: Optimisation

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graph TD; A[Firm: Optimisation] --- B[The setting]; A --- C[Stage 1: Cost Minimisation]; A --- D[Stage 2: Profit maximisation];
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The setting

Stage 1: Cost
Minimisation

Stage 2: Profit
maximisation

Stage 1 optimisation

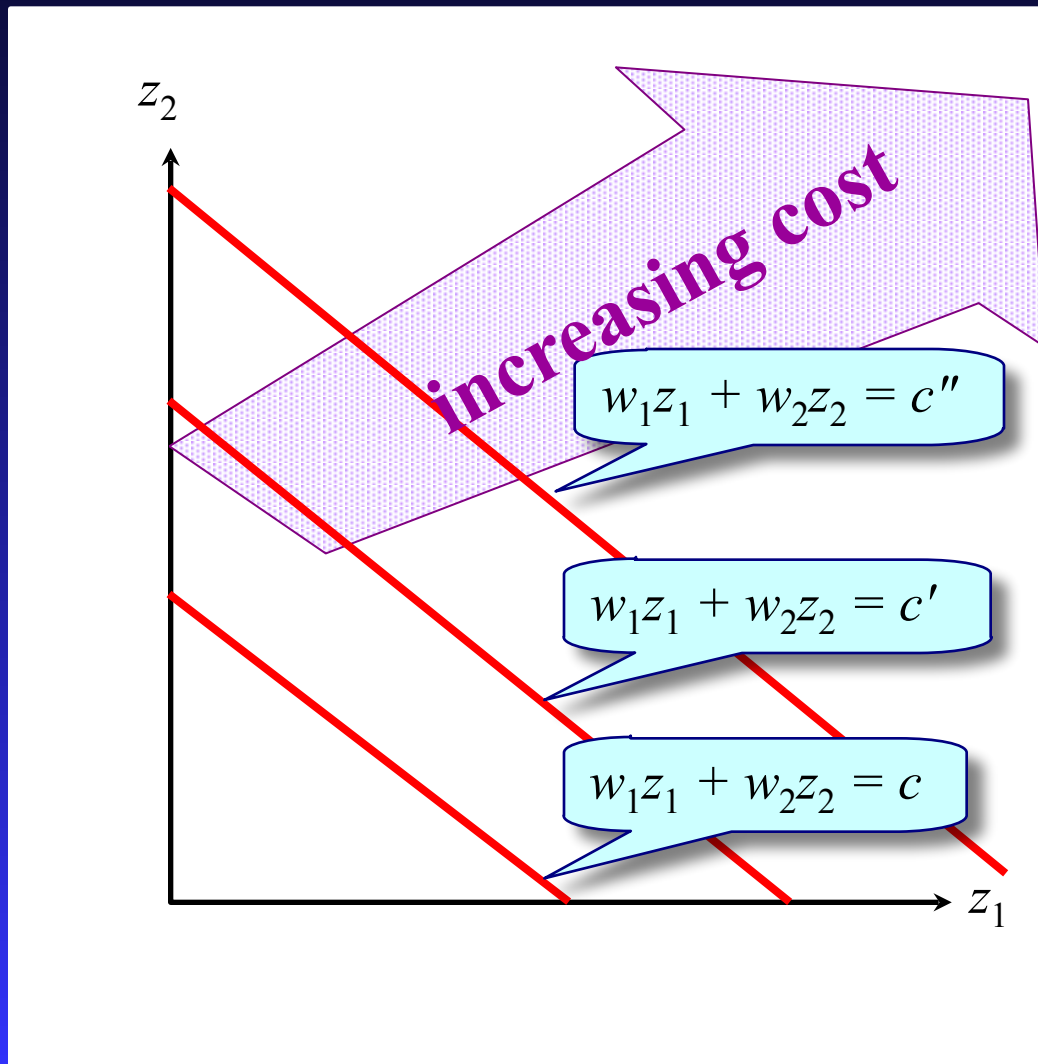
- Pick a target output level q
- Take as given the market prices of inputs w
- Maximise profits...
- ...by minimising costs

$$\sum_{i=1}^m w_i z_i$$

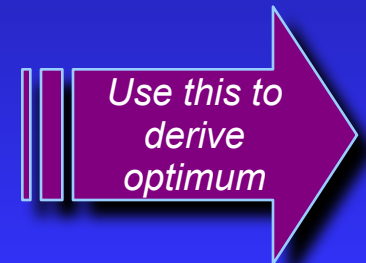
A useful tool

- For a given set of input prices w ...
- ...the *isocost* is the set of points z in input space...
- ...that yield a given level of factor cost.
- These form a hyperplane (straight line)...
- ...because of the simple expression for factor-cost structure.

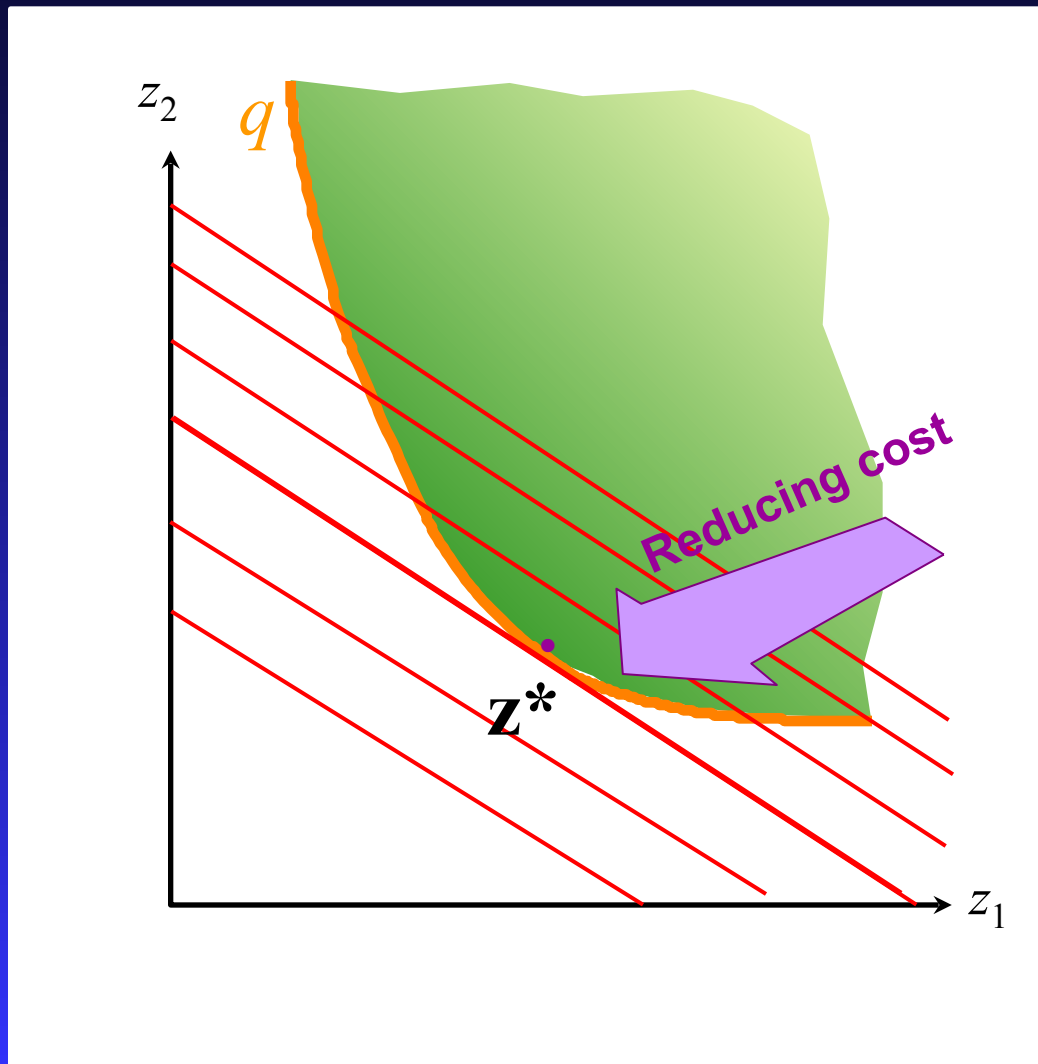
Iso-cost lines



- Draw set of points where cost of input is c , a constant
- Repeat for a higher value of the constant
- Imposes direction on the diagram...



Cost-minimisation



- The firm minimises cost...
- Subject to output constraint
- Defines the stage 1 problem.
- Solution to the problem

minimise

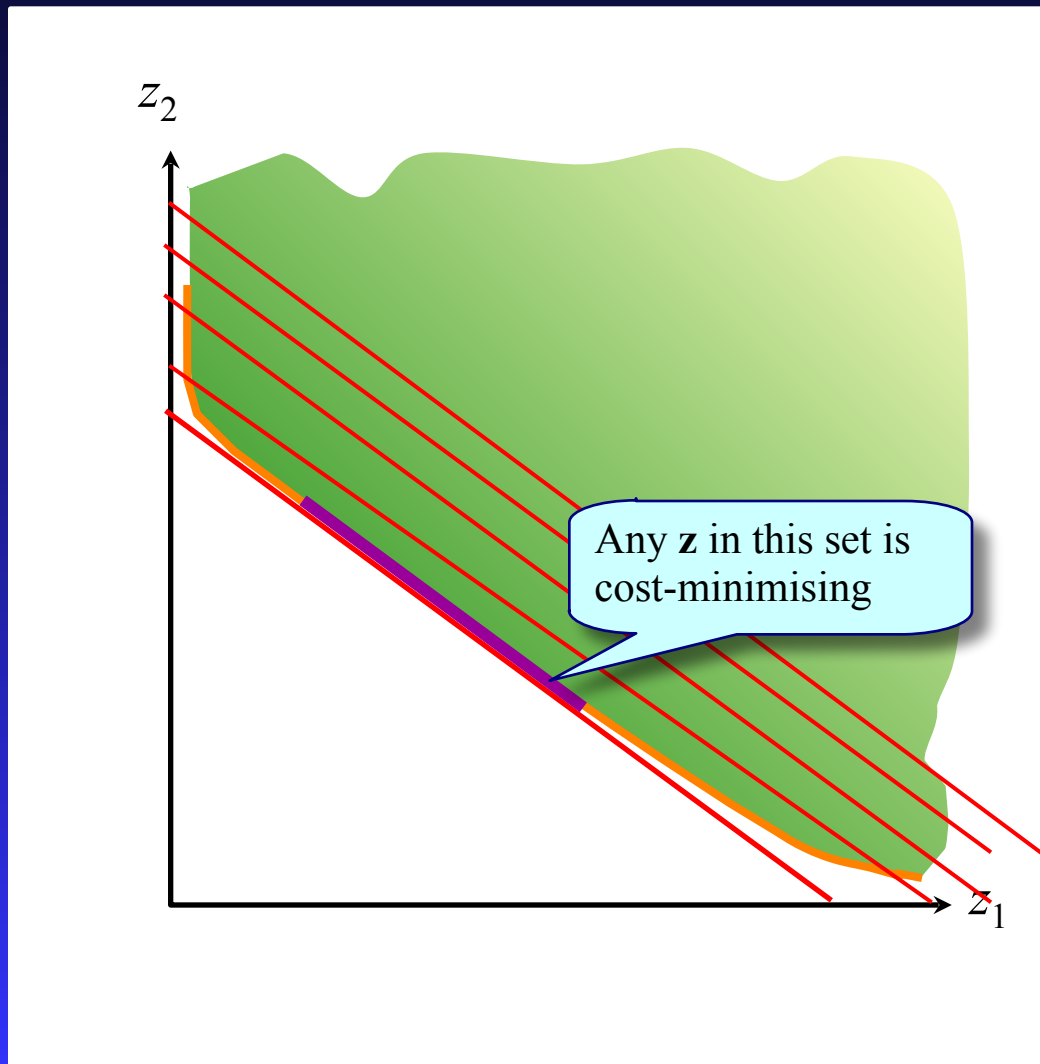
$$\sum_{i=1}^m w_i z_i$$

subject to $\phi(\mathbf{z}) \geq q$

- But the solution depends on the shape of the input-requirement set Z .

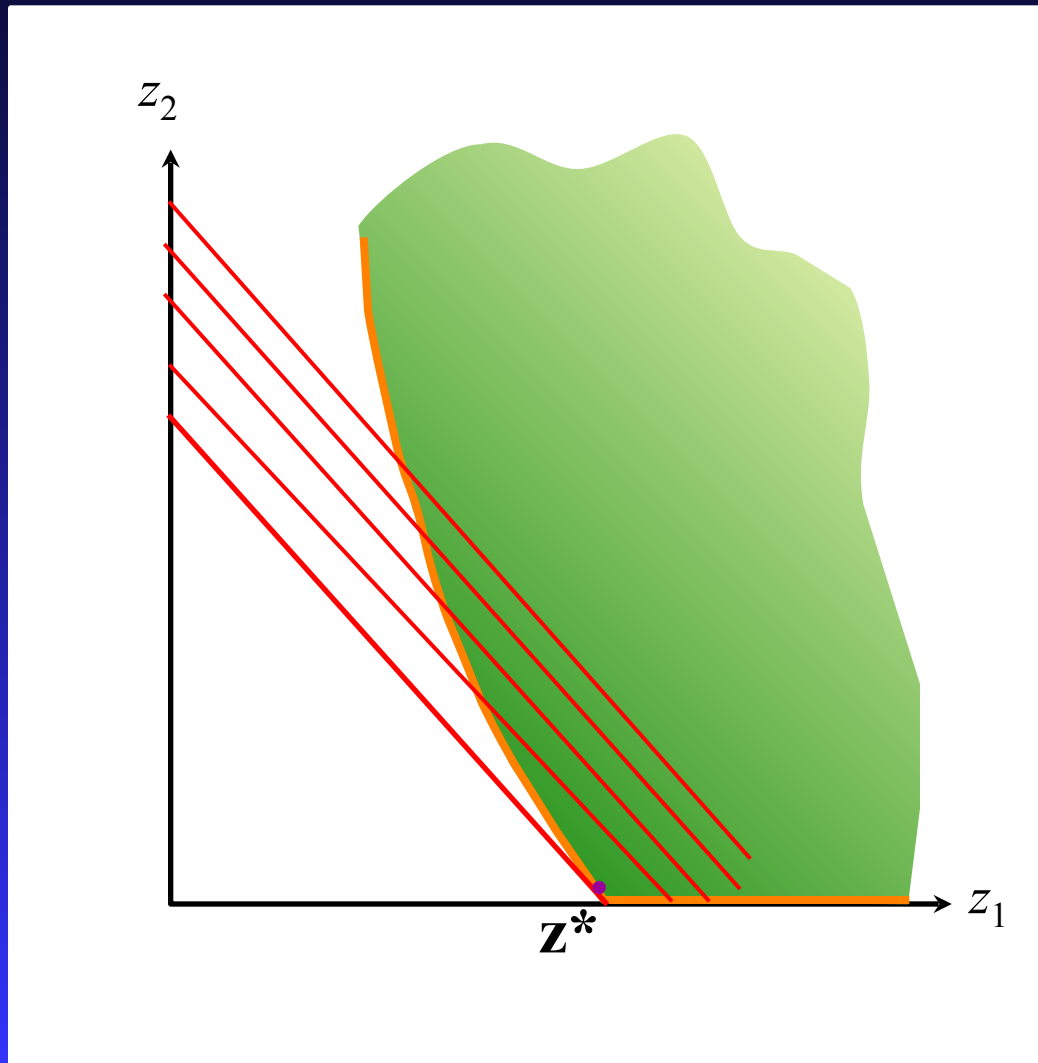
- What would happen in other cases?

Convex, but not strictly convex Z



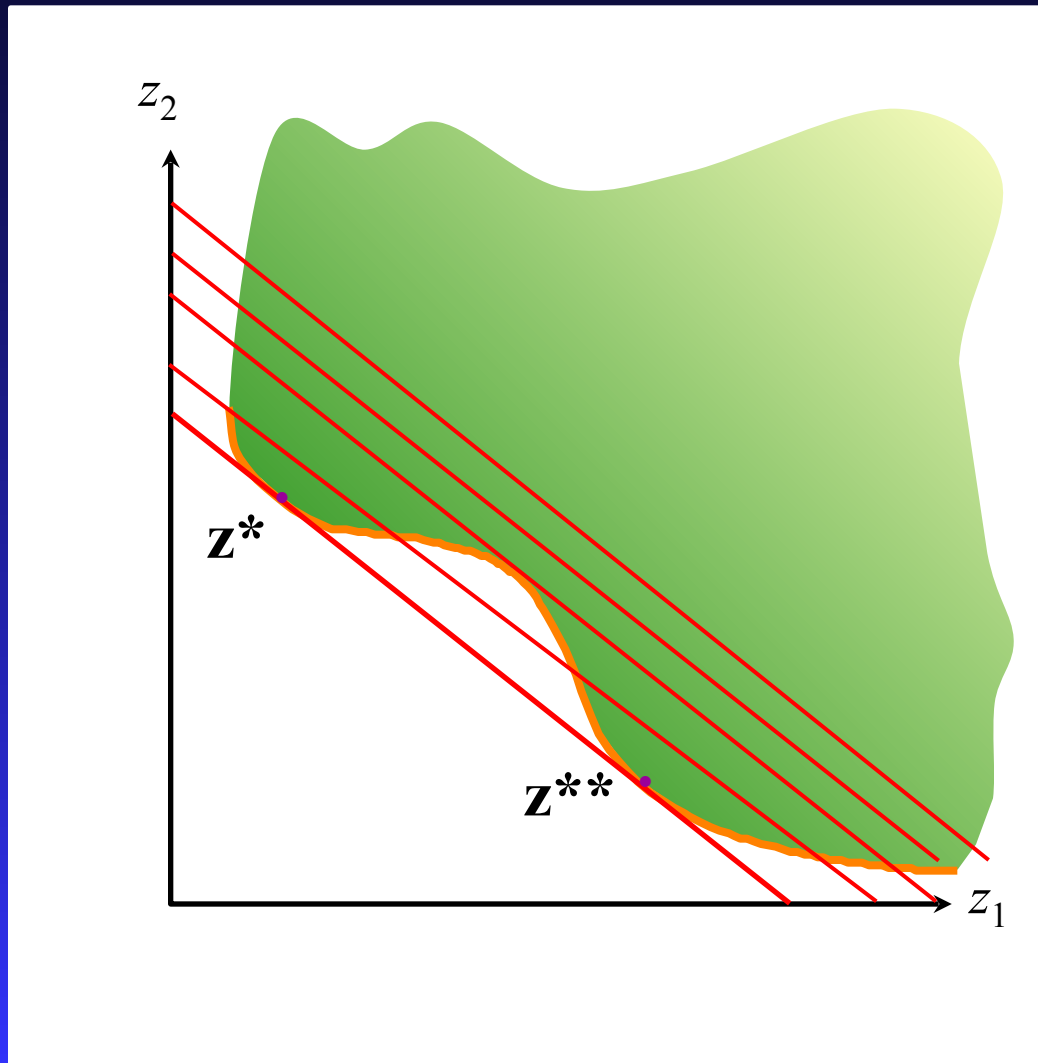
- An interval of solutions

Convex Z, touching axis



- Here $MRTS_{21} > w_1 / w_2$ at the solution.
- Input 2 is “too expensive” and so isn’t used: $z_2^* = 0$.

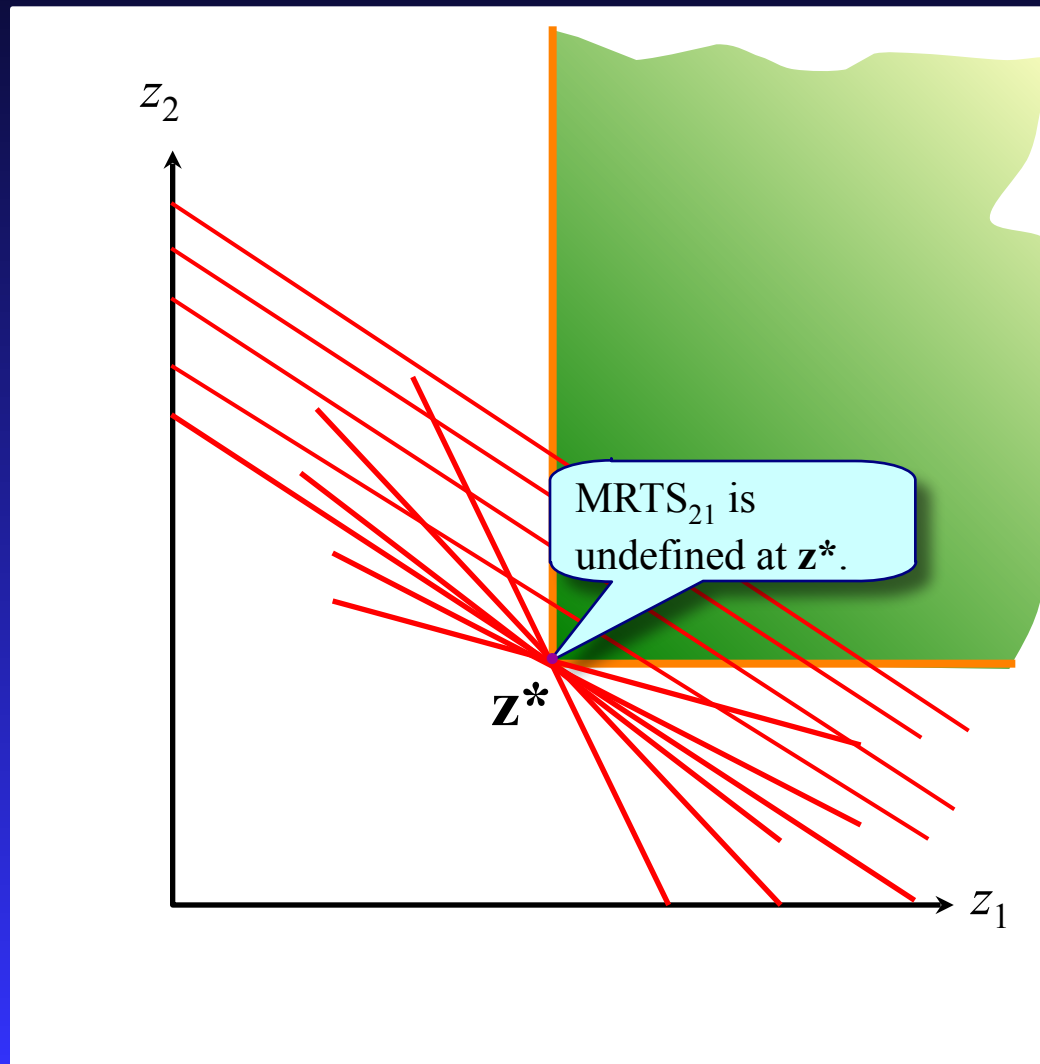
Non-convex Z



- *There could be multiple solutions.*

- *But note that there's no solution point between z^* and z^{**} .*

Non-smooth Z



- z^* is unique cost-minimising point for q .
- True for all positive finite values of w_1, w_2

Cost-minimisation: strictly convex Z

- Minimise
 m

$$\sum_{i=1}^m w_i z_i + \lambda[q - \phi(\mathbf{z})]$$

Lagrange multiplier

- Because of strict convexity we have an interior solution.
- A set of $m+1$ First-Order Conditions

$$\lambda^* \phi_1(\mathbf{z}^*) = w_1$$

$$\lambda^* \phi_2(\mathbf{z}^*) = w_2$$

...

$$\lambda^* \phi_m(\mathbf{z}^*) = w_m$$

$$q = \phi(\mathbf{z}^*)$$

one for each input

output constraint

- Use the objective function
- ...and output constraint
- ...to build the Lagrangean
- Differentiate w.r.t. z_1, \dots, z_m and set equal to 0.
- ... and w.r.t. λ
- Denote cost minimising values with a $*$.

If isoquants can touch the axes...

- Minimise

$$\sum_{i=1}^m w_i z_i + \lambda[q - \phi(\mathbf{z})]$$

- Now there is the possibility of corner solutions.
- A set of $m+1$ First-Order Conditions

$$\lambda^* \phi_1(\mathbf{z}^*) \leq w_1$$

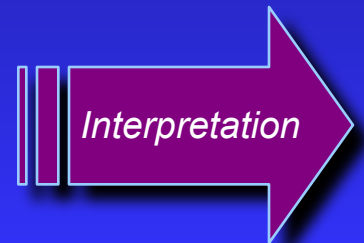
$$\lambda^* \phi_2(\mathbf{z}^*) \leq w_2$$

... ..

$$\lambda^* \phi_m(\mathbf{z}^*) \leq w_m$$

$$q = \phi(\mathbf{z}^*)$$

Can get “<” if optimal value of this input is 0



From the FOC

- If both inputs i and j are used and MRTS is defined then...

$$\frac{\phi_i(\mathbf{z}^*)}{\phi_j(\mathbf{z}^*)} = \frac{w_i}{w_j}$$

- MRTS = input price ratio

- “implicit” price = market price

- If input i could be zero then...

$$\frac{\phi_i(\mathbf{z}^*)}{\phi_j(\mathbf{z}^*)} \leq \frac{w_i}{w_j}$$

- MRTS _{ji} ≤ input price ratio

- “implicit” price ≤ market price



The solution...

- Solving the FOC, you get a cost-minimising value for each input...

$$z_i^* = H^i(\mathbf{w}, q)$$

- ...for the Lagrange multiplier

$$\lambda^* = \lambda^*(\mathbf{w}, q)$$

- ...and for the minimised value of cost itself.
- The *cost function* is defined as

$$C(\mathbf{w}, q) := \min_{\{\phi(\mathbf{z}) \geq q\}} \sum w_i z_i$$

vector of
input prices

Specified
output level

Interpreting the Lagrange multiplier

- The solution function:

$$C(\mathbf{w}, q) = \sum_i w_i z_i^*$$

$$= \sum_i w_i z_i^* - \lambda^* [\phi(\mathbf{z}^*) - q]$$

At the optimum, either the constraint binds or the Lagrange multiplier is zero

- Differentiate with respect to q :

$$C_q(\mathbf{w}, q) = \sum_i w_i H_q^i(\mathbf{w}, q)$$

Express demands in terms of (\mathbf{w}, q)

$$- \lambda^* \left[\sum_i \phi_i(\mathbf{z}^*) H_q^i(\mathbf{w}, q) \right]$$

Vanishes because of FOC $\lambda^* \phi_i(\mathbf{z}^*) = w_i$

- Rearrange:

$$C_q(\mathbf{w}, q) = \sum_i [w_i - \lambda^* \phi_i(\mathbf{z}^*)] H_q^i(\mathbf{w}, q) + \lambda^*$$

Lagrange multiplier in the stage 1 problem is just marginal cost

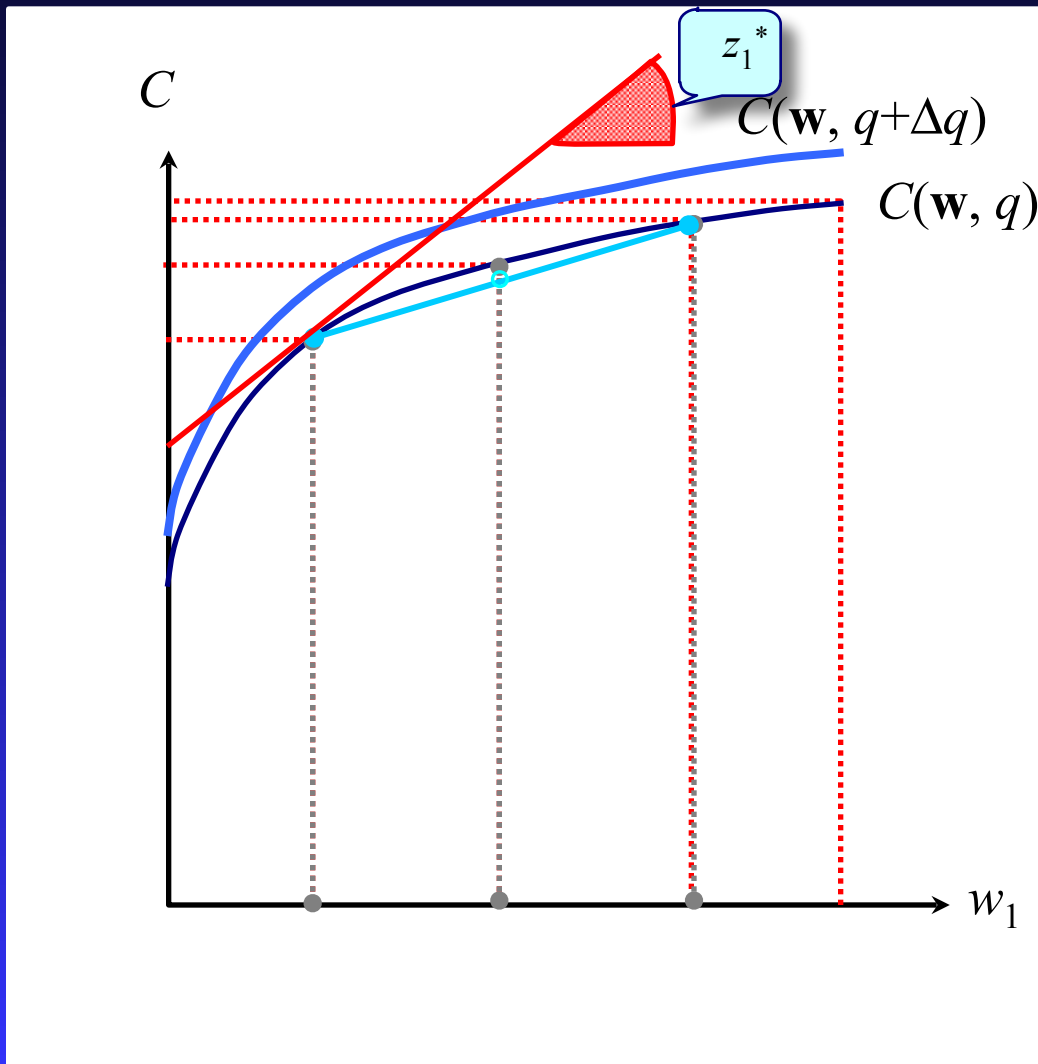
$$C_q(\mathbf{w}, q) = \lambda^*$$

This result – extremely important in economics – is just an applications of a general “envelope” theorem.

The cost function is an amazingly useful concept

- Because it is a solution function...
- ...it automatically has very nice properties.
- These are true for *all* production functions.
- And they carry over to applications other than the firm.
- We'll investigate these graphically.

Properties of C

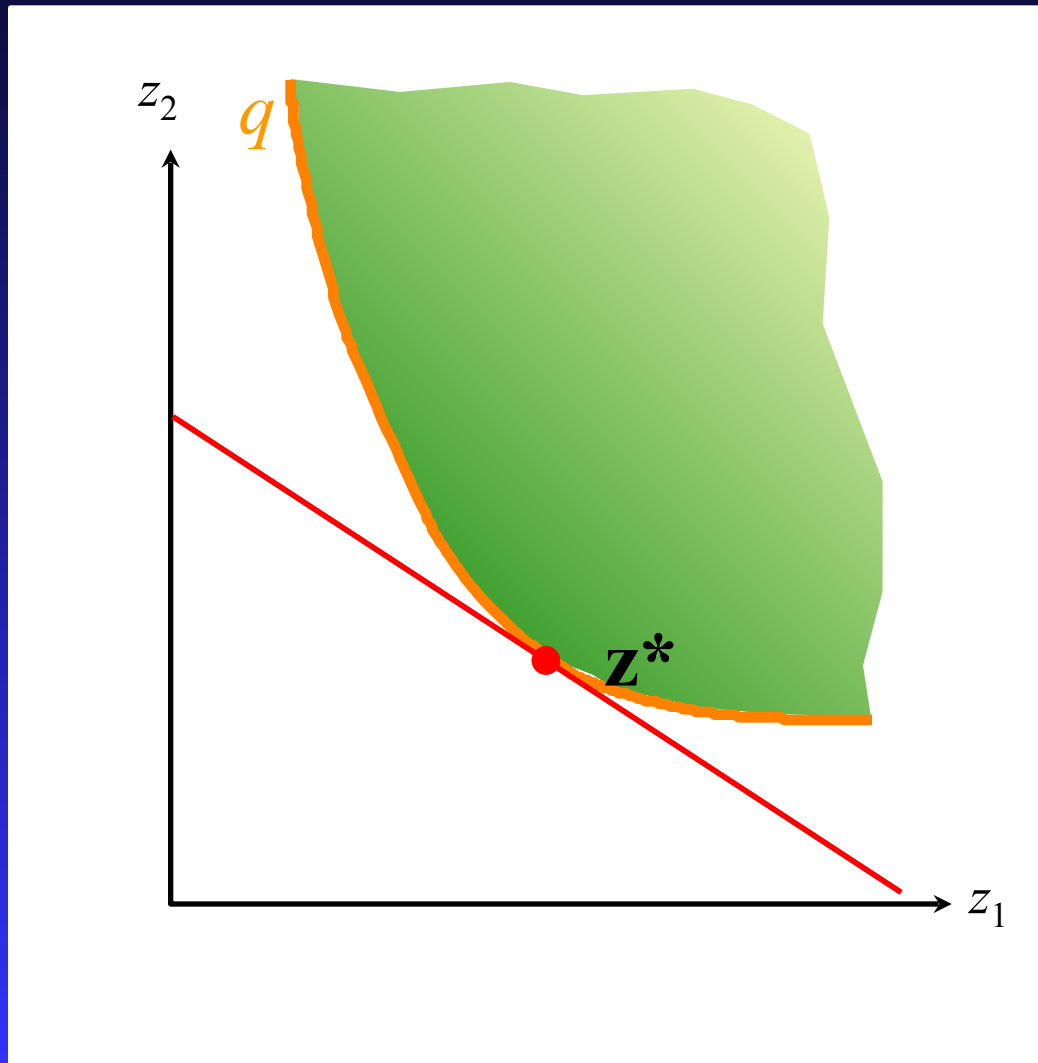


- Draw cost as function of w_1
- Cost is non-decreasing in input prices .
- Cost is increasing in output.
- Cost is concave in input prices.
- Shephard's Lemma

$$C(t\mathbf{w} + [1-t]\mathbf{w}', q) \geq tC(\mathbf{w}, q) + [1-t]C(\mathbf{w}', q)$$

$$\frac{\partial C(\mathbf{w}, q)}{\partial w_j} = z_j^*$$

What happens to cost if w changes to tw



- Find cost-minimising inputs for w , given q
- Find cost-minimising inputs for tw , given q

• So we have:

$$C(tw, q) = \sum_i t w_i z_i^* = t$$

$$\sum_i w_i z_i^* = C(w, q)$$

• The cost function is homogeneous of degree 1 in prices.

Cost Function: 5 things to remember

- Non-decreasing in every input price.
 - Increasing in at least one input price.
- Increasing in output.
- Concave in prices.
- Homogeneous of degree 1 in prices.
- Shephard's Lemma.

Example

Production function: $q \leq z_1^{0.1} z_2^{0.4}$

Equivalent form: $\log q \leq 0.1 \log z_1 + 0.4 \log z_2$

Lagrangian: $w_1 z_1 + w_2 z_2 + \lambda [\log q - 0.1 \log z_1 - 0.4 \log z_2]$

FOCs for an interior solution:

$$w_1 - 0.1 \lambda / z_1 = 0$$

$$w_2 - 0.4 \lambda / z_2 = 0$$

$$\log q = 0.1 \log z_1 + 0.4 \log z_2$$

From the FOCs:

$$\log q = 0.1 \log (0.1 \lambda / w_1) + 0.4 \log (0.4 \lambda / w_2)$$

$$\lambda = 0.1^{-0.2} 0.4^{-0.8} w_1^{0.2} w_2^{0.8} q^2$$

Therefore, from this and the FOCs:

$$w_1 z_1 + w_2 z_2 = 0.5 \lambda = 1.649 w_1^{0.2} w_2^{0.8} q^2$$

Overview...

*...using the
results of stage 1*

Firm: Optimisation

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graph TD; A[Firm: Optimisation] --- B[The setting]; A --- C[Stage 1: Cost Minimisation]; A --- D[Stage 2: Profit maximisation]; style D stroke:#ffff00,stroke-width:2px
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The setting

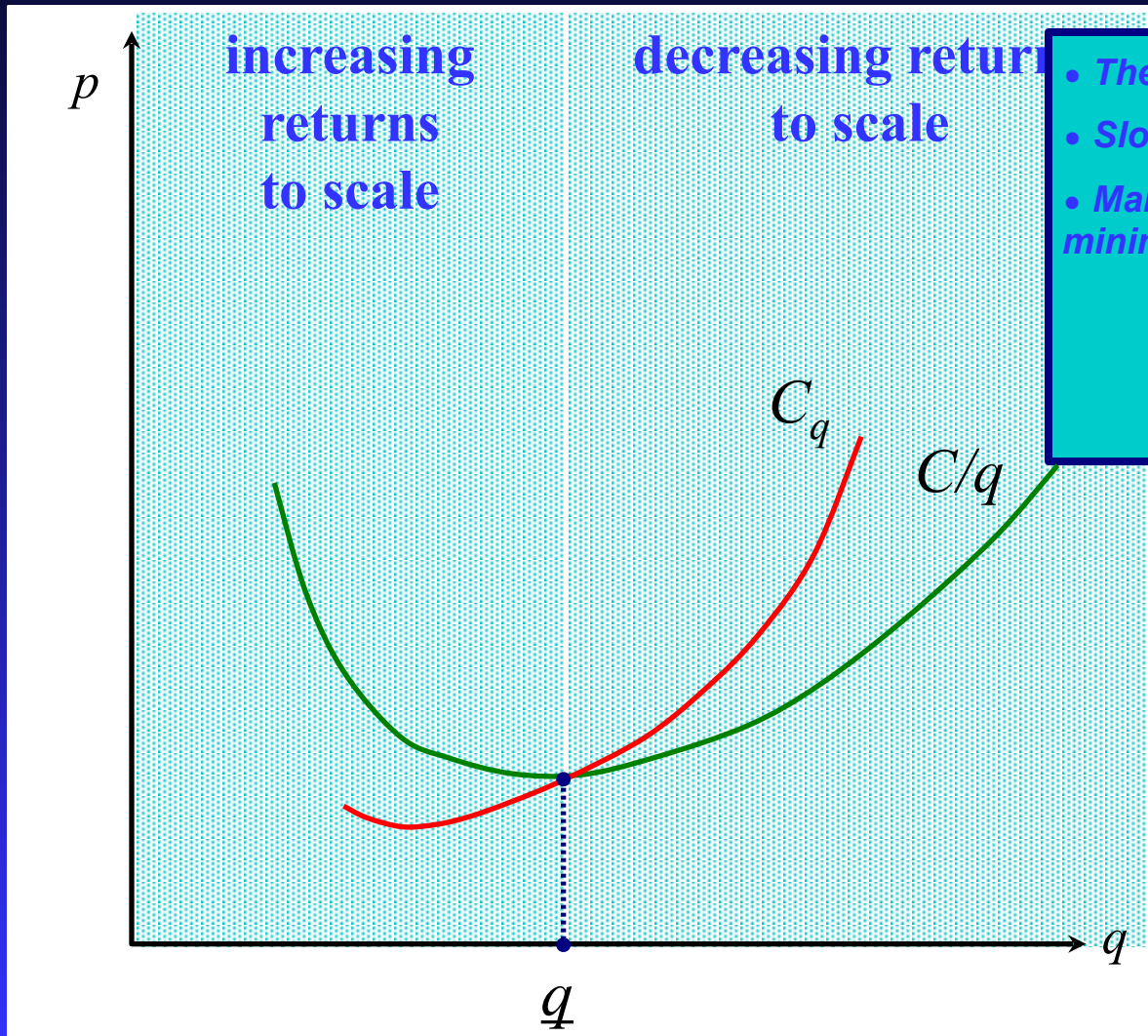
Stage 1: Cost
Minimisation

Stage 2: Profit
maximisation

Stage 2 optimisation

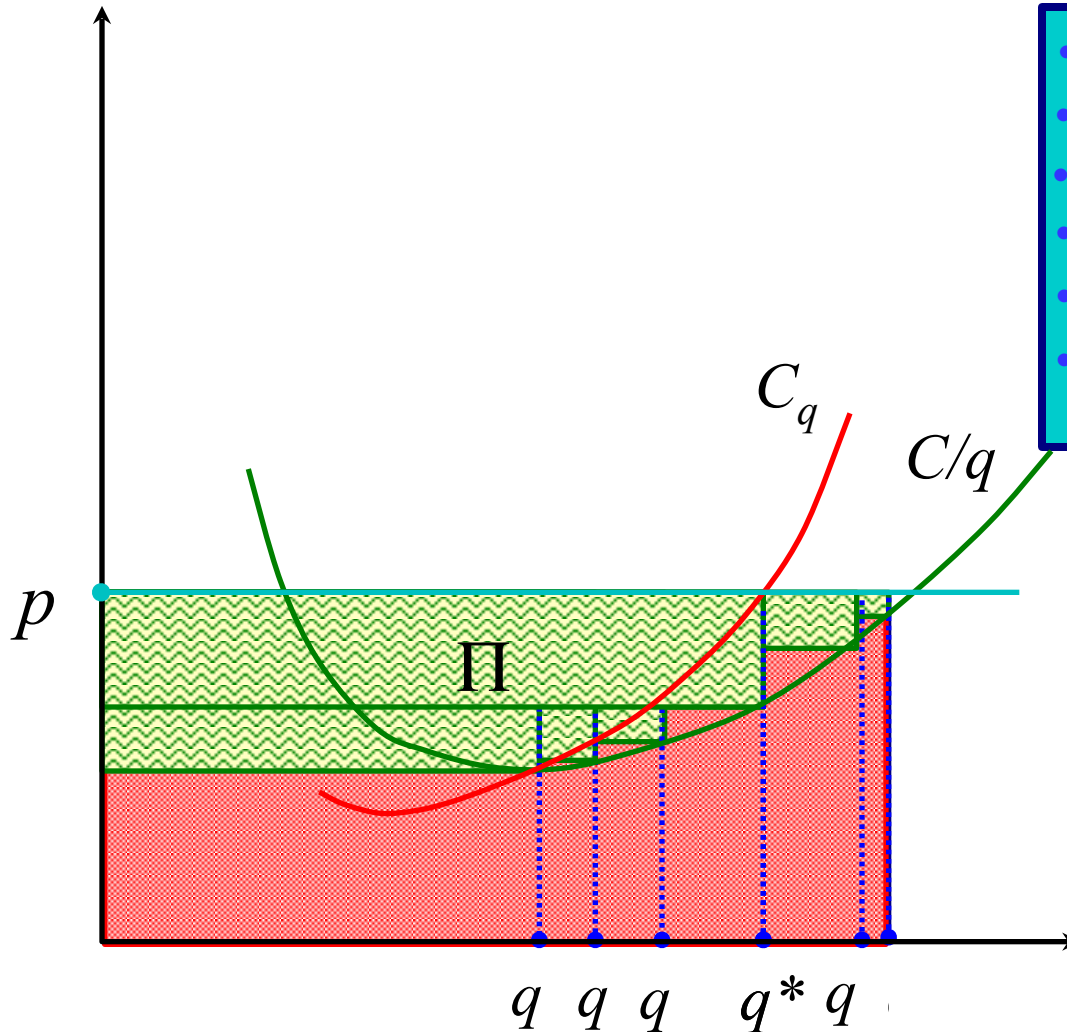
- Take the cost-minimisation problem as solved.
- Take output price p as given.
 - Use minimised costs $C(\mathbf{w}, q)$.
 - Set up a 1-variable maximisation problem.
- Choose q to maximise profits.
- First analyse the components of the solution graphically.
 - Tie-in with properties of the firm introduced in the previous presentation.
- Then we come back to the formal solution.

Average and marginal cost



- The average cost curve.
- Slope of AC depends on RTS.
- Marginal cost cuts AC at its minimum

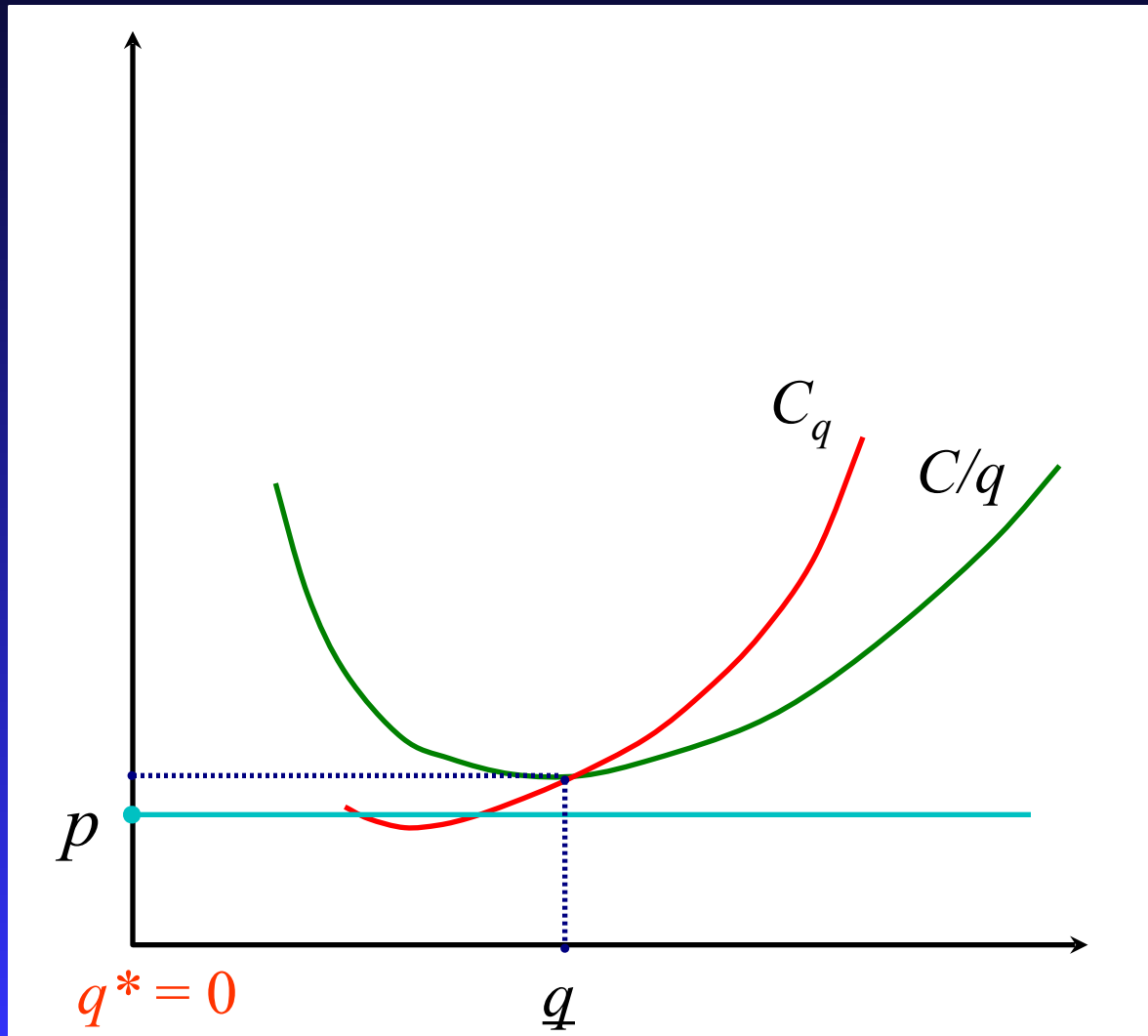
Revenue and profits



- A given market price p .
- Revenue if output is q .
- Cost if output is q .
- Profits if output is q .
- Profits vary with q .
- Maximum profits

• price =
marginal cost

What happens if price is low...



- price < marginal cost

Profit maximisation

- Objective is to choose q to max:

$$pq - C(\mathbf{w}, q)$$

“Revenue minus minimised cost”

- From the First-Order Conditions if $q^* > 0$:

$$p = C_q(\mathbf{w}, q^*)$$

“Price equals marginal cost”

$$p \geq \frac{C(\mathbf{w}, q^*)}{q^*}$$

“Price covers average cost”

- In general:

$$p \leq C_q(\mathbf{w}, q^*)$$

*covers both the cases:
 $q^* > 0$ and $q^* = 0$*

$$pq^* \geq C(\mathbf{w}, q^*)$$

Example (continued)

Production function: $q \leq z_1^{0.1} z_2^{0.4}$

Resulting cost function: $C(\mathbf{w}, q) = 1.649 w_1^{0.2} w_2^{0.8} q^2$

Profits:

$$pq - C(\mathbf{w}, q) = pq - A q^2$$

$$\text{where } A := 1.649 w_1^{0.2} w_2^{0.8}$$

FOC:

$$p - 2 A q = 0$$

Result:

$$q = p / 2A.$$

$$= 0.3031 w_1^{-0.2} w_2^{-0.8} p$$

Summary

- *Key point:* Profit maximisation can be viewed in two stages:

Review

- Stage 1: choose inputs to minimise cost

Review

- Stage 2: choose output to maximise profit

- *What next?* Use these to predict firm's reactions