

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0, \quad \rho \frac{d\mathbf{u}}{dt} = -\nabla P + \rho \nu \nabla^2 \mathbf{u} + \rho \frac{\nu + 3\nu_\tau}{3} \nabla (\nabla \cdot \mathbf{u}) + \rho \mathbf{g} + \delta \mathbf{E} + \frac{\mathbf{J} \times \mathbf{B}}{c}, \quad \mathbf{g} = -\nabla \Phi_g, \quad \nabla \cdot \mathbf{g} = -4\pi G \rho,$$

$$\frac{de}{dt} + P \frac{d}{dt} \left(\frac{1}{\rho} \right) = \frac{\rho q + \nabla \cdot (\kappa \nabla T) + \boldsymbol{\sigma}' : \mathbf{S} + J^2 / \sigma_E}{\rho}, \quad e = \frac{1}{\gamma - 1} \frac{P}{\rho}, \quad \boldsymbol{\sigma}' = 2\rho \nu \mathbf{S} + \rho \frac{3\nu_\tau - 2\nu}{3} (\nabla \cdot \mathbf{u}) \mathbf{I}, \quad S_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right),$$

$$\nabla \cdot \mathbf{E} = 4\pi \delta, \quad \nabla \cdot \mathbf{B} = 0, \quad \nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t}, \quad \nabla \times \mathbf{B} = \frac{4\pi}{c} \mathbf{J} + \frac{1}{c} \frac{\partial \mathbf{E}}{\partial t}, \quad \frac{\mathbf{J}}{\sigma_E} = \mathbf{E} + \frac{\mathbf{u} \times \mathbf{B}}{c},$$

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla, \quad \nabla \left(\frac{u^2}{2} \right) + (\nabla \times \mathbf{u}) \times \mathbf{u} = (\mathbf{u} \cdot \nabla) \mathbf{u} = u \frac{\partial \mathbf{u}}{\partial \ell} \hat{\ell} + \frac{u^2}{\mathcal{R}} \hat{n}, \quad (\nabla \times \mathbf{u}) \times \mathbf{u} = -\nabla_\perp \left(\frac{u^2}{2} \right) + \frac{u^2}{\mathcal{R}} \hat{n},$$

$$\frac{\partial}{\partial t} (\rho \mathbf{u}) + \nabla \cdot \boldsymbol{\Pi}^{\text{matter}} = \rho \mathbf{g} + \delta \mathbf{E} + \frac{\mathbf{J} \times \mathbf{B}}{c}, \quad \Pi_{ij}^{\text{matter}} = \rho u_i u_j + P \delta_{ij} - \sigma'_{ij},$$

$$\frac{\partial}{\partial t} \left(\frac{\mathbf{E} \times \mathbf{B}}{4\pi c} \right) + \nabla \cdot \boldsymbol{\Pi}^{\text{field}} = - \left(\delta \mathbf{E} + \frac{\mathbf{J} \times \mathbf{B}}{c} \right), \quad \Pi_{ij}^{\text{field}} = -\frac{E_i E_j + B_i B_j}{4\pi} + \frac{E^2 + B^2}{8\pi} \delta_{ij},$$

$$\frac{\partial}{\partial t} \left(\frac{\rho u^2}{2} + \rho e \right) + \nabla \cdot \left(\frac{\rho u^2}{2} \mathbf{u} + \rho e \mathbf{u} + P \mathbf{u} - \boldsymbol{\sigma}' \cdot \mathbf{u} - \kappa \nabla T \right) = \rho q + \rho \mathbf{g} \cdot \mathbf{u} + \mathbf{J} \cdot \mathbf{E}, \quad \frac{\partial}{\partial t} \left(\frac{E^2 + B^2}{8\pi} \right) + \nabla \cdot \left(\frac{c}{4\pi} \mathbf{E} \times \mathbf{B} \right) = -\mathbf{J} \cdot \mathbf{E}.$$

$$\text{Καρτεσιανές: } d\mathbf{r} = dx\hat{x} + dy\hat{y} + dz\hat{z}, \quad \nabla f = \frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z}, \quad \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2},$$

$$\nabla \times \mathbf{u} = \left(\frac{\partial u_z}{\partial y} - \frac{\partial u_y}{\partial z} \right) \hat{x} + \left(\frac{\partial u_x}{\partial z} - \frac{\partial u_z}{\partial x} \right) \hat{y} + \left(\frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \right) \hat{z}, \quad \nabla \cdot \mathbf{u} = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}, \quad \nabla^2 \mathbf{u} = \nabla^2 u_x \hat{x} + \nabla^2 u_y \hat{y} + \nabla^2 u_z \hat{z},$$

$$(\mathbf{u} \cdot \nabla) \mathbf{B} = \mathbf{u} \cdot \nabla B_x \hat{x} + \mathbf{u} \cdot \nabla B_y \hat{y} + \mathbf{u} \cdot \nabla B_z \hat{z}.$$

$$\text{Κυλινδρικές (} x = \varpi \cos \phi, \quad y = \varpi \sin \phi, \quad \hat{x} = \hat{\varpi} \cos \phi - \hat{\phi} \sin \phi, \quad \hat{y} = \hat{\varpi} \sin \phi + \hat{\phi} \cos \phi \text{): } d\mathbf{r} = d\varpi \hat{\varpi} + \varpi d\phi \hat{\phi} + dz \hat{z},$$

$$\nabla f = \frac{\partial f}{\partial \varpi} \hat{\varpi} + \frac{1}{\varpi} \frac{\partial f}{\partial \phi} \hat{\phi} + \frac{\partial f}{\partial z} \hat{z}, \quad \nabla^2 f = \frac{1}{\varpi} \frac{\partial}{\partial \varpi} \left(\varpi \frac{\partial f}{\partial \varpi} \right) + \frac{1}{\varpi^2} \frac{\partial^2 f}{\partial \phi^2} + \frac{\partial^2 f}{\partial z^2},$$

$$\nabla \times \mathbf{u} = \left(\frac{1}{\varpi} \frac{\partial u_z}{\partial \phi} - \frac{\partial u_\phi}{\partial z} \right) \hat{\varpi} + \left(\frac{\partial u_\varpi}{\partial z} - \frac{\partial u_z}{\partial \varpi} \right) \hat{\phi} + \frac{1}{\varpi} \left[\frac{\partial (\varpi u_\phi)}{\partial \varpi} - \frac{\partial u_\varpi}{\partial \phi} \right] \hat{z}, \quad \nabla \cdot \mathbf{u} = \frac{1}{\varpi} \frac{\partial (\varpi u_\varpi)}{\partial \varpi} + \frac{1}{\varpi} \frac{\partial u_\phi}{\partial \phi} + \frac{\partial u_z}{\partial z},$$

$$\nabla^2 \mathbf{u} = \left(\nabla^2 u_\varpi - \frac{u_\varpi}{\varpi^2} - \frac{2}{\varpi^2} \frac{\partial u_\phi}{\partial \phi} \right) \hat{\varpi} + \left(\nabla^2 u_\phi + \frac{2}{\varpi^2} \frac{\partial u_\varpi}{\partial \phi} - \frac{u_\phi}{\varpi^2} \right) \hat{\phi} + \nabla^2 u_z \hat{z},$$

$$(\mathbf{u} \cdot \nabla) \mathbf{B} = \left(u_\varpi \frac{\partial B_\varpi}{\partial \varpi} + \frac{u_\phi}{\varpi} \frac{\partial B_\varpi}{\partial \phi} + u_z \frac{\partial B_\varpi}{\partial z} - \frac{u_\phi B_\phi}{\varpi} \right) \hat{\varpi} + \left(u_\varpi \frac{\partial B_\phi}{\partial \varpi} + \frac{u_\phi}{\varpi} \frac{\partial B_\phi}{\partial \phi} + u_z \frac{\partial B_\phi}{\partial z} + \frac{u_\phi B_\varpi}{\varpi} \right) \hat{\phi} + \left(u_\varpi \frac{\partial B_z}{\partial \varpi} + \frac{u_\phi}{\varpi} \frac{\partial B_z}{\partial \phi} + u_z \frac{\partial B_z}{\partial z} \right) \hat{z},$$

$$S_{\varpi\varpi} = \frac{\partial u_\varpi}{\partial \varpi}, \quad S_{\varpi\phi} = S_{\phi\varpi} = \frac{1}{2\varpi} \left[\frac{\partial u_\varpi}{\partial \phi} + \varpi^2 \frac{\partial}{\partial \varpi} \left(\frac{u_\phi}{\varpi} \right) \right], \quad S_{\varpi z} = S_{z\varpi} = \frac{1}{2} \left(\frac{\partial u_\varpi}{\partial z} + \frac{\partial u_z}{\partial \varpi} \right),$$

$$S_{\phi\phi} = \frac{1}{\varpi} \left(u_\varpi + \frac{\partial u_\phi}{\partial \phi} \right), \quad S_{\phi z} = S_{z\phi} = \frac{1}{2} \left(\frac{\partial u_\phi}{\partial z} + \frac{1}{\varpi} \frac{\partial u_z}{\partial \phi} \right), \quad S_{zz} = \frac{\partial u_z}{\partial z}.$$

$$\text{Σφαιρικές (} x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta, \quad \hat{x} = \hat{r} \cos \theta - \hat{\theta} \sin \theta \text{): } d\mathbf{r} = dr \hat{r} + r d\theta \hat{\theta} + r \sin \theta d\phi \hat{\phi},$$

$$\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \hat{\phi}, \quad \nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2},$$

$$\nabla \times \mathbf{u} = \frac{1}{r \sin \theta} \left[\frac{\partial (u_\phi \sin \theta)}{\partial \theta} - \frac{\partial u_\theta}{\partial \phi} \right] \hat{r} + \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{\partial (r u_\phi)}{\partial r} \right] \hat{\theta} + \frac{1}{r} \left[\frac{\partial (r u_\theta)}{\partial r} - \frac{\partial u_r}{\partial \theta} \right] \hat{\phi},$$

$$\nabla \cdot \mathbf{u} = \frac{1}{r^2} \frac{\partial (r^2 u_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi}, \quad \nabla^2 \mathbf{u} = \left[\nabla^2 u_r - \frac{2u_r}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right] \hat{r} +$$

$$+ \left(\nabla^2 u_\theta - \frac{u_\theta}{r^2 \sin^2 \theta} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} \right) \hat{\theta} + \left(\nabla^2 u_\phi - \frac{u_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} \right) \hat{\phi},$$

$$(\mathbf{u} \cdot \nabla) \mathbf{B} = \left(u_r \frac{\partial B_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial B_r}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial B_r}{\partial \phi} - \frac{u_\theta B_\theta + u_\phi B_\phi}{r} \right) \hat{r} + \left(u_r \frac{\partial B_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial B_\theta}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial B_\theta}{\partial \phi} + \frac{u_\theta B_r}{r} - \frac{u_\phi B_\phi \cos \theta}{r \sin \theta} \right) \hat{\theta} +$$

$$+ \left(u_r \frac{\partial B_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial B_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial B_\phi}{\partial \phi} + \frac{u_\phi B_r}{r} + \frac{u_\theta B_\theta \cos \theta}{r \sin \theta} \right) \hat{\phi},$$

$$S_{rr} = \frac{\partial u_r}{\partial r}, \quad S_{r\theta} = S_{\theta r} = \frac{1}{2r} \left[\frac{\partial u_r}{\partial \theta} + r^2 \frac{\partial}{\partial r} \left(\frac{u_\theta}{r} \right) \right], \quad S_{r\phi} = S_{\phi r} = \frac{1}{2r \sin \theta} \left[\frac{\partial u_r}{\partial \phi} + r^2 \sin \theta \frac{\partial}{\partial r} \left(\frac{u_\phi}{r} \right) \right],$$

$$S_{\theta\theta} = \frac{1}{r} \left(u_r + \frac{\partial u_\theta}{\partial \theta} \right), \quad S_{\theta\phi} = S_{\phi\theta} = \frac{1}{2r \sin \theta} \left[\frac{\partial u_\theta}{\partial \phi} + \sin^2 \theta \frac{\partial}{\partial \theta} \left(\frac{u_\phi}{\sin \theta} \right) \right], \quad S_{\phi\phi} = \frac{1}{r \sin \theta} \left(u_r \sin \theta + u_\theta \cos \theta + \frac{\partial u_\phi}{\partial \phi} \right).$$

$$\iiint (\nabla \cdot \mathbf{A}) d\tau = \iint \mathbf{A} \cdot d\mathbf{a}, \quad \iint (\nabla \times \mathbf{A}) \cdot d\mathbf{a} = \oint \mathbf{A} \cdot d\mathbf{r}, \quad \mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} - (\mathbf{a} \cdot \mathbf{b}) \mathbf{c}.$$

$$\nabla \cdot (f \mathbf{A}) = (\nabla f) \cdot \mathbf{A} + f (\nabla \cdot \mathbf{A}), \quad \nabla \times (f \mathbf{A}) = (\nabla f) \times \mathbf{A} + f (\nabla \times \mathbf{A}), \quad \nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}.$$

$$0 = 2T + V + \sum_i \mathbf{r}_i \cdot \mathbf{F}_i^{\text{ext}}, \quad 0 = 3 \iiint P d\tau - \iint \mathbf{Pr} \cdot d\mathbf{a} + V, \quad V = \frac{1}{2} \iiint \Phi_g \rho d\tau = -\frac{1}{8\pi G} \iiint g^2 d\tau.$$

$$\lambda_D = \sqrt{\frac{k_B T}{8\pi n e^2}}, \quad \omega_p = \sqrt{\frac{4\pi n e^2}{m_e}}, \quad \sigma = 8\sigma_{\text{large}} \ln \Lambda, \quad \sigma_{\text{SB}} T_{\text{eff}}^4 = \frac{3GM\dot{M}_a}{8\pi\varpi^3} \left(1 - \sqrt{\frac{\varpi_{\text{in}}}{\varpi}} \right), \quad c_s = \sqrt{\gamma \frac{P}{\rho}}, \quad v_A = \frac{B}{\sqrt{4\pi\rho}}.$$

$$[\rho u_n] = 0, \quad [\rho u_n^2 + P] = 0, \quad [\rho u_n u_t] = 0, \quad \left[\frac{\rho u^2}{2} u_n + \frac{\gamma}{\gamma - 1} P u_n \right] = 0, \quad \frac{\rho_2}{\rho_1} = \frac{\gamma + 1}{\gamma - 1 + 2/M_{1n}^2}, \quad \frac{P_2}{P_1} = \frac{2\gamma M_{1n}^2 - \gamma + 1}{\gamma + 1}.$$

Τιμές φυσικών σταθερών στο σύστημα μονάδων cgs: $c = 3 \times 10^{10}$, $G = 6.67 \times 10^{-8}$, $h = 6.625 \times 10^{-27}$, $e = 4.8 \times 10^{-10}$, $m_e = 9.1 \times 10^{-28}$, $m_p = 1.67 \times 10^{-24}$, $k_B = 1.38 \times 10^{-16}$, $\sigma_{\text{SB}} = 5.67 \times 10^{-5}$, $1 \text{ eV} = 1.6 \times 10^{-12}$, $1 \text{ yr} = 3.1 \times 10^7$, $1 \text{ AU} = 1.5 \times 10^{13}$, $1 \text{ pc} = 3 \times 10^{18}$, $M_\odot = 2 \times 10^{33}$, $R_\odot = 6.96 \times 10^{10}$.