



$\alpha(T, P) = \frac{1}{l(T)} \frac{dl}{dT} \Big|_P \Rightarrow l(T'), l(T), P$

$\alpha(T, P) dT = \frac{dl}{l(T)} \Rightarrow \int_T^{T'} \alpha(T, P) dT = \int_{l(T)}^{l(T')} \frac{dl}{l} \Rightarrow$

$\int_T^{T'} \alpha(T) dT = \left[\ln(l) \right]_{l(T)}^{l(T')} = \ln \left(\frac{l(T')}{l(T)} \right) \Rightarrow$

$l(T') = l(T) \exp \left(\int_T^{T'} \alpha(T) dT \right)$ ←

$\alpha(T) \approx \alpha_0, \int_T^{T'} \alpha_0 dT = \alpha_0 (T' - T)$

$l(T') = l(T) \exp(\alpha \Delta T)$
 $\Delta T = T' - T$

$l(T') = l(T) \exp(\alpha \Delta T)$
 $\alpha \approx 10^{-5} / K \quad \Delta T \approx 10^2, \alpha \Delta T \approx 10^{-3}$

$\exp(10^{-3}) = \exp(0.001) \approx 1 + 0.001$
 $\exp(x) \approx 1 + x + \dots \quad |x| \ll 1$

22/3/2021 σελ. 2

$$l(T') = l(T) e^{a\Delta T}, \text{ εάν } a\Delta T \ll 1 \text{ τότε } e^{a\Delta T} = 1 + a\Delta T$$

$$l(T') = l(T) (1 + a\Delta T)$$

$$V(T') = V(T) (1 + \beta\Delta T)$$

$$\beta\Delta T \ll 1$$

$$T = 300 \text{ K}$$

$$T = 300^\circ \text{ K}$$

$$\Theta = 300^\circ \text{ C}$$

$$\underline{dW = dK}$$

$$\underline{d\vec{L} = \vec{F} dt = d\vec{p}}$$

$$dW = \vec{F} \cdot d\vec{x}, \quad d\vec{x} = 0 \Rightarrow dW = 0$$

$$\Rightarrow dK = 0$$



$$\underline{v = \sqrt{v^2}} \quad \frac{1}{2m} (p_x^2 + p_y^2) = \frac{1}{2m} (p_x'^2 + p_y'^2)$$

$$\Rightarrow p_x' = \pm p_x \Rightarrow \boxed{v_x' = \pm v_x}$$

$$\boxed{p_y' = p_y}$$

$$\boxed{v_x' = -v_x}$$

$$\left. \begin{array}{l} (v_x)_i > 0 \\ (v_x)_i < 0 \end{array} \right\} \begin{array}{l} (v_x)_i > 0 \\ 0 \\ (v_x)_i < 0 \end{array} \rightarrow \begin{array}{l} 2m(v_x)_i^2 \\ 0 \\ 0 \end{array}$$

$$\underline{m(v_x)_i^2 + m(-v_x)_i^2}$$

$$\boxed{pV = \frac{2K}{3}}$$

$$\boxed{pV = Nk_B T}$$

$$\frac{2K}{3} = Nk_B T$$

$$\# \text{outon}$$

$$\boxed{K = \frac{3}{2} Nk_B T}$$

1 Διάσταση



$$\cancel{\frac{1}{2} m_1 v_1^2} + \cancel{\frac{1}{2} m_2 v_2^2} = \cancel{\frac{1}{2} m_1 v_1'^2} + \cancel{\frac{1}{2} m_2 v_2'^2}, \quad m_1 = m_2$$

$$\rightarrow v_1^2 + v_2^2 = v_1'^2 + v_2'^2 \Rightarrow v_1^2 - v_1'^2 = v_2'^2 - v_2^2 \quad (\text{ADE})$$

$$(\text{ADO}) \quad dt \rightarrow 0 \quad d\vec{L} = \vec{F} \cdot dt \rightarrow 0 \quad d\vec{p} = 0$$

$$m v_1 + m v_2 = m v_1' + m v_2' \Rightarrow v_1 - v_1' = v_2' - v_2 \quad (1)$$

$$(v_1 - v_1')(v_1 + v_1') = (v_2' - v_2)(v_2' + v_2) \quad (2)$$

$$v_1 + v_1' = v_2' + v_2 \quad (2'), \quad (1) + (2') \Rightarrow 2v_1 = 2v_2' = v_2' + v_2 \quad (3)$$

$$\Rightarrow (3) \Rightarrow (2) \Rightarrow v_1' = v_2$$



$$\cancel{\frac{1}{2} m v_1^2} = \cancel{\frac{1}{2} m v_1'^2}$$

$$v_1' = \pm \sqrt{v_1^2}$$

$$v_1' = \pm v_1$$

$$v_1'^2 = v_1^2 \Rightarrow$$

$$v_1' = v_1$$

$$v_1' = -v_1$$

$$d\vec{L} = \vec{F}_{12} \cdot dt + \vec{F}_{21} \cdot dt = (\vec{F}_{12} + \vec{F}_{21}) dt$$

$\rightarrow 0$
3ος Ν. Newton