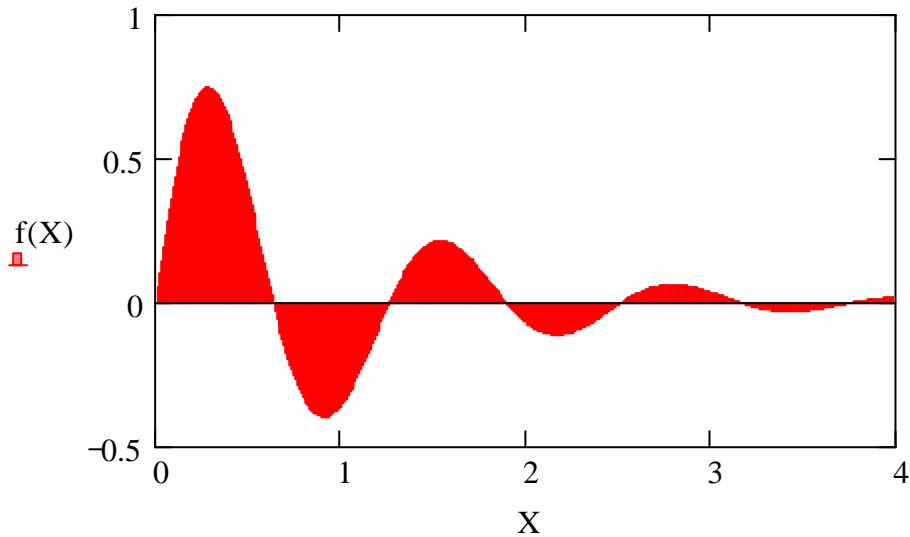


Simple Programming

$$f(x) := \sin(5x) \cdot e^{-x}$$

$$X := 0, 0.01 .. 4$$



$$\int_0^{10} f(x) dx = 0.1923$$

Integration: Simpson's Rule

```
INTG(F,A,B ,N) := | NN <- 2N
                    | Step <- (B - A) / NN
                    | Sum <- 0.0
                    | for i <- 1 .. NN - 1
                    |   xx <- A + i·Step
                    |   Sum <- Sum + F(xx)
                    | Sum <- Sum + (F(A) + F(B)) / 2
                    | INTG <- Sum·Step
                    | return INTG
```

$$\int_0^{10} f(x) dx = 0.19229973$$

$$\text{INTG}(f, 0, 10, 12) = 0.19229724$$

Symbolic Evaluation

$$\int \sin(5x) \cdot e^{-x} dx \rightarrow \frac{-5}{26} \cdot \exp(-x) \cdot \cos(5 \cdot x) - \frac{1}{26} \cdot \sin(5 \cdot x) \cdot \exp(-x)$$

Differential Equations

Harmonic Oszillator: Solutions through Runge-Kutta Integration

The differential equation has the form:

$$\frac{d^2x}{dt^2} = -kx$$

If $x(t) = X_0$ and $dx/dt = X_1$ then the differential equation is equivalent to the following system:

$$\begin{aligned} \frac{dX_0}{dt} &= X_1 \\ \frac{dX_1}{dt} &= -kX_0 \end{aligned}$$

Using a fixed step Runge-Kutta method:

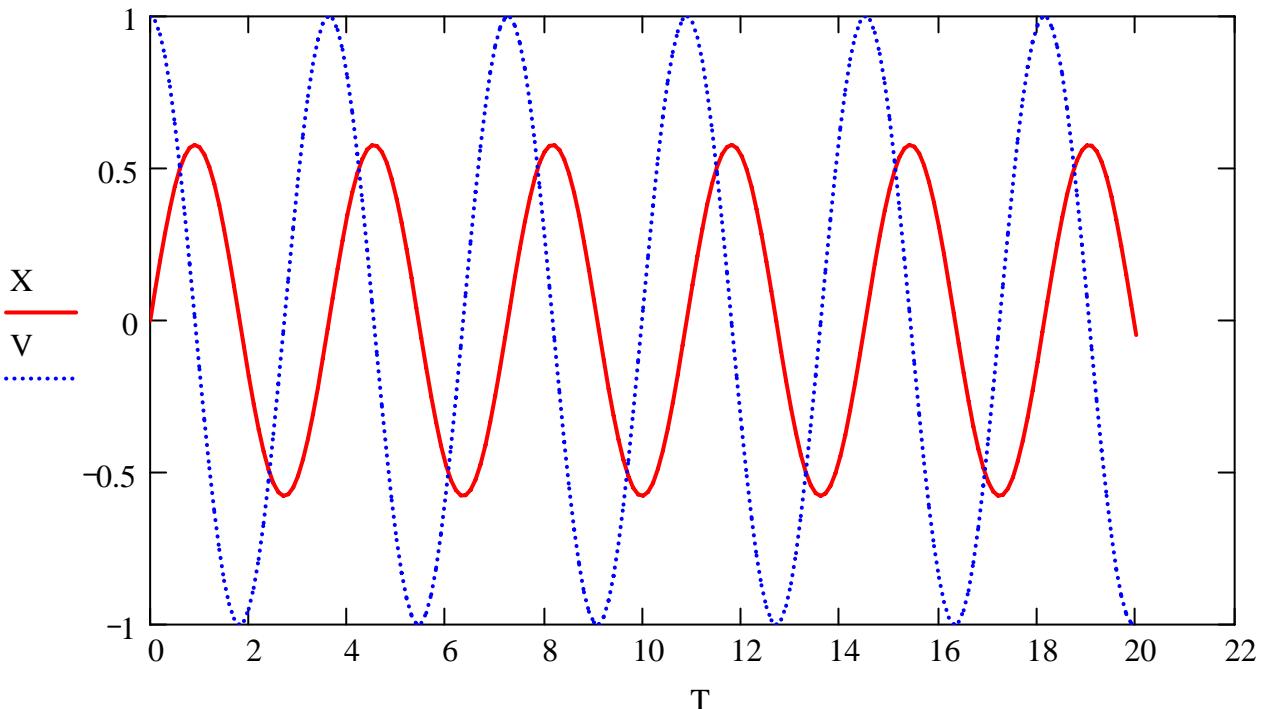
$$t0 := 0.0 \quad t1 := 20 \quad N := 200 \quad k := 3$$

$$D(t, X) := \begin{pmatrix} X_1 \\ -k \cdot X_0 \end{pmatrix}$$

$$ic := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$S := rkfixed(ic, t0, t1, N, D)$$

$$V := S^{(2)} \quad X := S^{(1)} \quad T := S^{(0)}$$



Harmonic Oszillator with Friction

$t0 := 0.0$ $t1 := 20$ $N := 200$ $k := 3$ $c := 0.2$

$$D(t, X) := \begin{pmatrix} X_1 \\ -k \cdot X_0 - c \cdot X_1 \end{pmatrix}$$

$$ic := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$S := rkfixed(ic, t0, t1, N, D)$

$V := S^{\langle 2 \rangle}$ $X := S^{\langle 1 \rangle}$ $T := S^{\langle 0 \rangle}$

