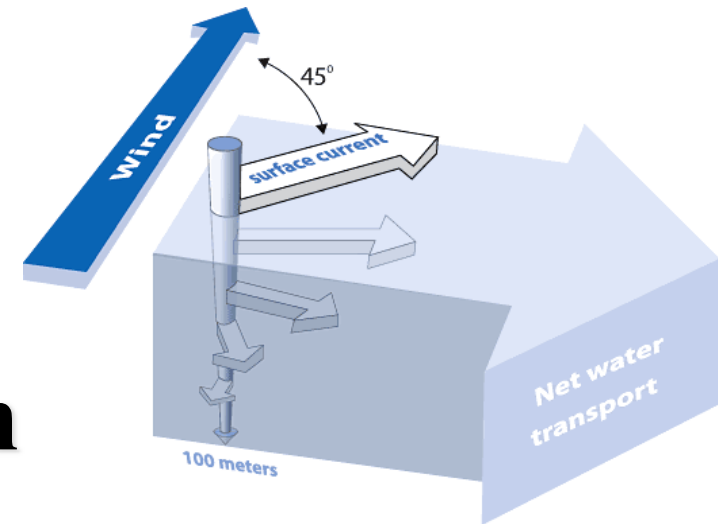
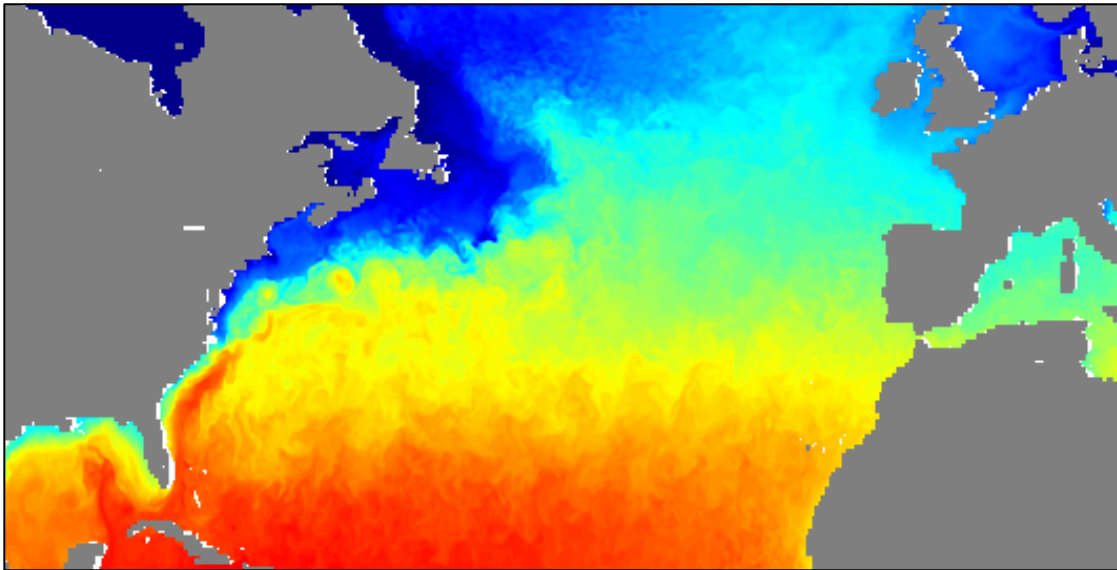




5. Wind driven circulation

5. Ανεμογενής κυκλοφορία



- Εισαγωγικές έννοιες
- Η θεωρία του Ekman
- Η θεωρία του Sverdrup για την ανεμογενή κυκλοφορία
- Το δυτικό όριο και οι προσεγγίσεις των Stommel και Munk

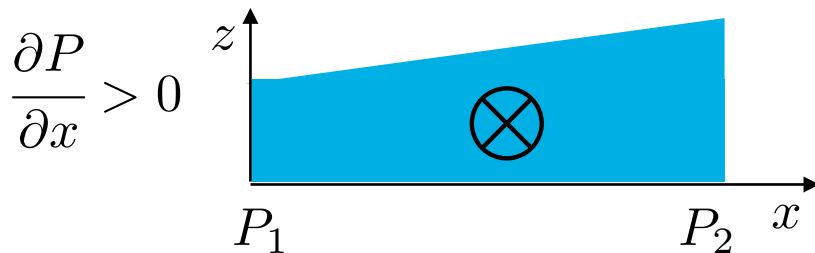
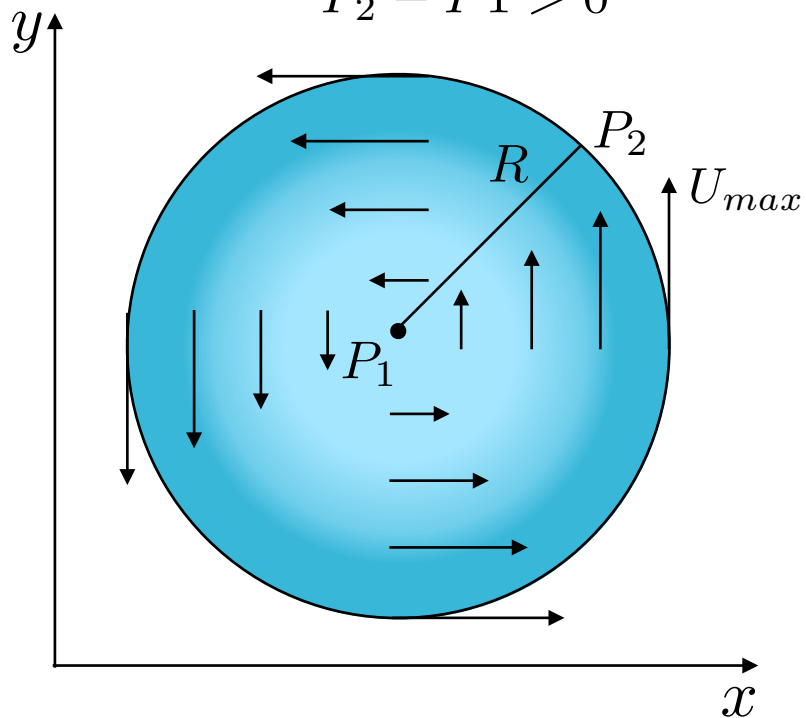
The geostrophic – hydrostatic limit

Large L

$$fv = \frac{1}{\rho_0} \frac{\partial p}{\partial x}, \quad (1) \quad fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}, \quad (2) \quad \frac{1}{\rho_0} \frac{\partial p}{\partial z} = -g \quad (3)$$

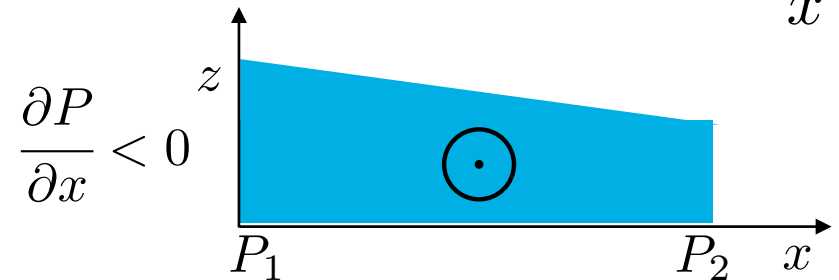
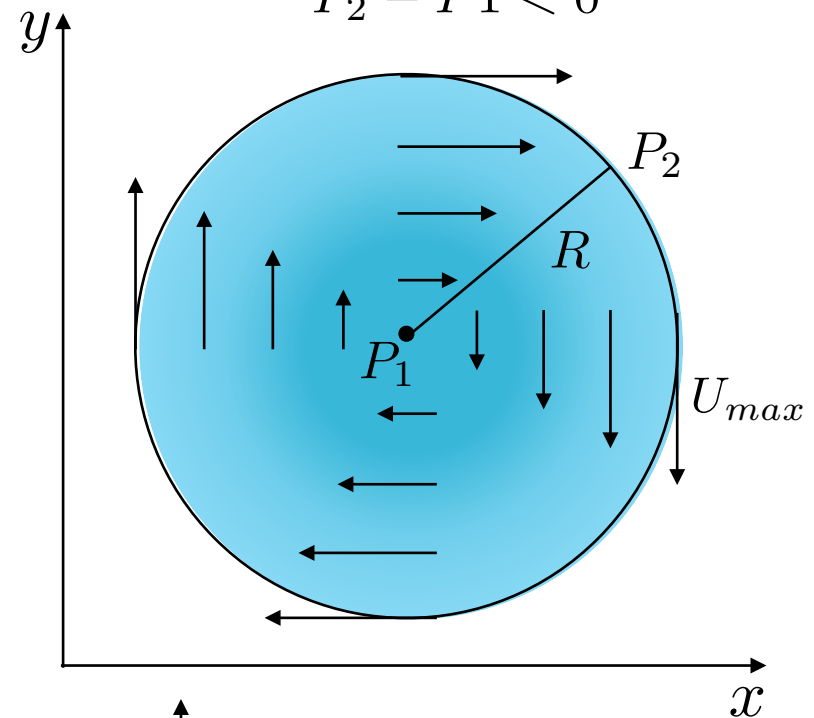
Κυκλώνας (B.H.)
Cyclone

$$P_2 - P_1 > 0$$

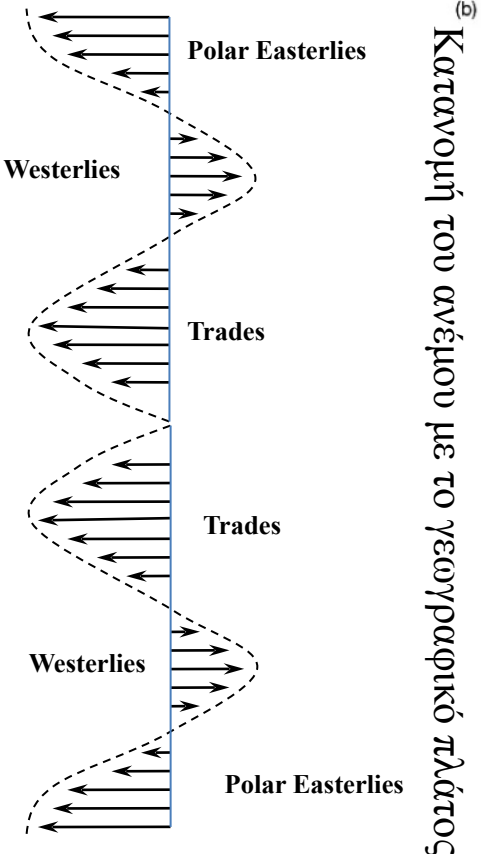
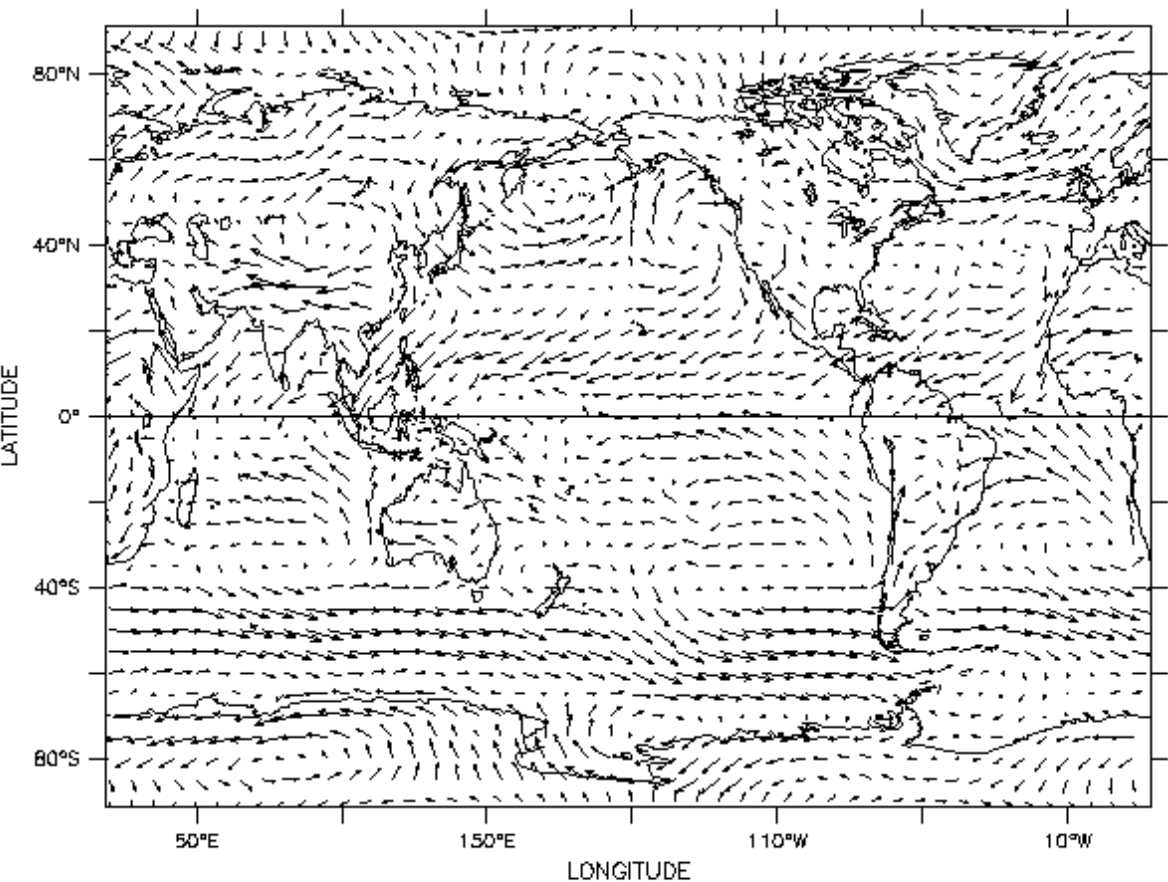
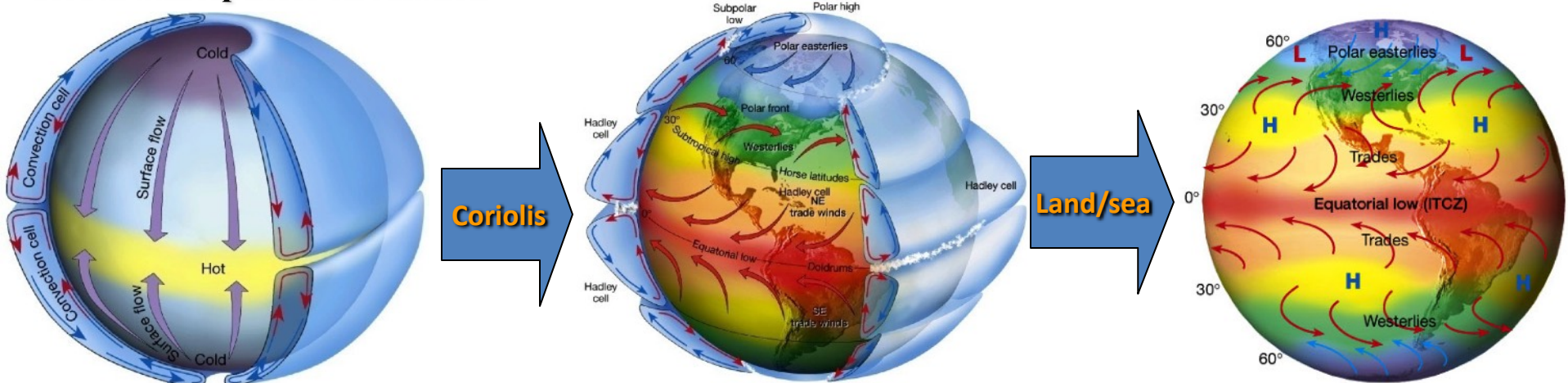


Αντικυκλώνας (B.H.)
Anticyclone

$$P_2 - P_1 < 0$$



Global atmospheric circulation



(b) Καταννομή του ανέμου με το γεωγραφικό πλάτος

Wind stress on the sea

$$\vec{\tau} = c_D \rho_a |u_{10}| \vec{u}_{10}$$

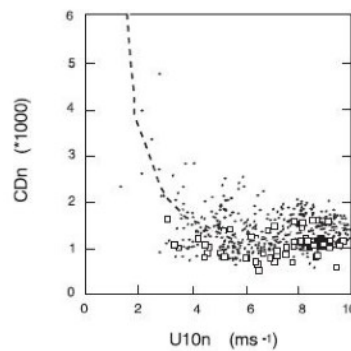
where:

ρ_a air density (1.3 kg/m^3)

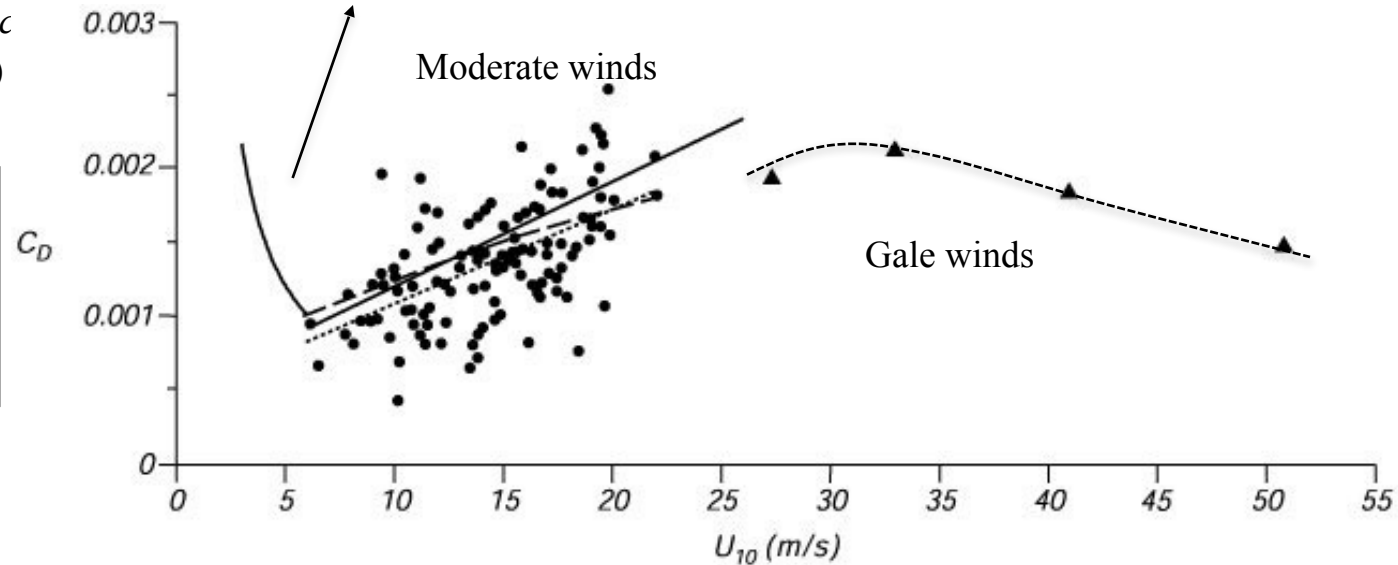
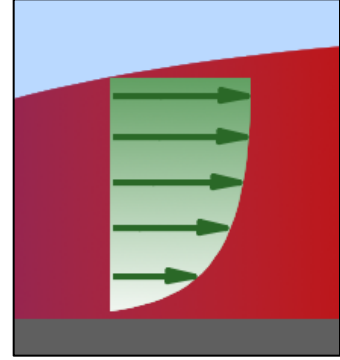
u_{10} wind speed at 10 m (m/sec)

c_D drag coefficient (unitless)

Measurements showed that c_D is related to the wind speed (not a constant). Nevertheless, we usually use a constant value for simplicity.



Weak winds



Examples of c_D used:

$$c_D = 1.4 \times 10^{-3}$$

$$c_D = 1.1 \times 10^{-3} \text{ ασθενείς άνεμοι}$$

$$c_D = (0.61 + 0.063u) \times 10^{-3} \text{ ισχυροί άνεμοι}$$

$$c_D = (0.29 + 3.1u_{10}^{-1} + 7.7u_{10}^{-2}) 10^{-3}$$

$$\text{for } 3 \text{ m/sec} \leq u_{10} \leq 6 \text{ m/sec}$$

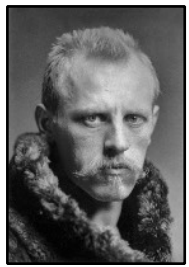
$$c_D = (0.60 + 0.070u_{10}) 10^{-3}$$

$$\text{for } 6 \text{ m/sec} \leq u_{10} \leq 26 \text{ m/sec}$$



Evolution of wind-driven circulation theory:

<i>Fridtjof Nansen</i>	(1898)	Qualitative theory, currents transport water at an angle to the wind.
<i>Vagn Walfrid Ekman</i>	(1902)	Quantitative theory for wind-driven transport at the sea surface.
<i>Harald Sverdrup</i>	(1947)	Theory for wind-driven circulation in the eastern Pacific.
<i>Henry Stommel</i>	(1948)	Theory for westward intensification of wind-driven circulation (western boundary currents).
<i>Walter Munk</i>	(1950)	Quantitative theory for main features of the wind-driven circulation
<i>Kirk Bryan</i>	(1963)	Numerical models of the oceanic circulation.



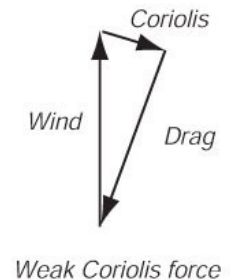
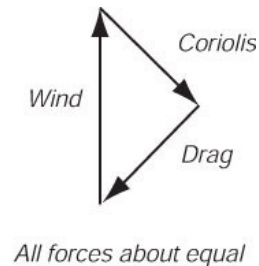
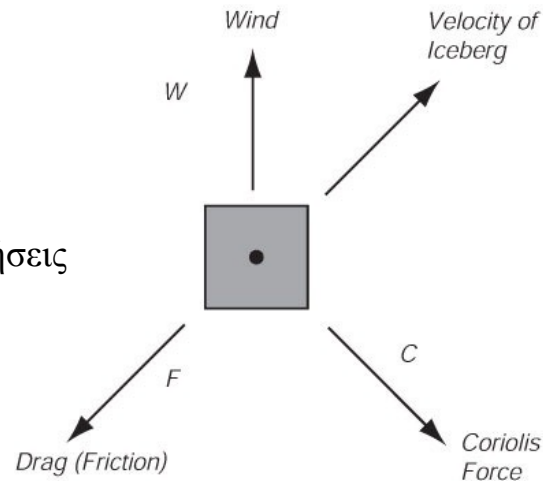
Fridtjof Nansen
1861-1930

The surface wind effect (Nansen theory):

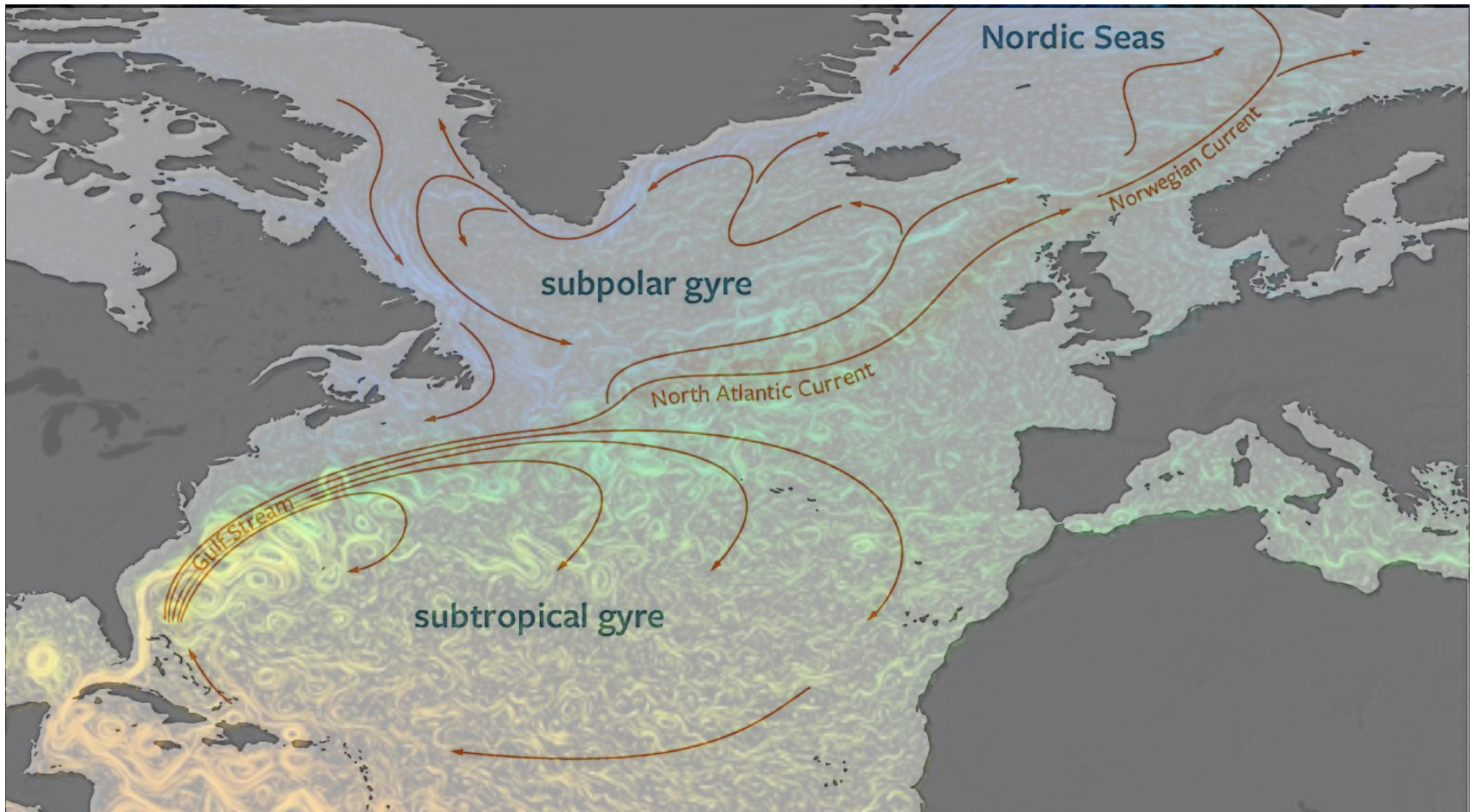


Βασισμένος σε παρατηρήσεις
της κίνησης παγόβουνων

$$W + F + C = 0$$



Η περιοχή μελέτης



Πως εξηγείται η δομή της κυκλοφορίας (με τα ίδια χαρακτηριστικά στους τρεις ωκεανούς); Αυτά θα μελετηθούν με τις θεωρίες Ekman, Sverdrup, Stommel και Munk.

Ekman Theory



Vagn Walfrid Ekman
1874-1954

Εξισώσεις εργασίας:

Conservation of momentum equations:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + f v + A_H \frac{\partial^2 u}{\partial x^2} + A_H \frac{\partial^2 u}{\partial y^2} + A_V \frac{\partial^2 u}{\partial z^2}$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial y} - f u + A_H \frac{\partial^2 v}{\partial x^2} + A_H \frac{\partial^2 v}{\partial y^2} + A_V \frac{\partial^2 v}{\partial z^2}$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial z} - g + A_H \frac{\partial^2 w}{\partial x^2} + A_H \frac{\partial^2 w}{\partial y^2} + A_V \frac{\partial^2 w}{\partial z^2}$$

Conservation of mass equation:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Υποθέσεις:

Κινήσεις μεγάλης (οριζόντιας) κλίμακας: very large L

Για απλούστευση των λύσεων θα αγνοήσουμε μεταβολές στην πυκνότητα: $\rho = \rho_0$

$$E_k = \frac{\text{Viscosity terms}}{\text{Coriolis terms}} \begin{cases} \rightarrow A_H \frac{U}{L^2} \frac{1}{fU} = \frac{A_H}{fL^2} \ll 1 \\ \rightarrow A_V \frac{U}{H^2} \frac{1}{fU} = \frac{A_V}{fH^2} \sim 1 \end{cases} \quad R_o = \frac{\text{Non-linear terms}}{\text{Coriolis terms}} = \frac{U}{fL} \ll 1$$

Θεωρώντας ότι το H είναι το βάθος επίδρασης του ανέμου $\ll$ του ολικού βάθους

$$A_H \nabla_H^2 \vec{u} \ll A_V \frac{\partial^2 \vec{u}}{\partial z^2}$$

Και οι εξισώσεις κίνησης γίνονται:

$$\left. \begin{aligned} -fv &= -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + A_V \frac{\partial^2 u}{\partial z^2} \\ fu &= -\frac{1}{\rho_0} \frac{\partial p}{\partial y} + A_V \frac{\partial^2 v}{\partial z^2} \end{aligned} \right\} \quad (\text{A})$$

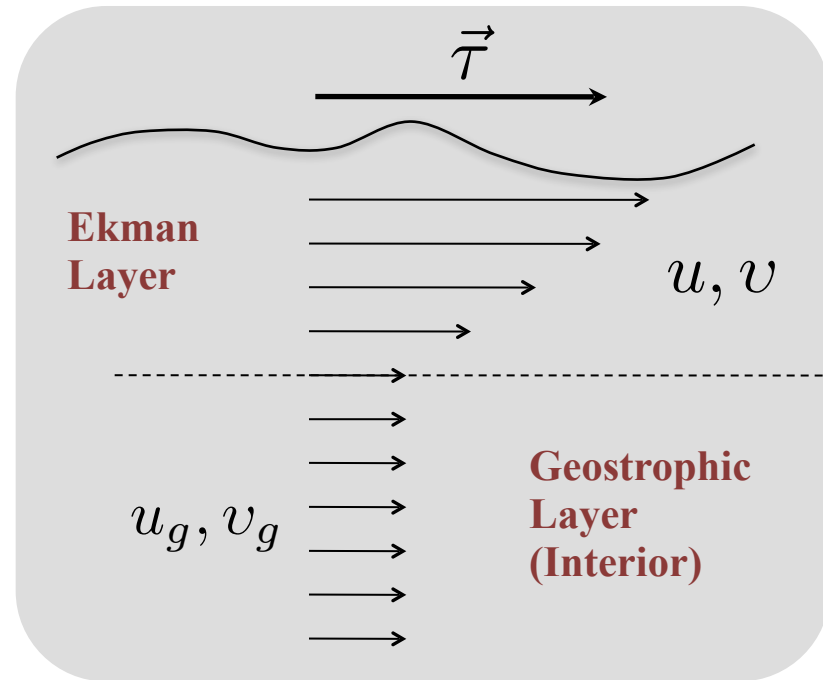
Η γεωστροφική ισορροπία συνεχίζει να ισχύει (ο άνεμος δημιουργεί βαθμίδες πίεσης):

$$\left. \begin{aligned} -fv_g &= -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ fu_g &= -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \end{aligned} \right\} \quad (\text{B})$$

(A) - (B) $\longrightarrow$

$$\begin{aligned} -f(v - v_g) &= A_V \frac{\partial^2 u}{\partial z^2} \\ f(u - u_g) &= A_V \frac{\partial^2 v}{\partial z^2} \end{aligned}$$

Ekman Equations



$$\begin{aligned} -f(v - v_g) &= A_V \frac{\partial^2 u}{\partial z^2} \quad (1) \\ f(u - u_g) &= A_V \frac{\partial^2 v}{\partial z^2} \quad (2) \end{aligned}$$

για απλούστευση θεωρούμε μόνο ζωνικό άνεμο: $\tau^y = 0$

Οριακές συνθήκες:
$$\begin{cases} \text{at } z = 0 \rightarrow \rho_0 A_V \frac{\partial u}{\partial z} = \tau^x; \rho_0 A_V \frac{\partial v}{\partial z} = 0 \\ \text{at } z \rightarrow \infty \rightarrow u = u_g; v = v_g \end{cases}$$

Πολ/ζουμε (2) με $i = \sqrt{-1}$ και προσθέτουμε την (1):

Η λύση είναι: $V = Ae^{(1+i)z/\delta} + Be^{-(1+i)z/\delta}$

$$\frac{d^2 V}{dz^2} - \frac{if}{A_V} V = 0 \quad (3), \text{ where } V = u - u_g + i(v - v_g)$$

$$\text{where } \delta = \sqrt{\frac{2A_V}{f}}$$

remember: $u_g, v_g \not\propto z$

B=0, αφού η λύση δεν μπορεί να απειρίζεται για $z \rightarrow -\infty$

Χρησιμοποιώντας τις δύο οριακές συνθήκες: $A = \frac{\tau^x \delta (1 - i)}{2\rho_0 A_V}$

Αντικαθιστώντας στην V:

$$u - u_g + i(v - v_g) = \frac{\tau^x \delta (1 - i)}{2\rho_0 A_V} e^{\frac{(1+i)z}{\delta}} = (1 - i) \frac{\tau^x / \rho_0 \sqrt{2}}{\sqrt{f A_V}} \frac{1}{2} e^{z/\delta} \left(\cos \frac{z}{\delta} + i \sin \frac{z}{\delta} \right) =$$

$$= \frac{\tau^x / \rho_0}{\sqrt{f A_V}} e^{z/\delta} \left(\frac{\sqrt{2}}{2} \cos \frac{z}{\delta} + \frac{\sqrt{2}}{2} \sin \frac{z}{\delta} \right) - i \frac{\tau^x / \rho_0}{\sqrt{f A_V}} e^{z/\delta} \left(\frac{\sqrt{2}}{2} \cos \frac{z}{\delta} - \frac{\sqrt{2}}{2} \sin \frac{z}{\delta} \right)$$

$$\cos \frac{\pi}{4} \cos \frac{z}{\delta} + \sin \frac{\pi}{4} \sin \frac{z}{\delta} = \cos \left(-\frac{z}{\delta} + \frac{\pi}{4} \right) \quad \sin \frac{\pi}{4} \cos \frac{z}{\delta} - \cos \frac{\pi}{4} \sin \frac{z}{\delta} = \sin \left(-\frac{z}{\delta} + \frac{\pi}{4} \right)$$

$$u = u_g + \frac{\tau^x / \rho_0}{\sqrt{f A_V}} e^{z/\delta} \cos \left(-\frac{z}{\delta} + \frac{\pi}{4} \right) \quad v = v_g - \frac{\tau^x / \rho_0}{\sqrt{f A_V}} e^{z/\delta} \sin \left(-\frac{z}{\delta} + \frac{\pi}{4} \right)$$

$$u = u_g + \frac{\tau^x / \rho_0}{\sqrt{f A_V}} e^{z/\delta} \cos \left(-\frac{z}{\delta} + \frac{\pi}{4} \right) \quad v = v_g - \frac{\tau^x / \rho_0}{\sqrt{f A_V}} e^{z/\delta} \sin \left(-\frac{z}{\delta} + \frac{\pi}{4} \right)$$

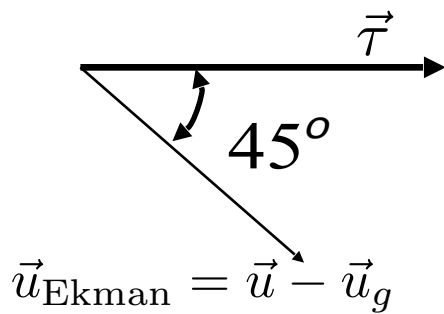
II. Επιφανειακή ταχύτητα Ekman:

at $z = 0$

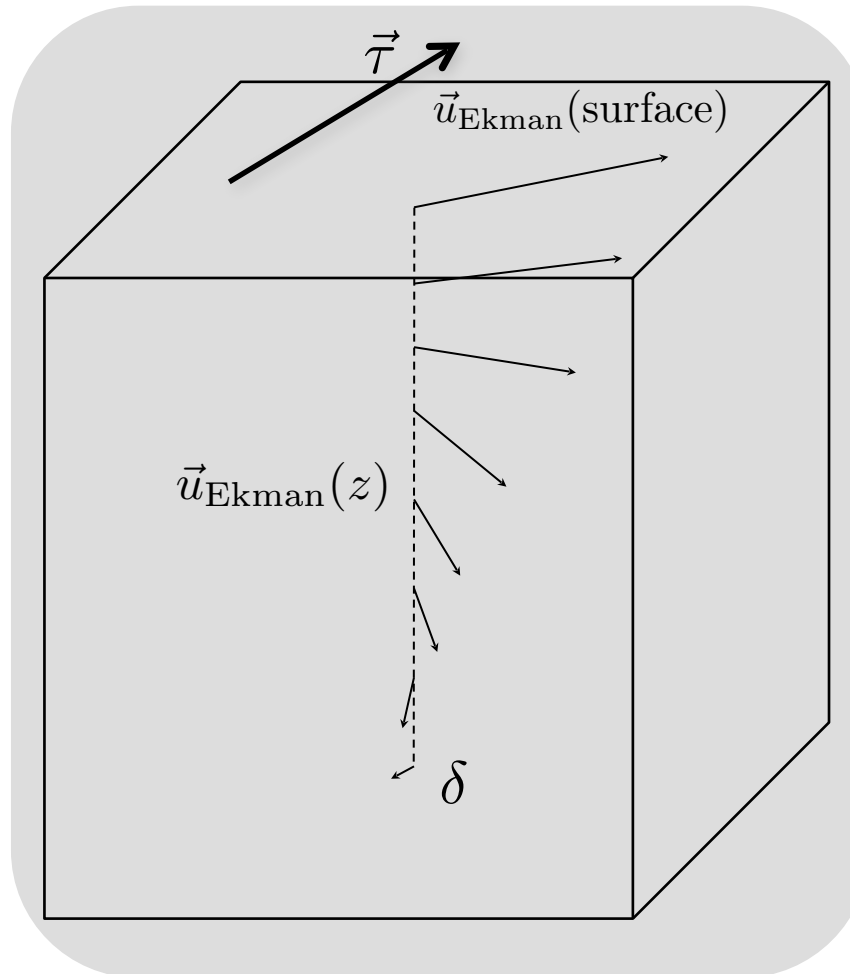
$$u_{surface} = u_g + \frac{\tau^x / \rho_0}{\sqrt{f A_V}} \cos \left(\frac{\pi}{4} \right)$$

$$v_{surface} = v_g - \frac{\tau^x / \rho_0}{\sqrt{f A_V}} \sin \left(\frac{\pi}{4} \right)$$

at $z = 0$



II. Η κατακόρυφη κατανομή της ταχύτητας Ekman:



Ekman Spiral (Η σπείρα του Ekman)

Το βάθος του στρώματος Ekman (**Ekman layer**) ορίζεται ως το βάθος όπου η ταχύτητα μειώνεται κατά ένα e (e-folding scale)

$$\delta = \sqrt{\frac{2A_V}{f}}$$

III. Η κατά βάθος ολοκληρωμένη μεταφορά Ekman (Ekman transport):

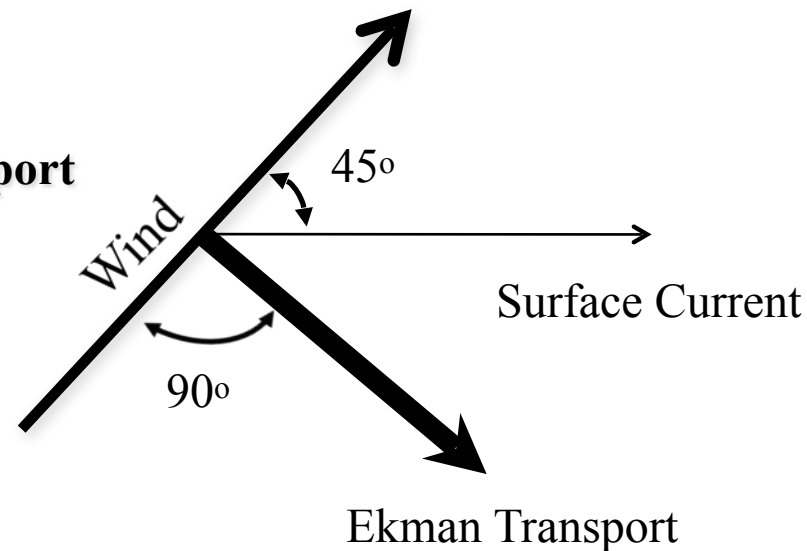
Ολοκληρώνοντας την ταχύτητα λόγω επίδρασης του ανέμου ($\vec{u} - \vec{u}_g$) από την επιφάνεια μέχρι το εσωτερικό του ωκεανού:

$$U_E = \int_{-\infty}^0 (u - u_g) dz = \frac{1}{\rho_0 f} \tau^y$$

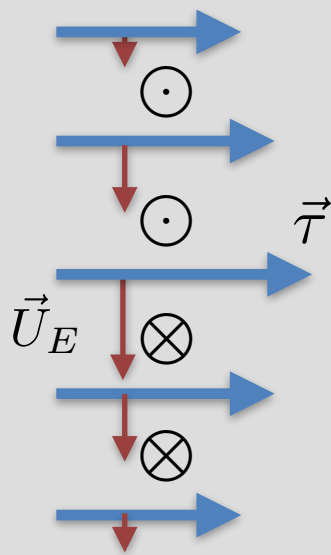
$$V_E = \int_{-\infty}^0 (v - v_g) dz = -\frac{1}{\rho_0 f} \tau^x$$

Ekman Transport

Συνέπειες:

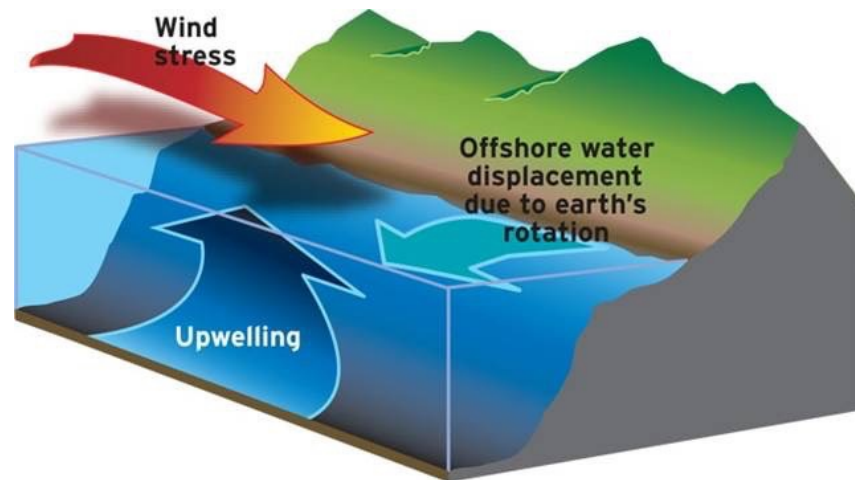


Open sea upwelling/downwelling

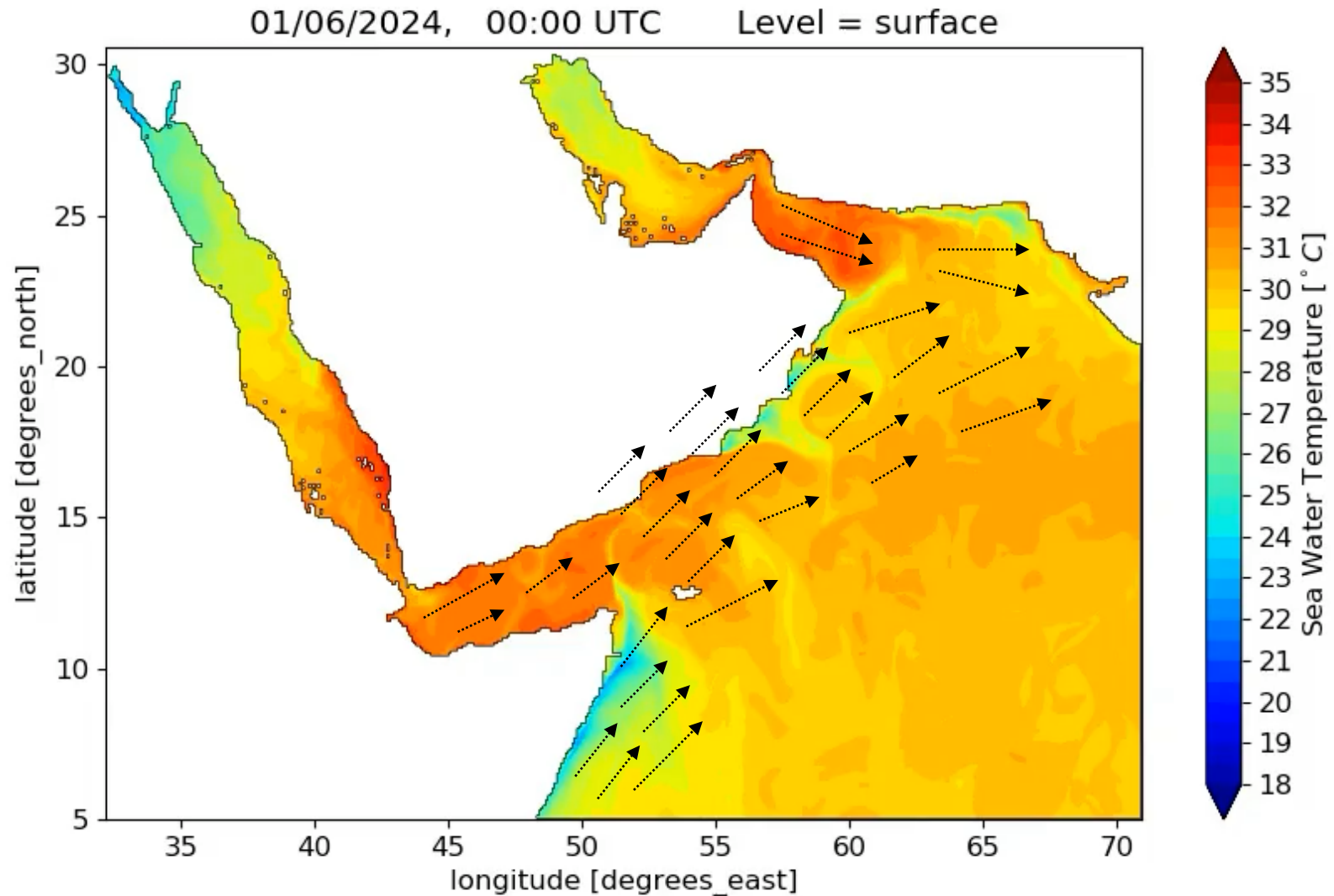


Η σύγκλιση/απόκλιση μεταφοράς Ekman δημιουργεί καταβύθιση/ανάβλιση, αντίστοιχα

Coastal upwelling

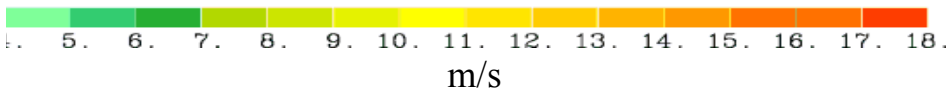
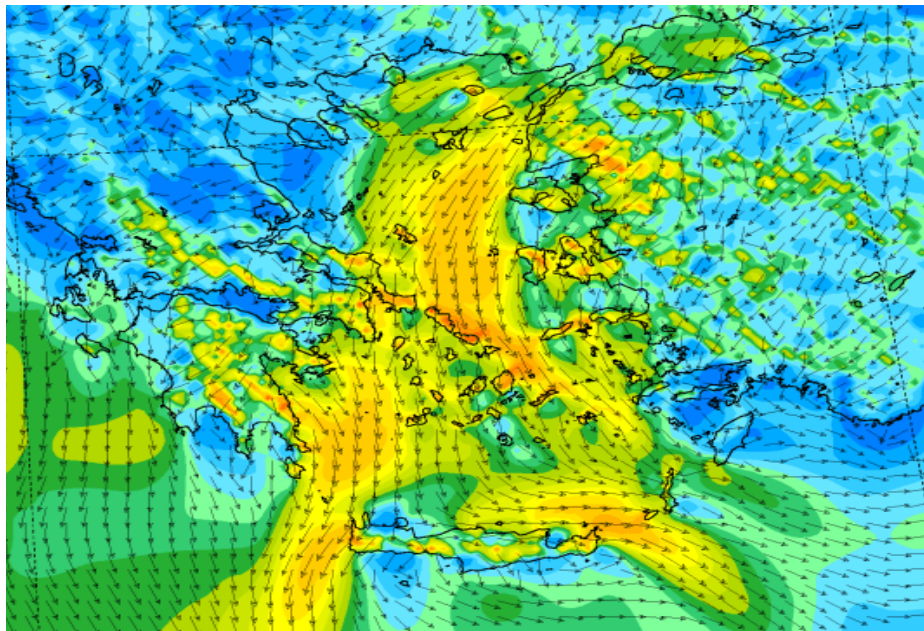


Coastal upwelling induced by the summer monsoon wind forcing

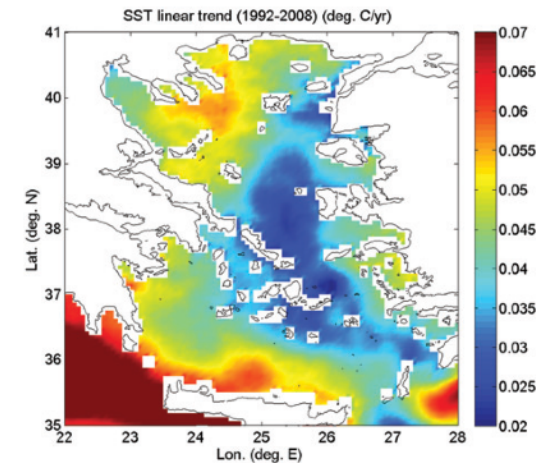
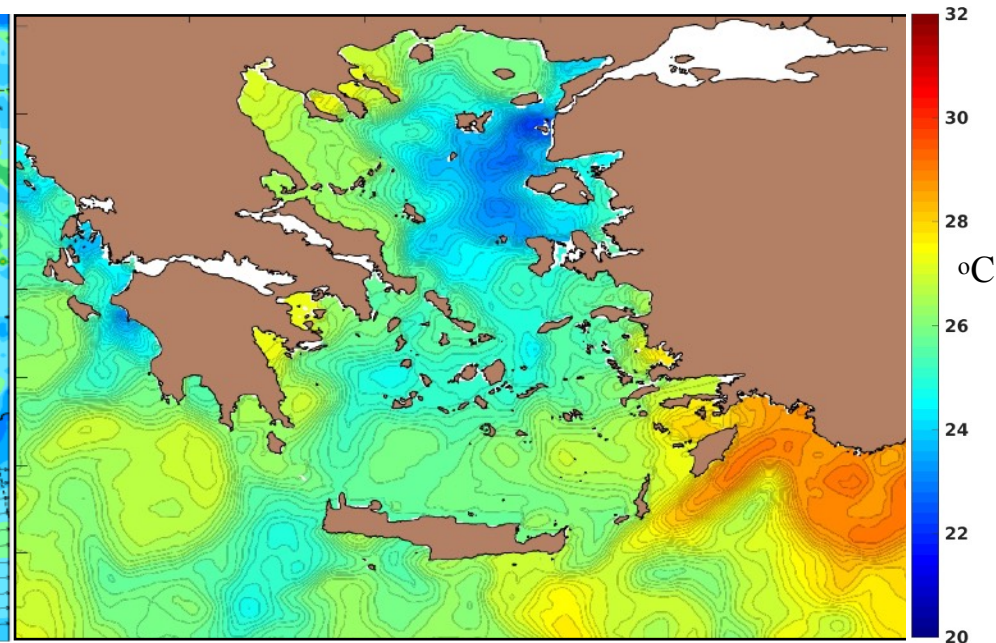


August 9, 2025

Winds at 10 m (AM&WFG)

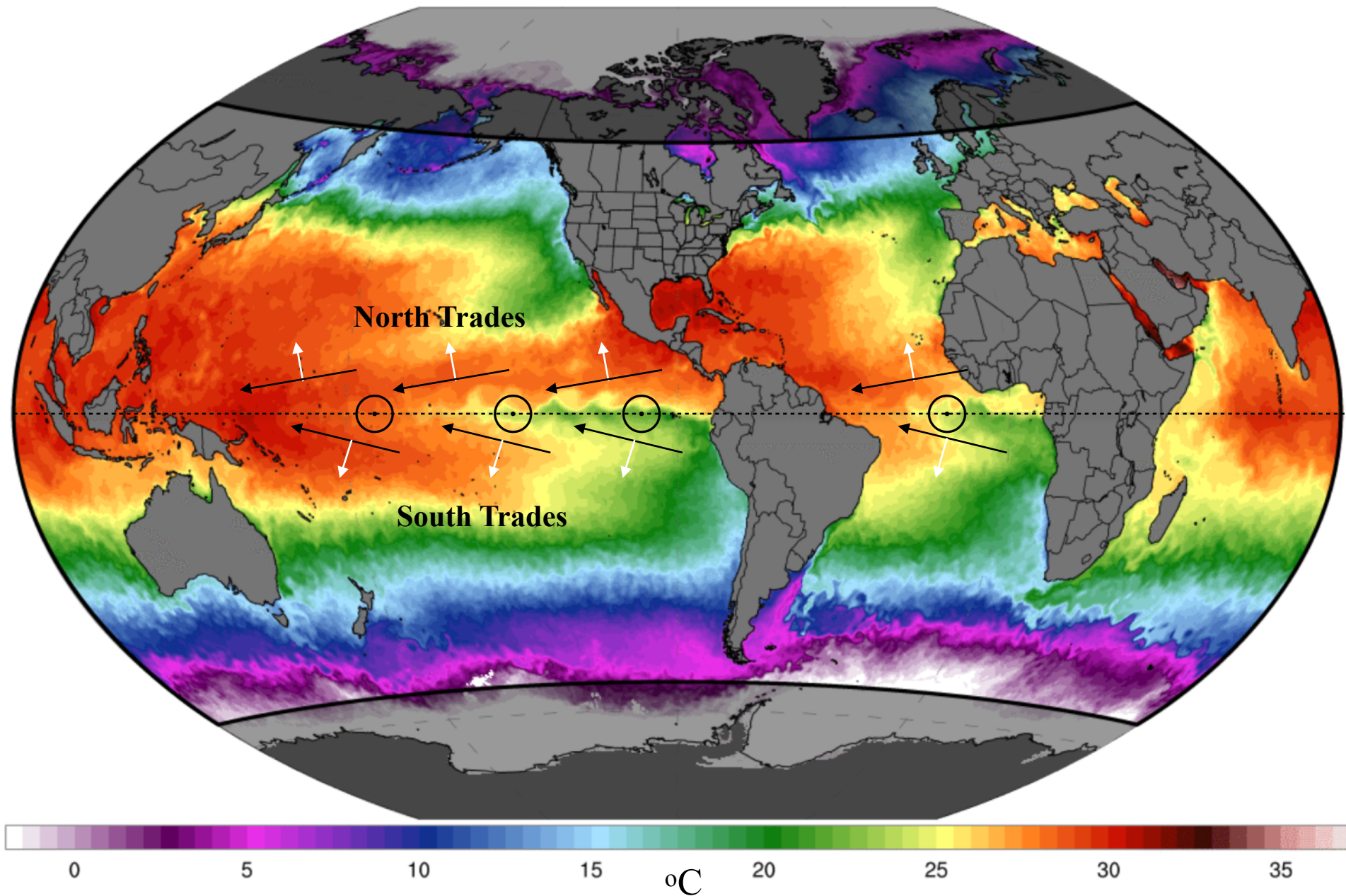


Sea Surface temperature (AVHRR - OPAM)



και η επίδραση στις κλιματικές τάσεις

Open sea upwelling/downwelling



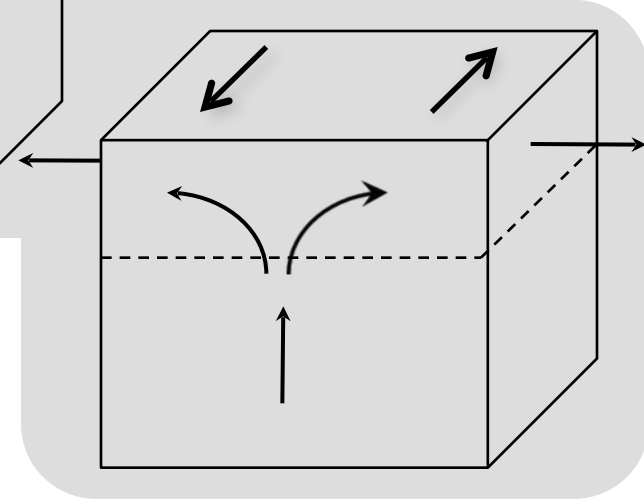
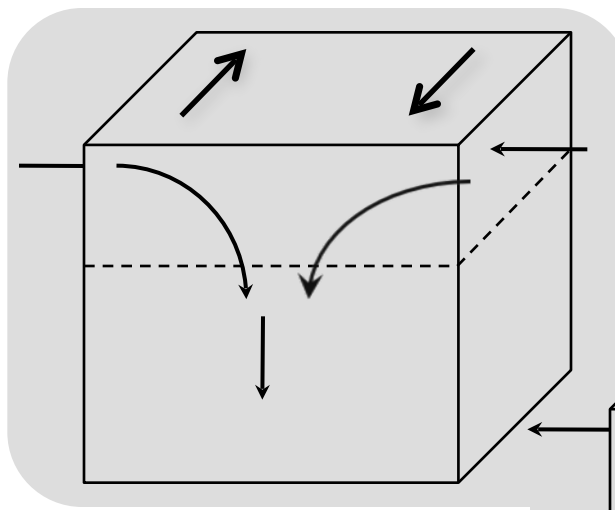
IV. Ekman pumping

Από την εξίσωση συνέχειας: $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

$$-\int_{-\infty}^0 dw = \int_{-\infty}^0 \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) dz$$

$$\Rightarrow -\cancel{w(0)} + w(-\infty) = \frac{1}{\rho_0 f} \underbrace{\left(\frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} \right)}$$

Wind Stress Curl



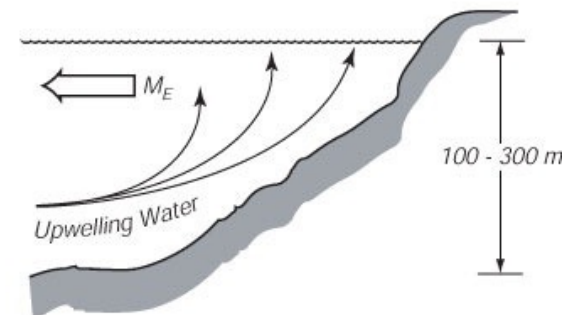
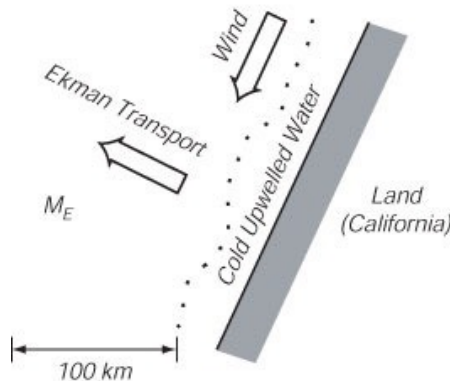
Coastal Ekman pumping

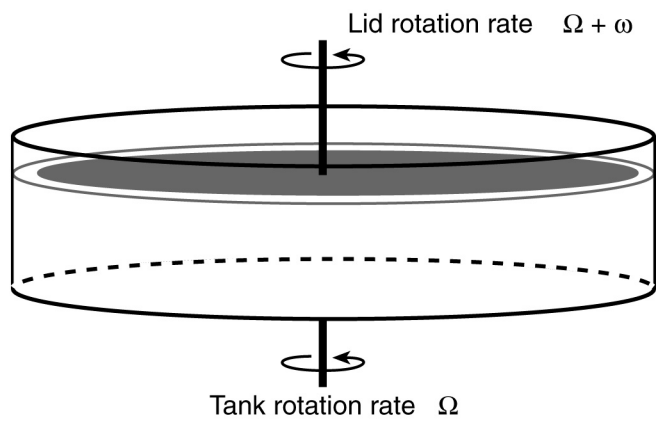
Στο εσωτερικό (κάτω από το στρώμα Ekman):

$$w_{Ek} = \frac{1}{\rho_0 f} \left(\frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} \right)$$

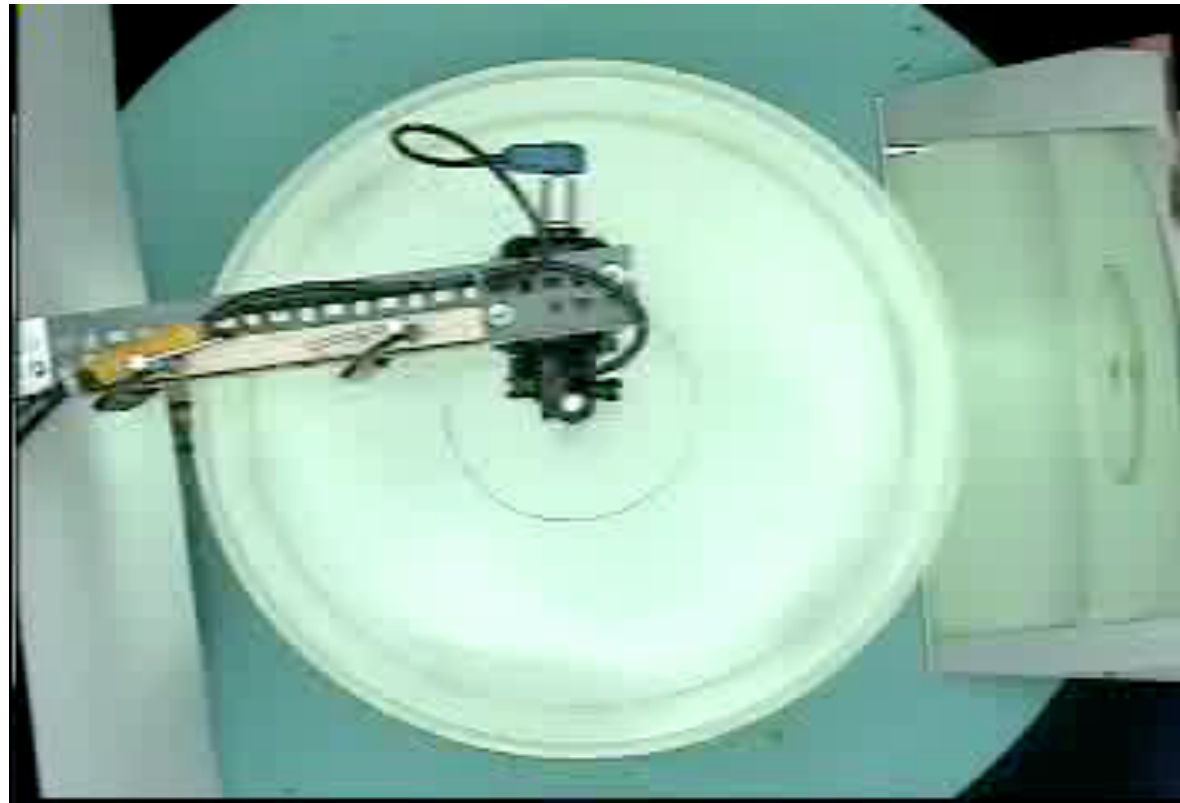
Επειδή η παράγωγος δεν ορίζεται στην παράκτια περιοχή (η τάση είναι ασυνεχής συνάρτηση)

$$w_{Ek} = \frac{U_E}{L} = \frac{\tau^{x,y}}{L\rho_0 f}$$





Ekman dynamics in a tank



Sverdrup's theory for the wind-driven circulation



Harald Ulrik Sverdrup
1888-1957

Ξεκινώντας από τις εξισώσεις κίνησης παρουσία (κατακόρυφης) τριβής:

$$\left. \begin{aligned} -fv &= -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + A_V \frac{\partial^2 u}{\partial z^2} \quad (1) \\ fu &= -\frac{1}{\rho_0} \frac{\partial p}{\partial y} + A_V \frac{\partial^2 v}{\partial z^2} \quad (2) \end{aligned} \right\} \quad \frac{\partial}{\partial x}(2) - \frac{\partial}{\partial y}(1)$$

$$u \cancel{\frac{\partial f}{\partial x}} + f \frac{\partial u}{\partial x} + v \left(\frac{\partial f}{\partial y} \right) + f \frac{\partial v}{\partial y} = \frac{1}{\rho_0} \cancel{\frac{\partial^2 p}{\partial x \partial y}} - \frac{1}{\rho_0} \cancel{\frac{\partial^2 p}{\partial x \partial y}} + A_V \frac{\partial^3 v}{\partial x \partial z^2} - A_V \frac{\partial^3 u}{\partial y \partial z^2}$$

$$\Rightarrow f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \beta v = A_V \frac{\partial^2}{\partial z^2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

$$\text{at } z = 0 \rightarrow \rho_0 A_V \frac{\partial u}{\partial z} = \tau^x$$

$$\rho_0 A_V \frac{\partial v}{\partial z} = \tau^y$$

$$\text{at } z = -H \rightarrow \rho_0 A_V \frac{\partial u}{\partial z} = 0$$

$$\rho_0 A_V \frac{\partial v}{\partial z} = 0$$

Ολοκληρώνοντας από το βυθό (-H) μέχρι την επιφάνεια της θάλασσας:

$$\Rightarrow \rho_0 f \int_{-H}^0 \left(\frac{\partial u}{\partial x} + \cancel{\frac{\partial v}{\partial y}} \right) dz + \beta \int_{-H}^0 \rho_0 v dz = \frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y}$$

Using continuity and the fact that $w(0)=w(-H)=0$

Meridional mass transport M_y

Wind stress curl

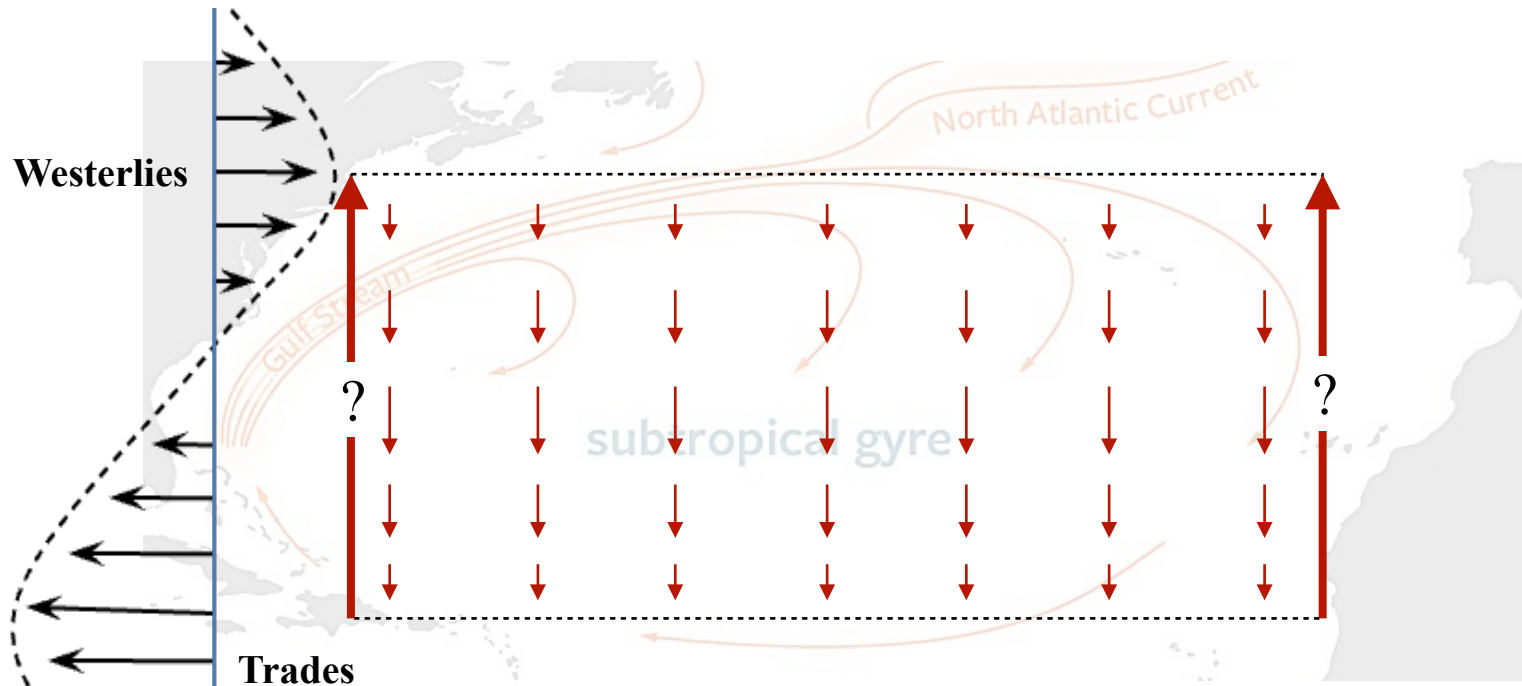
Depth integrated vorticity equation for the wind-driven circulation

and for $\tau_y = 0$

$$\beta M_y = \frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} \quad \text{(wind-stress curl)}$$

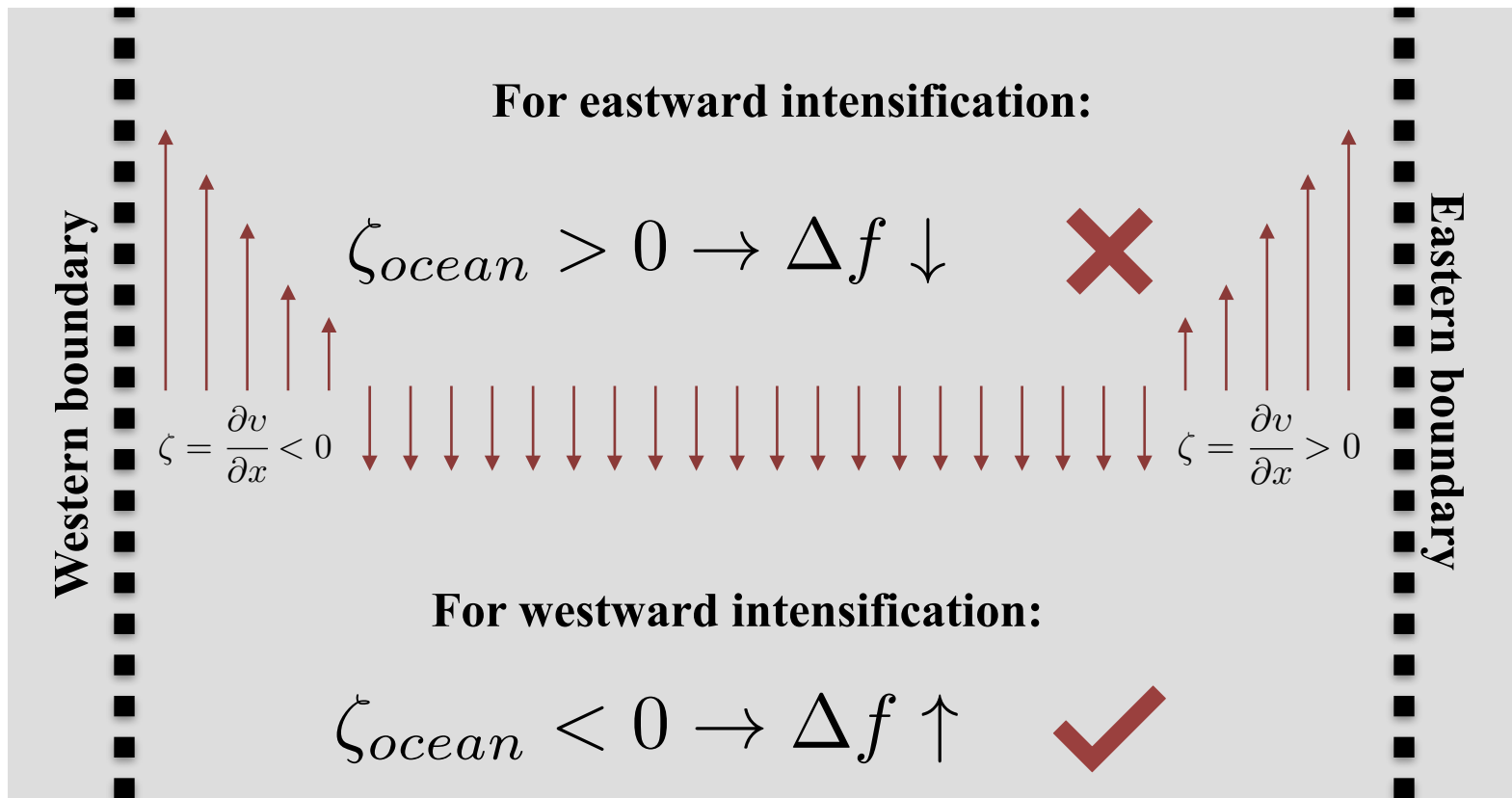
$$M_y = -\frac{1}{\beta} \frac{\partial \tau^x}{\partial y}$$

**Meridional
Sverdrup
Transport**



$$M_y \longrightarrow$$

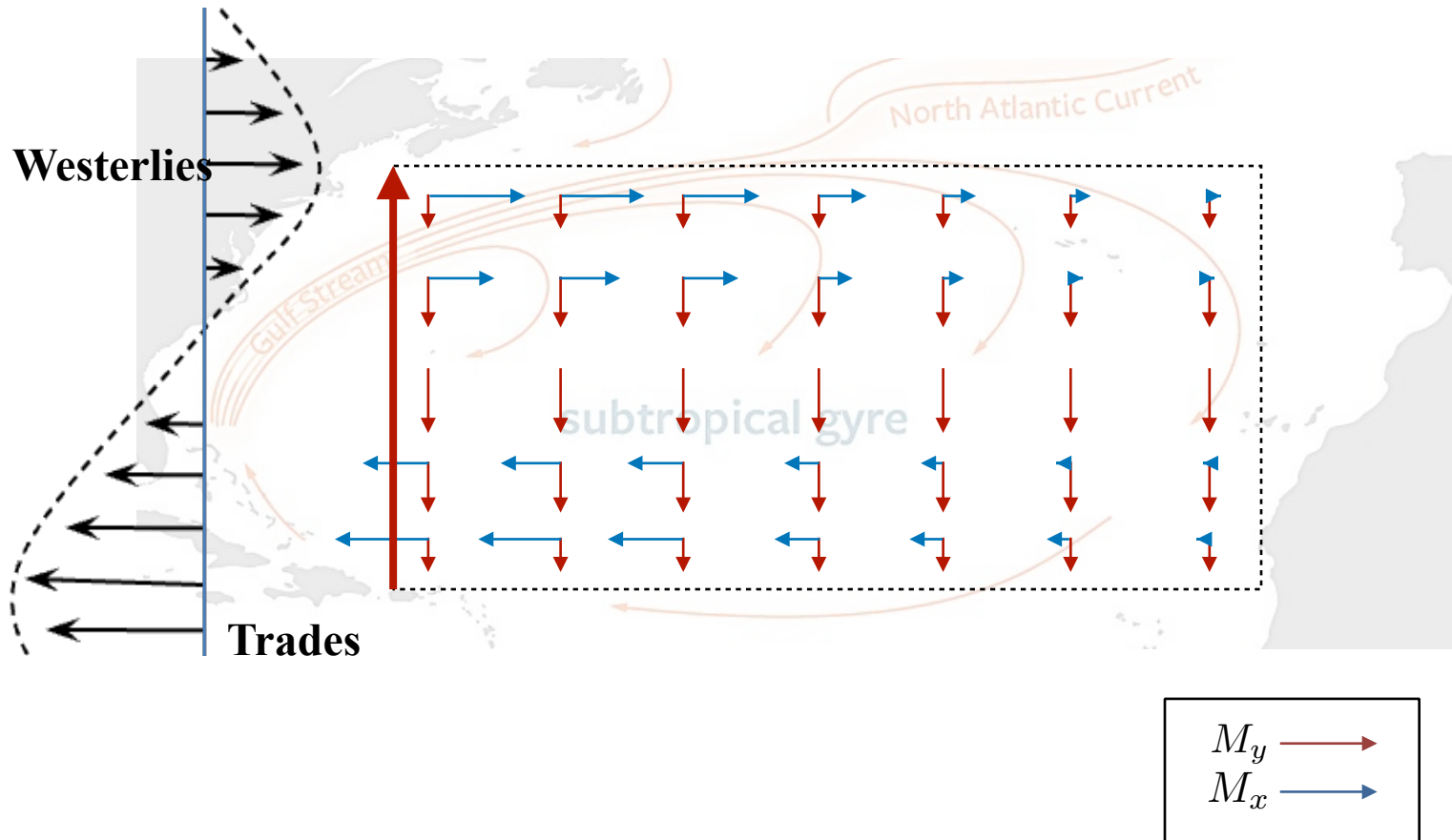
Vorticity considerations $f + \zeta = ct$



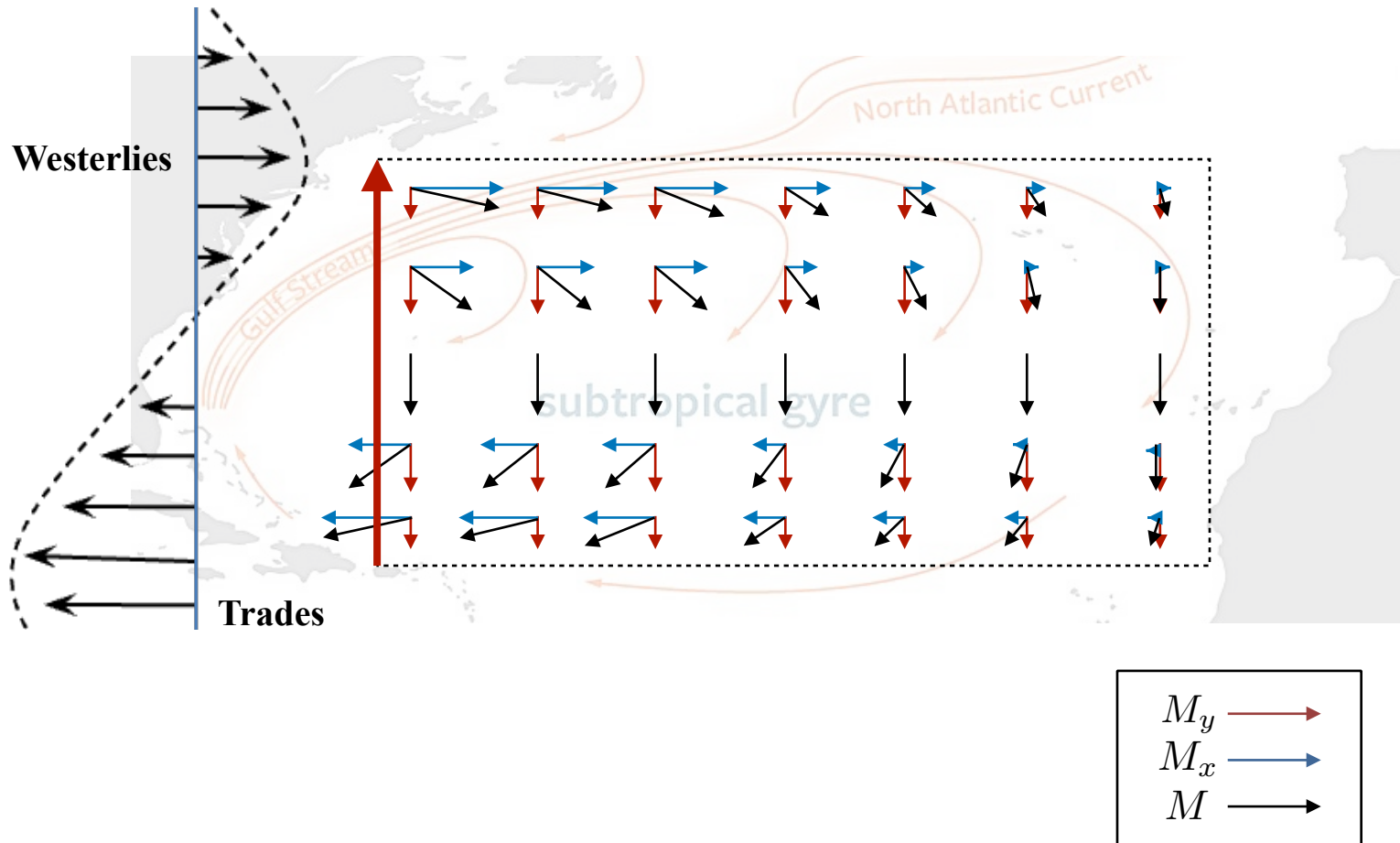
The zonal Sverdrup transport

Using the depth
integrated mass
conservation

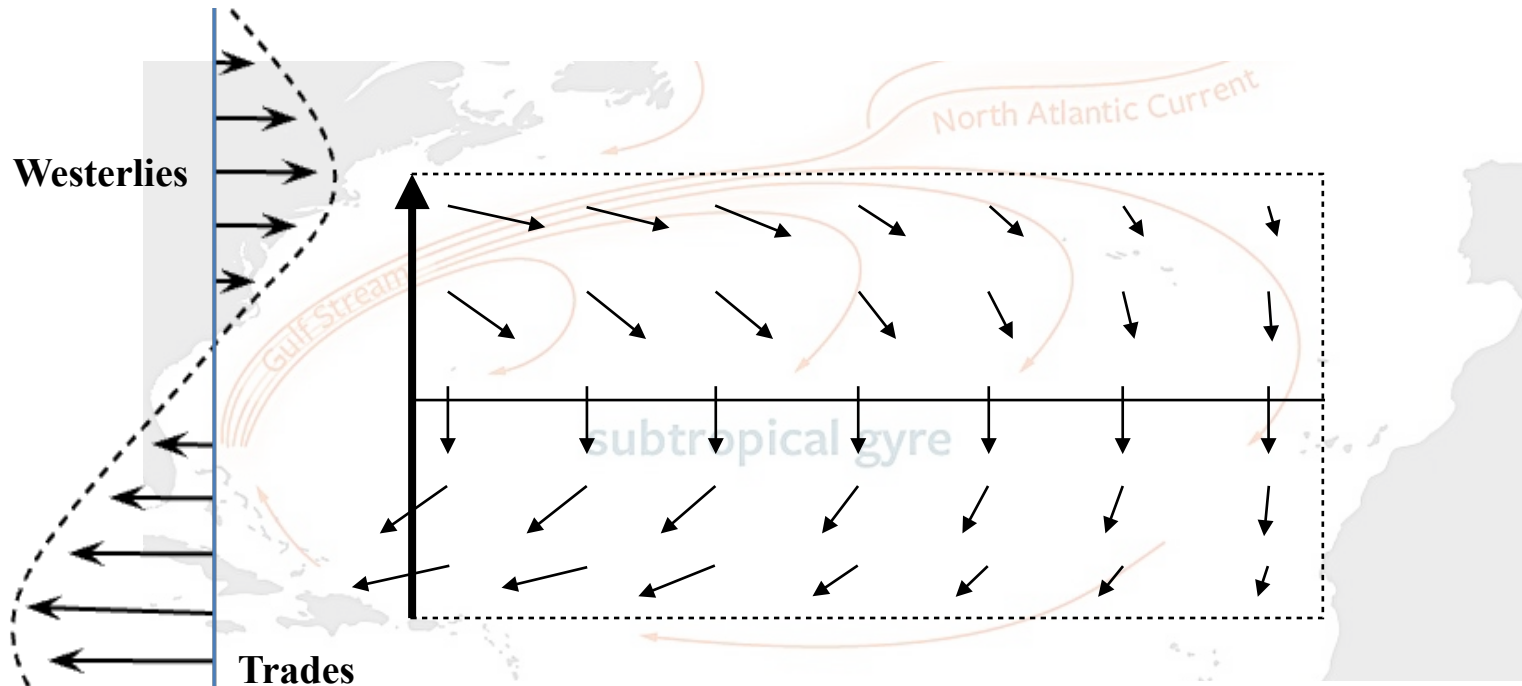
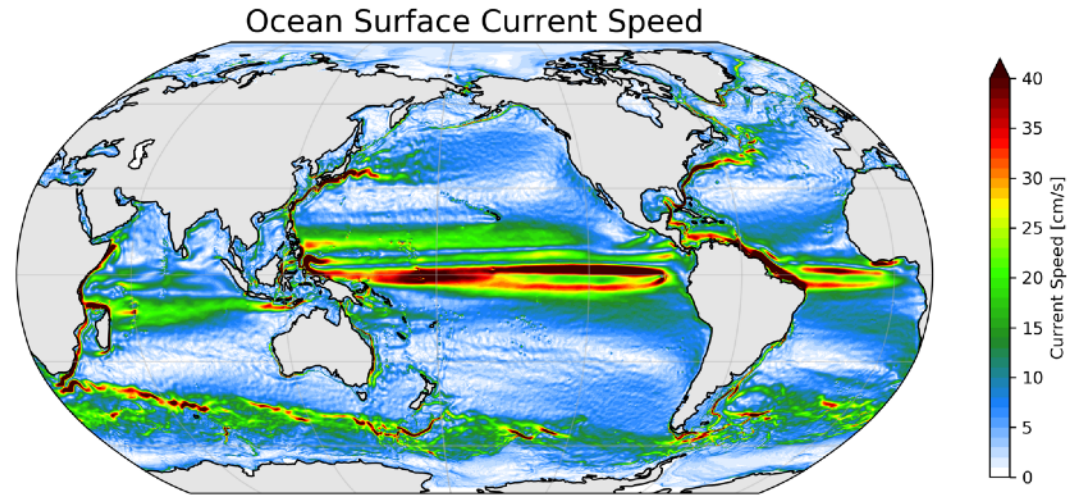
$$\frac{\partial M_x}{\partial x} + \frac{\partial M_y}{\partial y} = 0 \Rightarrow M_x(x) = \frac{\partial}{\partial y} \int_x^{x_{East}} -M_y dx = -\frac{1}{\beta} \frac{\partial^2 \tau^x}{\partial y^2} (x_{East} - x)$$



Combining M_x and M_y to estimate the Sverdrup Circulation



Sverdrup Circulation for the Subtropical Gyre



$M \longrightarrow$

$$v = \frac{U_{Sv}}{H} = -\frac{1}{H\beta\rho_0} \left(\frac{\partial\tau^x}{\partial y} \right)_{max} = v_g = \frac{g}{f} \frac{\partial\eta}{\partial x} \Rightarrow$$

$$\frac{\partial\eta}{\partial x} = -\frac{f}{gH\beta\rho_0} \left(\frac{\partial\tau^x}{\partial y} \right)_{max} \Rightarrow$$

$$\eta(x) = -\frac{f}{gH\beta\rho_0} \left(\frac{\partial\tau^x}{\partial y} \right)_{max} \int_x^{x_{east}} dx$$

$$\eta(x) = \frac{f}{gH\beta\rho_0} \left(\frac{\partial\tau^x}{\partial y} \right)_{max} (x_{east} - x)$$

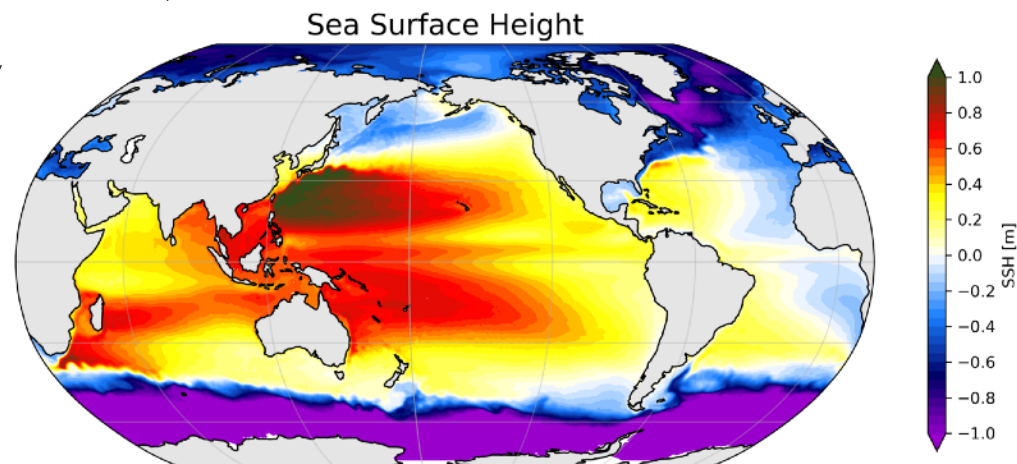
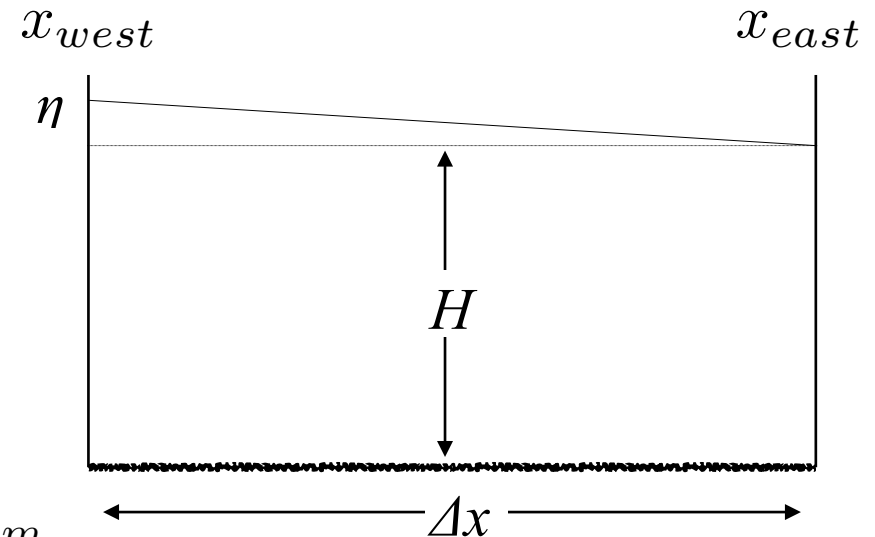
and η_{max} (Western boundary) = 1m

for: $f = 10^{-4} s^{-1}$, $\beta = 10^{-11} m^{-1} s^{-1}$, $H = 1000m$,

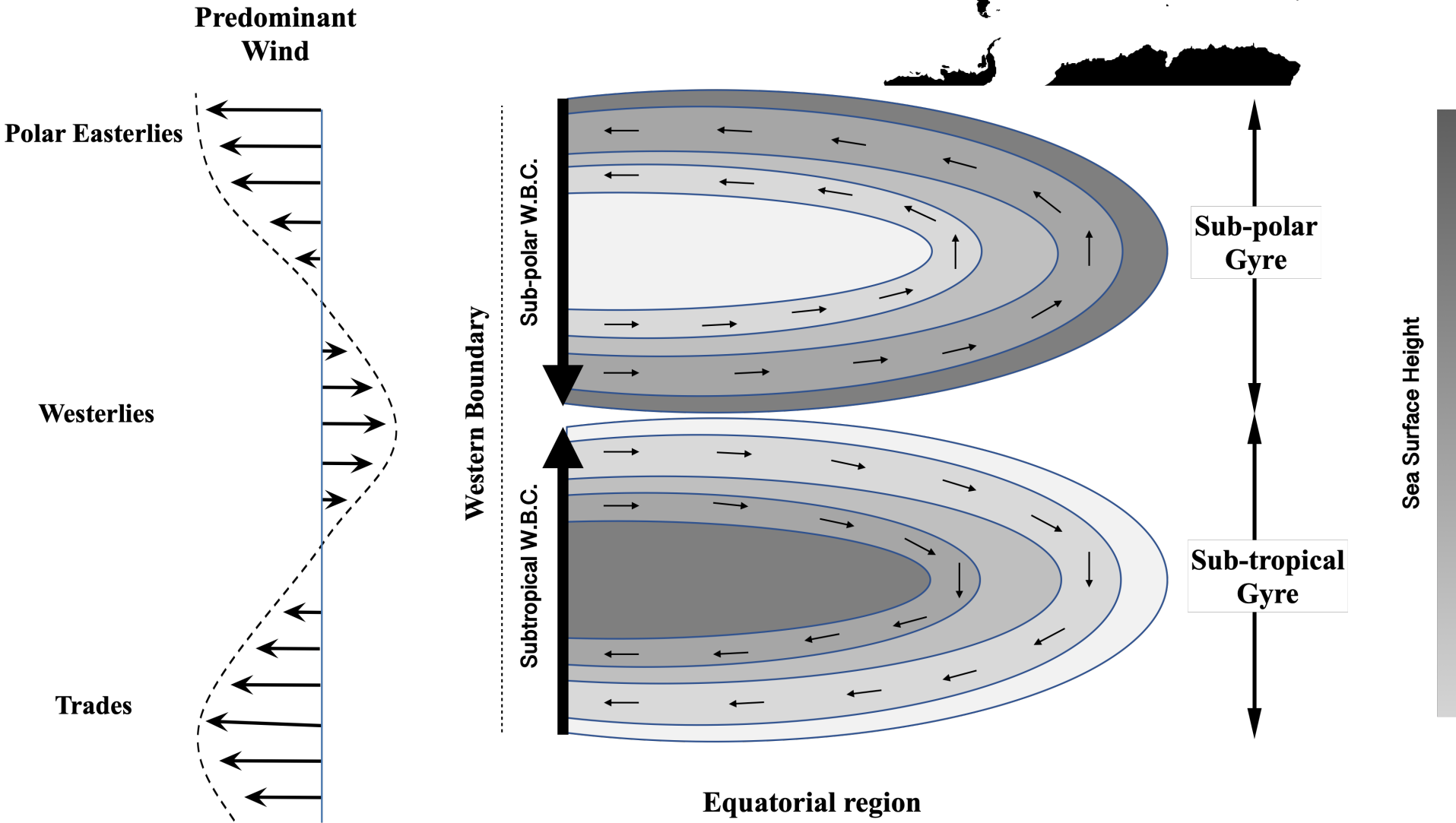
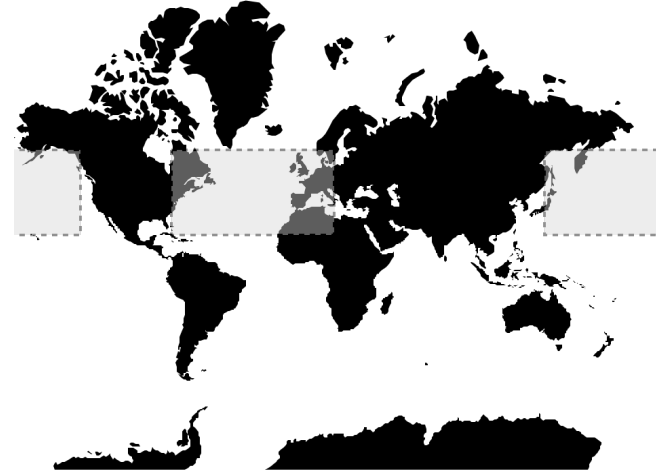
$g = 10 m s^{-1}$, $\tau_{max} = 10^{-1} Pa$, $\Delta x = 10^7 m$

Meridional Gyre span: 30°

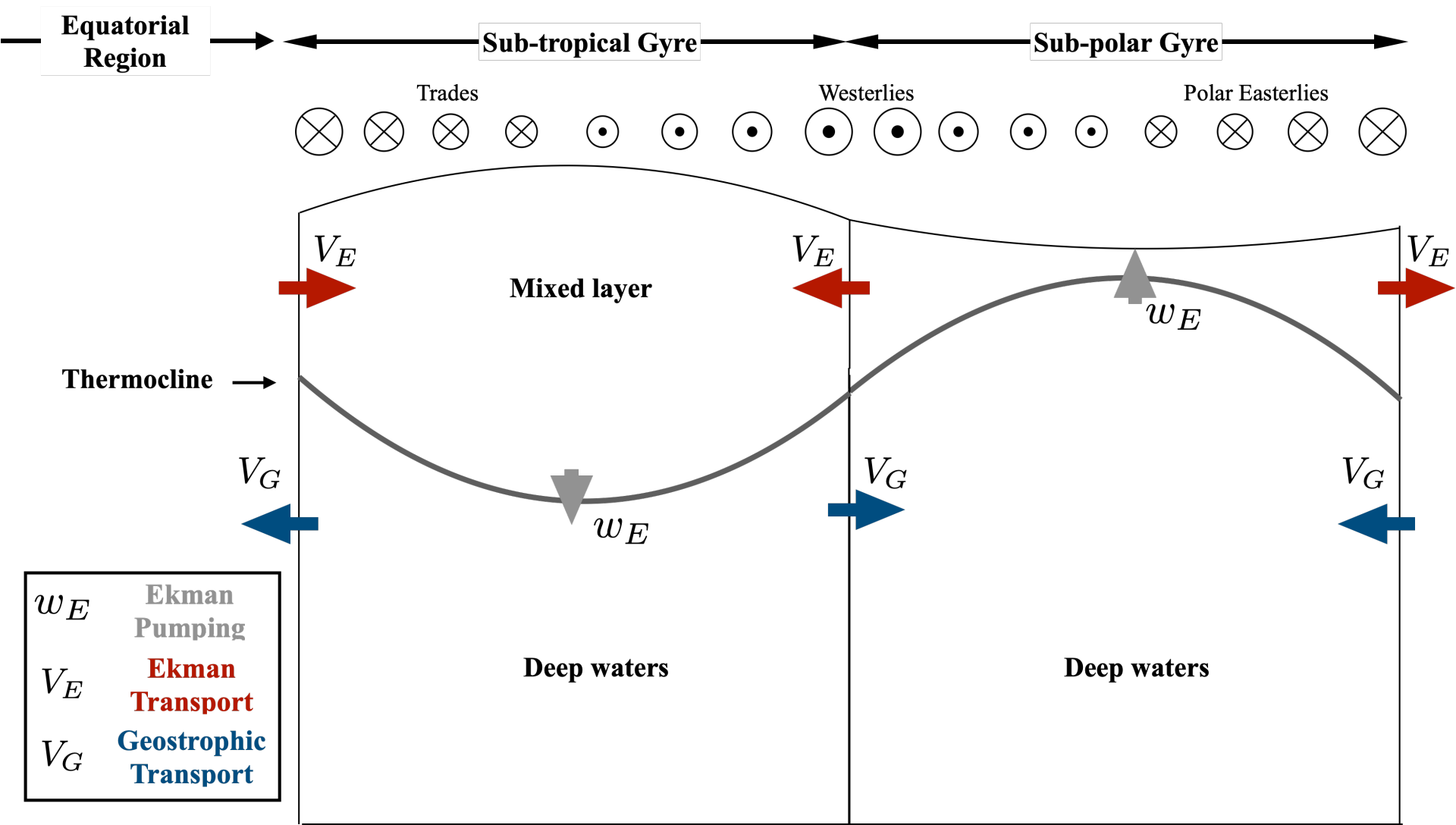
The Sverdrup Circulation and the zonal sea level variability



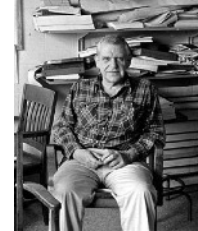
A top view of the wind-driven gyres



A side view of the wind-driven gyres



Ο **Stommel** πρότεινε μια πιο πλήρη σχέση για τη διατήρηση του στροβιλισμού, που περιλαμβάνει και όρο απομάκρυνσης του σχετικού στροφιλισμού ζ , της μορφής $-R\zeta$



Henry Stommel
1920-1992



Walter Munk
1917-

Interior

$$\beta U + \frac{\partial \tau^x}{\partial y} = 0$$

$$\leftarrow \beta U - R\zeta + \frac{\partial \tau^x}{\partial y} = 0 \rightarrow$$

WBL

$$\beta U - R\zeta = 0$$

Ο **Munk** πρότεινε μια πιο πλήρη διατύπωση για τον όρο απομάκρυνσης του σχετικού στροφιλισμού ζ , της μορφής: $A_H \nabla_H^2 \zeta$

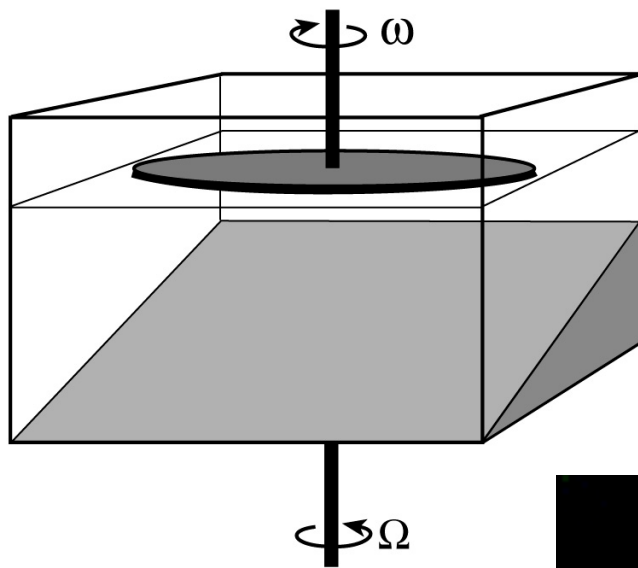
Interior

$$\beta U + \frac{\partial \tau^x}{\partial y} = 0$$

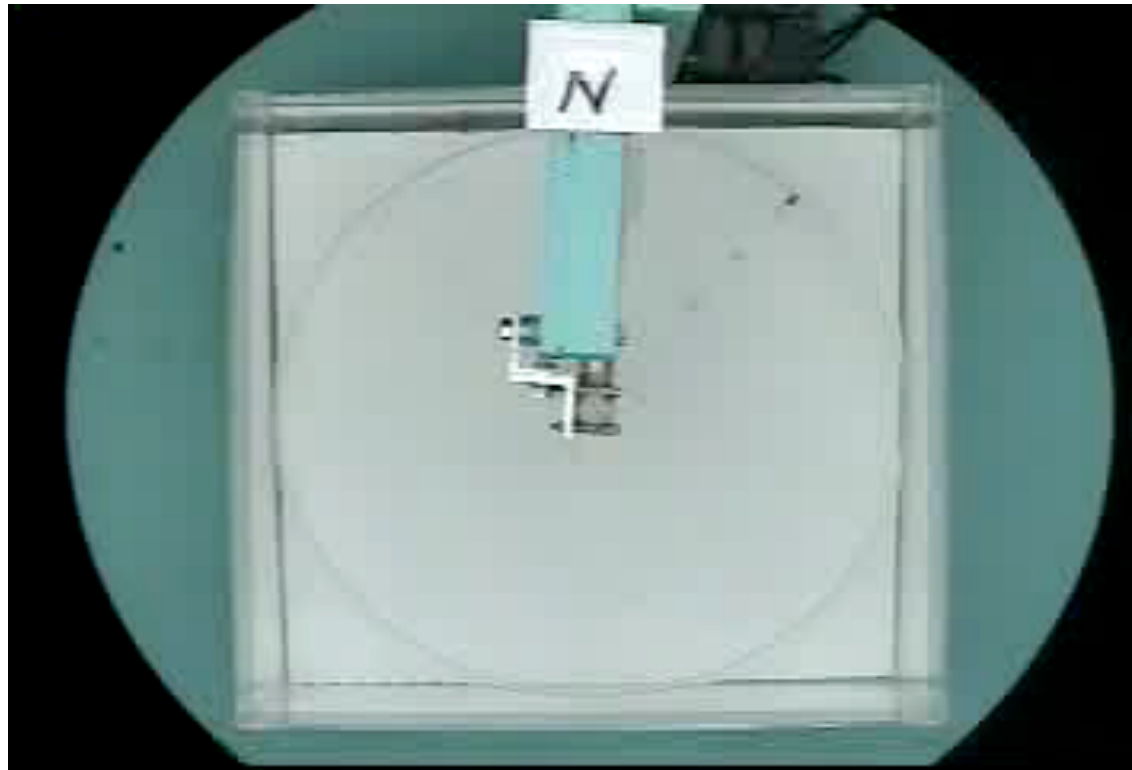
$$\leftarrow \beta U - A_H \nabla_H^2 \zeta + \frac{\partial \tau^x}{\partial y} = 0 \rightarrow$$

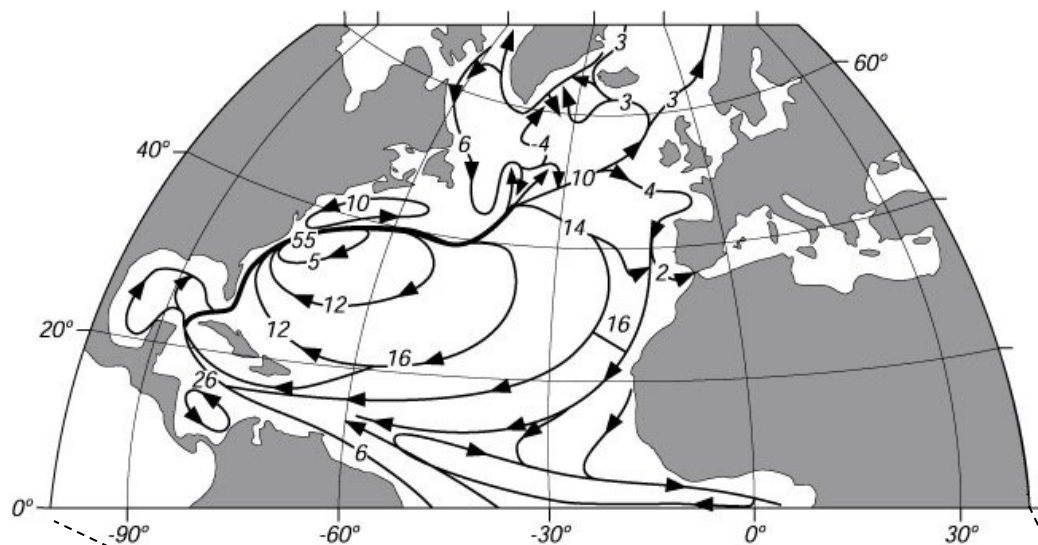
WBL

$$\beta U - A_H \nabla_H^2 \zeta = 0$$



Wind-driven gyre dynamics (the “Stommel Gyre”)





Stommel Model:

$$R\zeta \simeq \beta U$$

$$\Rightarrow R \frac{U}{L} \simeq \beta U$$

$$\Rightarrow L = O\left(\frac{R}{\beta}\right)$$

Munk Model:

$$A_H \nabla_H^2 \zeta \simeq \beta U$$

$$\Rightarrow A_H \frac{U}{L^3} \simeq \beta U$$

$$\Rightarrow L = O\left(\sqrt[3]{\frac{A_H}{\beta}}\right)$$

We can estimate L
or R/A_H .

