

$$\dot{C}_1(t) = C_2(t) \frac{i\Omega_R}{2} [e^{i\Omega t} + e^{-i\Omega t}]$$

$$\dot{C}_2(t) = C_1(t) \frac{i\Omega_R}{2} [e^{-i\Omega t} + e^{i\Omega t}]$$

πριν από ομαδοποίηση  $\frac{i\Omega_R \Omega}{1}$

**Α ΤΡΟΠΟΣ**

Αν υποθέσουμε πως  $e^{\dots} \sim 1$  δηλαδή  $\Delta \sim 0, \Sigma \sim 0$   
 δηλαδή πως θεωρούμε συντηρητικό ο όρος  $\frac{i\Omega_R}{2}$  εξ'ω από την τετραγωνική παρένθεση.  
 Τότε οι εξισώσεις γίνονται:

$$\dot{C}_1(t) = C_2(t) \frac{i\Omega_R}{2} \cdot 2 = i\Omega_R C_2(t)$$

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$$\ddot{C}_1(t) = i\Omega_R \dot{C}_2(t) = (i\Omega_R)^2 C_1(t)$$

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Δύο ΔΜ  $C_k(t) = U_k e^{i\lambda_k t} \Rightarrow \lambda_k^2 = \Omega_R^2$   
 $\lambda_k = \pm \Omega_R$

$\Omega_R$  (M) (N2)  $\Rightarrow$

$$A i\Omega_R e^{i\Omega_R t} + B (-i\Omega_R) e^{-i\Omega_R t} =$$

$$i\Omega_R (\Gamma e^{i\Omega_R t} + \Delta e^{-i\Omega_R t}) \xrightarrow{t=0}$$

$$C_1(t) = A e^{i\Omega_R t} + B e^{-i\Omega_R t} \quad (M)$$

$$C_2(t) = \Gamma e^{i\Omega_R t} + \Delta e^{-i\Omega_R t} \quad (N2)$$

Α.Σ.  $C_1(0) = 1, C_2(0) = 0$

$A - B = \Gamma + \Delta$  (3)

$1 = A + B$  (1)

$$\Gamma i\Omega_R e^{i\Omega_R t} + \Delta (-i\Omega_R) e^{-i\Omega_R t} =$$

$$i\Omega_R (A e^{i\Omega_R t} + B e^{-i\Omega_R t}) \xrightarrow{t=0}$$

$0 = \Gamma + \Delta \Rightarrow \Delta = -\Gamma$  (2)

$\Gamma - \Delta = A + B$  (4)

(1)(2)(3)(4)

$\Delta = -\Gamma \quad A = B \quad 2\Gamma = 2A \quad \Gamma = A \quad 1 = A + A = 2A$

$A = B = \Gamma = \frac{1}{2} = -\Delta$  (5)

$$C_1(t) = \frac{e^{i\Omega_R t} + e^{-i\Omega_R t}}{2} \Rightarrow C_1(t) = \cos(\Omega_R t) \Rightarrow P_1(t) = \cos^2(\Omega_R t) = \frac{1}{2} + \frac{1}{2} \cos(2\Omega_R t)$$

$$C_2(t) = \frac{e^{i\Omega_R t} - e^{-i\Omega_R t}}{2} \Rightarrow C_2(t) = i \sin(\Omega_R t) \Rightarrow P_2(t) = \sin^2(\Omega_R t) = \frac{1}{2} - \frac{1}{2} \cos(2\Omega_R t)$$

$\frac{1}{f} = T = \frac{2\pi}{2\Omega_R} = \frac{\pi}{\Omega_R} \quad A = 1$

$\dot{C}_1(t) = i\Omega_R C_2(t)$   
 $\dot{C}_2(t) = i\Omega_R C_1(t)$

$$\begin{bmatrix} \dot{C}_1(t) \\ \dot{C}_2(t) \end{bmatrix} = \begin{bmatrix} 0 & i\Omega_R \\ i\Omega_R & 0 \end{bmatrix} \begin{bmatrix} C_1(t) \\ C_2(t) \end{bmatrix}$$

$$\dot{\vec{x}}(t) = iA \vec{x}(t)$$

Össz  $\vec{x}(t) = \vec{u} e^{i\Omega t}$   
 $\dot{\vec{x}}(t) = i\Omega \vec{u} e^{i\Omega t}$

$$\dot{\vec{x}}(t) = iA \vec{x}(t) \Rightarrow i\Omega \vec{u} e^{i\Omega t} = iA \vec{u} e^{i\Omega t} \Rightarrow A\vec{u} = \Omega \vec{u}$$

$$(A - \Omega I)\vec{u} = \vec{0}$$

$$\det(A - \Omega I) = 0 \Rightarrow \begin{vmatrix} -\Omega & \Omega_R \\ \Omega_R & -\Omega \end{vmatrix} = 0 \Rightarrow \Omega^2 = \Omega_R^2 \Rightarrow \Omega = \pm \Omega_R$$

α  $\Omega_1 = -\Omega_R$

$$\begin{bmatrix} 0 & \Omega_R & \Omega_R \\ \Omega_R & 0 & \end{bmatrix} \begin{bmatrix} u_{11} \\ u_{21} \end{bmatrix} = -\Omega_R \begin{bmatrix} u_{11} \\ u_{21} \end{bmatrix} \Rightarrow \begin{cases} \Omega_R u_{21} = -\Omega_R u_{11} \\ \Omega_R u_{11} = -\Omega_R u_{21} \end{cases} \Rightarrow u_{21} = -u_{11}$$

$$\vec{u}_1 = \begin{bmatrix} c \\ -c \end{bmatrix} \quad |\vec{u}_1|^2 = 1 \Rightarrow 2|c|^2 = 1 \Rightarrow |c|^2 = 1/2 \quad (u_{21} = -u_{11})$$

n.x.  $c = \frac{1}{\sqrt{2}}$

$$\vec{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

β  $\Omega_2 = \Omega_R$

$$\begin{bmatrix} 0 & \Omega_R \\ \Omega_R & 0 \end{bmatrix} \begin{bmatrix} u_{12} \\ u_{22} \end{bmatrix} = \Omega_R \begin{bmatrix} u_{12} \\ u_{22} \end{bmatrix} \Rightarrow \begin{cases} \Omega_R u_{22} = \Omega_R u_{12} \\ \Omega_R u_{12} = \Omega_R u_{22} \end{cases} \Rightarrow u_{12} = u_{22}$$

$$\vec{u}_2 = \begin{bmatrix} c \\ c \end{bmatrix} \quad |\vec{u}_2|^2 = 1 \Rightarrow 2|c|^2 = 1 \Rightarrow |c|^2 = 1/2 \Rightarrow \text{n.x. } c = \frac{1}{\sqrt{2}}$$

$$\vec{u}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Γενική λύση

$$\vec{x}(t) = \sigma_1 \vec{u}_1 e^{i\Omega_1 t} + \sigma_2 \vec{u}_2 e^{i\Omega_2 t}$$

$$\begin{bmatrix} C_1(t) \\ C_2(t) \end{bmatrix} = \sigma_1 \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-i\Omega_R t} + \sigma_2 \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{i\Omega_R t}$$

A.Σ.  $C_1(0) = 1$      $C_2(0) = 0$

$$1 = \frac{\sigma_1}{\sqrt{2}} + \frac{\sigma_2}{\sqrt{2}}$$

$$0 = -\frac{\sigma_1}{\sqrt{2}} + \frac{\sigma_2}{\sqrt{2}} \Rightarrow \sigma_1 = \sigma_2 := \sigma$$

$$1 = 2 \frac{\sigma}{\sqrt{2}} \Rightarrow \sigma = \frac{\sqrt{2}}{2}$$

$$\sigma = \frac{\sqrt{2}}{2}$$

$$\frac{4\sigma_2 - \sigma_1}{3}$$

$$C_1(t) = \frac{1}{2} e^{-i\Omega t} + \frac{1}{2} e^{i\Omega t}$$

$$C_1(t) = \frac{e^{-i\Omega t} + e^{i\Omega t}}{2} \Rightarrow$$

$$C_2(t) = -\frac{1}{2} e^{-i\Omega t} + \frac{1}{2} e^{i\Omega t}$$

$$C_2(t) = \frac{e^{i\Omega t} - e^{-i\Omega t}}{2} \Rightarrow$$

$$C_1(t) = \cos(\Omega t) \Rightarrow P_1(t) = \cos^2(\Omega t) = \frac{1}{2} + \frac{1}{2} \cos(2\Omega t)$$

$$C_2(t) = i \sin(\Omega t) \Rightarrow P_2(t) = \sin^2(\Omega t) = \frac{1}{2} - \frac{1}{2} \cos(2\Omega t)$$

$$\frac{1}{f} = T = \frac{2\pi}{\Omega} = \frac{\pi}{\Omega} \quad A = 1$$