

## Example

Let  $X_1, \dots, X_n$  r.s of  $N(\mu, \sigma^2)$ , where  $\mu, \sigma^2$  are unknown.  
Let  $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$  u.e. of  $\sigma^2$ . Find the value of the constant  $c$  so that  $c \cdot S^2$  is a minimal-MSF estimator of  $\theta$ .

### Solution

The MSF of an estimator  $Y$  of  $\theta$  is:

$$\text{MSF} = E[(Y - \theta)^2] = V(Y) + b^2(\theta), \quad \text{where } b(\theta) = E(Y) - \theta$$

We are looking for  $c$  so that  $E[(cS^2 - \sigma^2)^2]$  is minimal.

$$\begin{aligned} \text{It is: } E[(cS^2 - \sigma^2)^2] &= V(cS^2) + E[(cS^2 - \sigma^2)^2] = \\ &= c^2 V(S^2) + (c\sigma^2 - \sigma^2)^2 = c^2 V(S^2) + \sigma^4 (c-1)^2 \quad (1) \end{aligned}$$

We know that  $\frac{(n-1)S^2}{\sigma^2} \sim \chi_{n-1}^2$

$$\begin{aligned} \text{So } V\left[\frac{(n-1)S^2}{\sigma^2}\right] &= 2(n-1) \Rightarrow \frac{(n-1)^2}{\sigma^4} V(S^2) = 2(n-1) \Rightarrow \\ \Rightarrow V(S^2) &= \frac{2\sigma^4}{n-1} \end{aligned}$$

$$\text{Hence, (1)} \Rightarrow E[(cS^2 - \sigma^2)^2] = c^2 \cdot \frac{2\sigma^4}{n-1} + \sigma^4 (c-1)^2$$

To find the minimum we set the derivative (with respect

$$\text{to } c) \text{ equal to zero: } 2c \frac{2\sigma^4}{n-1} + 2\sigma^4 (c-1) = 0 \Rightarrow$$

$$\Rightarrow 2c + (c-1)(n-1) = 0 \Rightarrow c = \frac{n-1}{n+1}$$

The 2nd derivative is  $> 0$ , hence the statistic  $\frac{n-1}{n+1} \cdot S^2 = \frac{1}{n+1} \sum_{i=1}^n (X_i - \bar{X})^2$  is the minimal-MSF estimator of  $\sigma^2$ .

## Reminder

R-B Theorem: Let  $U=U(\underline{X})$  u.e. of  $\theta$  and  $T=T(\underline{X})$  sufficient, then  $W=f[U|T]$  u.e. of  $\theta$  and  $V(W) \leq V(U)$

## Generalization of R-B

Let  $X_1, \dots, X_n$  r.s. of  $f(x; \theta)$ . If  $U = U(\underline{x})$  u.e. of  $g(\theta)$  and  $T(\underline{x})$  sufficient statistic for  $\theta$ , then the statistic  $\delta = \delta(\underline{x}) = \psi(T(\underline{x})) = E[U | T]$  is an u.e. of  $g(\theta)$  and  $V(\delta) \leq V(U)$

## Theorem (Lehmann-Scheffé)

With the same assumptions as the R-B Theorem and the assumption that  $T = T(\underline{x})$  is also complete, we have that  $\delta(\underline{x}) = \psi(T(\underline{x})) = E[U | T]$  is m.v.u.e. of  $g(\theta)$

### Proof

Let  $\psi_0(t)$  and  $\psi_1(t)$  functions of the sufficient and complete statistic  $T$  and  $\psi_0(T), \psi_1(T)$  u.e. of  $g(\theta)$ . Then:

$$E[\psi_0(T)] = g(\theta) = E[\psi_1(T)] \Rightarrow E[\psi_0(T) - \psi_1(T)] = 0 \quad \forall \theta \in \Theta$$

$$\xrightarrow{T \text{ complete}} \psi_0(t) - \psi_1(t) = 0 \quad \forall t \Rightarrow \psi_0(t) = \psi_1(t) \quad \forall t$$

## Proposition

If  $T = T(\underline{x})$  sufficient and complete statistic for  $\theta$  and  $\psi_1(T)$  u.e. of  $g(\theta)$ , then  $\psi_1(T)$  is m.v.u.e. of  $g(\theta)$

### Proof

From L-S Theorem we get a function  $\psi(T) = E[U | T]$  that is an u.e. of  $g(\theta)$  and has minimal variance among the estimators of  $g(\theta)$ . Then:

$$E[\psi(T) - \psi_1(T)] = 0 \text{ and since } T \text{ is complete } \psi(T) = \psi_1(T)$$

hence,  $\psi_1(T)$  is m.v.u.e. of  $g(\theta)$ .

## Example

Let  $X_1, \dots, X_n$  r.s of  $N(\theta, 1)$ .

a) Find m.v.u.e of  $\theta$

b) Prove that  $\bar{X}^2 - \frac{1}{v}$  is m.v.u.e. of  $\theta^2$

## Solution

a) We are looking for a sufficient and complete statistic for  $\theta$ . We have previously proven that  $T = T(\underline{X}) = \sum_{i=1}^n X_i$  is sufficient and complete for  $\theta$ . We have also proven that  $E[\bar{X}] = E[X] = \theta$ . Hence,  $E[\bar{X}] = E\left[\frac{\sum X_i}{v}\right] = E\left[\frac{T}{v}\right] = \theta$ , so from L-S theorem  $\psi(T) = \frac{T}{v}$  is m.v.u.e. of  $\theta$  (as it is an u.e. of  $\theta$  and a function of the sufficient and complete  $T$ ).

b)  $T = \sum_{i=1}^n X_i$  is sufficient and complete for  $\theta$  so, we just have to prove that  $\bar{X}^2 - \frac{1}{v}$  is an u.e. of  $g(\theta) = \theta^2$  (because it is a function of  $T$ )

$$\begin{aligned} E\left[\bar{X}^2 - \frac{1}{v}\right] &= E[\bar{X}^2] - \frac{1}{v} = V(\bar{X}) + E[\bar{X}]^2 - \frac{1}{v} = \frac{1}{v} \cdot V(X) + \theta^2 - \frac{1}{v} \\ &= \frac{1}{v} \cdot 1 + \theta^2 - \frac{1}{v} = \theta^2 \end{aligned}$$

Finally,  $\bar{X}^2 - \frac{1}{v}$  is m.v.u.e. of  $\theta^2$ .

Alternatively:  $X_i \sim N(\theta, 1) \Rightarrow \bar{X} \sim N(\theta, 1/v) \Rightarrow$   
 $\Rightarrow \frac{\bar{X} - \theta}{\sqrt{1/v}} \sim N(0, 1) \Rightarrow v(\bar{X} - \theta)^2 \sim \chi_1^2$

$$\begin{aligned} E[v(\bar{X} - \theta)^2] &= 1 \Rightarrow E[(\bar{X} - \theta)^2] = \frac{1}{v} \Rightarrow \\ \Rightarrow E[\bar{X}^2 + \theta^2 - 2\theta\bar{X}] &= \frac{1}{v} \Rightarrow E[\bar{X}^2] + \theta^2 - 2\theta E[\bar{X}] = \frac{1}{v} \\ \Rightarrow E[\bar{X}^2] + \theta^2 - 2\theta \cdot \theta &= \frac{1}{v} \Rightarrow E[\bar{X}^2 - \frac{1}{v}] = \theta^2 \end{aligned}$$

## Example

Let  $X_1, \dots, X_n$  r.s. of  $U(0, \theta)$ .

a) Find m.v.u.e of  $g(\theta) = \theta^k$

b) Find m.v.u.e of  $E[X]$  and  $V(X)$

### Solution

a)  $f(x; \theta) = \frac{1}{\theta} \cdot \mathbb{I}(0 < x < \theta)$ , where  $\mathbb{I}(0 < x < \theta) = \begin{cases} 1, & 0 < x < \theta \\ 0, & \text{otherwise} \end{cases}$

We have proven that  $T = X_{(n)} = \max\{X_i\}$

is a sufficient statistic for  $\theta$ . For completeness we need  $E[g(T)] = 0 \quad \forall \theta > 0 \Rightarrow g(t) = 0 \quad \forall t$  for all functions  $g(T)$ .

$F_T(t) = P(T \leq t) = P(X_{(n)} \leq t) = P(X_1, \dots, X_n \leq t) = \prod_{i=1}^n P(X_i \leq t) = [F_X(t)]^n$

but  $X \sim U(0, \theta)$  so  $F_X(t) = \int_0^t \frac{1}{\theta} dx = \frac{t}{\theta}$ .

Hence,  $F_T(t) = \left(\frac{t}{\theta}\right)^n \xrightarrow{\partial/\partial t} f_T(t) = \frac{nt^{n-1}}{\theta^n}, \quad t \in (0, \theta)$

Then:  $E[g(T)] = 0 \quad \forall \theta > 0 \Rightarrow \int_0^\theta g(t) f_T(t) dt = 0 \quad \forall \theta > 0 \Rightarrow$

$\xrightarrow{\partial/\partial \theta} \int_0^\theta g(t) \frac{nt^{n-1}}{\theta^n} dt = 0 \quad \forall \theta > 0 \Rightarrow \int_0^\theta g(t) t^{n-1} dt = 0 \quad \forall \theta > 0 \Rightarrow$

$\Rightarrow g(\theta) \cdot \theta^{n-1} = 0 \quad \forall \theta > 0 \Rightarrow g(\theta) = 0 \quad \forall \theta > 0 \Rightarrow g(t) = 0 \quad \forall t \in (0, \theta)$

Finally,  $T = X_{(n)}$  is complete.

To find a m.v.u.e of  $g(\theta) = \theta^k$  we just need to find a function  $\psi(T) : E[\psi(T)] = \theta^k \quad \forall \theta > 0$ .

$E[\psi(T)] = \theta^k \Rightarrow \int_0^\theta \psi(t) f_T(t) dt = \theta^k \Rightarrow \int_0^\theta \psi(t) \frac{nt^{n-1}}{\theta^n} dt = \theta^k$

$\Rightarrow \int_0^\theta \psi(t) t^{n-1} dt = \frac{\theta^{k+n}}{n} \xrightarrow{\partial/\partial \theta} \psi(\theta) \cdot \theta^{n-1} = \frac{n+k}{n} \cdot \theta^{n+k-1} \quad \forall \theta > 0 \Rightarrow$

$\Rightarrow \psi(\theta) = \frac{n+k}{n} \cdot \theta^k$

Hence, the m.v.u.e of  $\theta^k$  is  $\psi(T) = \frac{n+k}{n} \cdot \theta^k$

b) Since  $X \sim U(0, \theta)$ , it is  $E[X] = \frac{\theta}{2}$  and  $V(X) = \frac{\theta^2}{12}$

We just proved that  $\psi(T) = \frac{n+k}{n} \cdot \theta^k$  m.v.u.e of  $\theta^k$

$$\text{For } k=1: f\left[\frac{v+1}{v} \cdot T\right] = \theta \Rightarrow f\left[\frac{v+1}{2v} \cdot T\right] = \frac{\theta}{2} \text{ so } \psi_2(T) = \frac{v+1}{2v} \cdot T$$

m.v.u.e of  $f(X)$

$$\text{For } k=2: f\left[\frac{v+2}{v} T^2\right] = \theta^2 \Rightarrow f\left[\frac{v+2}{12v} T^2\right] = \frac{\theta^2}{12}$$

so  $\psi_3(T) = \frac{v+2}{12v} T^2$  m.v.u.e of  $V(X)$