

# Clustering algorithms

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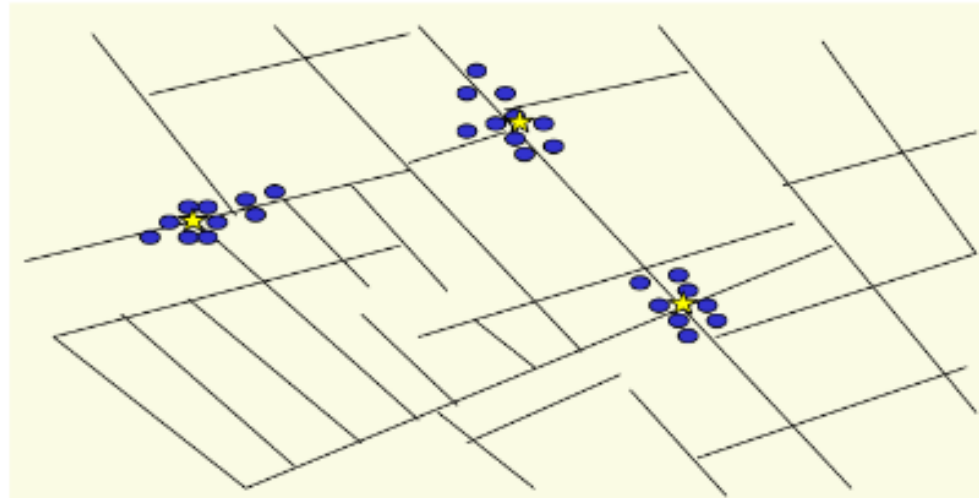
## Unit 4

- Cost function optimization clustering algorithms: The hard clustering case

# Clustering: A historic example(\*)

Dr John Snow plotted the **location** of **cholera deaths** on a **map** during an outbreak at London in the 1850s

The **locations** were **clustered** around certain intersections where there were **polluted wells!!!**



## Questions:

- Which are the **entities** and how they are **represented**?
- Which **dissimilarity measure** could be used?
- What is the **form** of the **resulted clusters**?
- What kind of clusters should be able to reveal the adopted **clustering criterion**?

# Clustering algorithms

## Number of possible clusterings

Let  $X = \{x_1, x_2, \dots, x_N\}$  be a set of data points.

**Question:** In how many ways the  $N$  points of  $X$  can be assigned into  $m$  groups?

**Answer:** 
$$S(N, m) = \frac{1}{m!} \sum_{i=0}^m (-1)^{m-i} \binom{m}{i} i^N$$

### Examples:

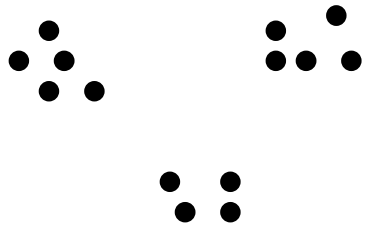
- $S(15, 3) = 2,375,101$
- $S(20, 4) = 45,232,115,901$
- $S(25, 8) = 690,223,721,118,368,580$
- $S(100, 5) \approx 10^{68}!!$

**NOTE:** The above calculations are for fixed  $m$ . If this varies, then we have to enumerate **all clusterings**, for **all possible** values of  $m$ !!

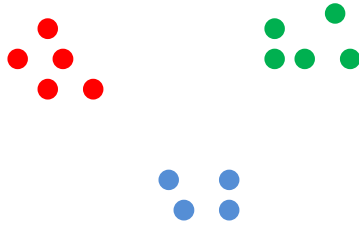
⇒

**Evaluating** all possible clusterings is **impractical** even for **moderate values** of  $N$ .

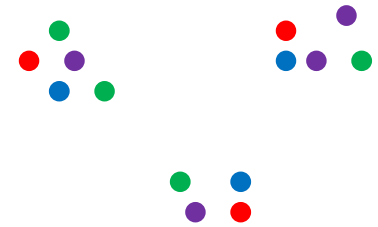
# Clustering algorithms



Data set



A "sensible" clustering



A "less sensible" clustering

- **Clustering algorithms** may be **viewed** as **schemes** that provide us with *sensible clusterings* by considering only *a small fraction* of all possible partitions of  $X$ .
- This *fraction* **depends on** the adopted **criteria**.
- Thus a **clustering algorithm** is a **learning procedure** that tries to **identify clusters** formed by the data vectors, **in accordance to the adopted criteria**.

# Clustering algorithms

## Major categories of clustering algorithms

A **vast amount** of **algorithms** **exists** based on **very diverse criteria**  
⇒ **Strict categorization** is extremely **difficult** (rather **impossible**).

## A rough categorization:

- **Sequential**: A **single clustering** is produced. **One** or **few sequential passes** on the data.
- **Hierarchical**: A **sequence** of (nested) **clusterings** is produced.
  - Agglomerative**
    - Matrix theory
    - Graph theory
  - Divisive**
  - Combinations** of the above (e.g., the Chameleon algorithm.)

# Clustering algorithms

## Major categories of clustering algorithms

### A rough categorization:

#### Cost function optimization.

- For most of the cases a *single clustering* is obtained.
- They can be further **categorized** through the notion of “**belongness**”.  
**Hard clustering** (each **point belongs** exclusively to **a** single **cluster**):

- Basic hard clustering algorithms (e.g.,  $k$ -means)
- $k$ -medoids algorithms
- Mixture decomposition
- Branch and bound
- Simulated annealing
- Deterministic annealing
- Boundary detection
- Mode seeking
- Genetic clustering algorithms

**Probabilistic clustering** (a hard clustering case where probabilistic framework is utilized)

**Fuzzy clustering** (each **point belongs** to **more** than one **clusters** simultaneously).

**Possibilistic clustering** (it is based on the notion of the “*degree of compatibility*” of a point with a cluster).

# Clustering algorithms

## Major categories of clustering algorithms

### A rough categorization:

#### Other.

- Algorithms based on **graph theory** (e.g., Spectral clustering, Minimum Spanning Tree, regions of influence, directed trees).
- **Density-based** algorithms.
- **Competitive learning** algorithms (basic competitive learning scheme, Kohonen self organizing maps).
- **Subspace clustering** algorithms.
- **Ensemble of clusterings**
- **Kernel-based** methods.

# Sequential clustering algorithms

The common traits shared by the sequential clustering algorithms are:

- One or very **few passes** on the data are **required**.
- The number of clusters  $m$  is **not known a-priori**, except (possibly) an **upper bound**,  $q$ .
- The **clusters** are **defined** with the **aid** of
  - ✓ An appropriately defined distance  $d(x, C)$  of a point from a cluster.
  - ✓ A threshold  $\Theta$  associated with the distance.

# Sequential clustering algorithms

## Basic Sequential Clustering Algorithm Scheme (BSAS)

- $m = 1 \setminus \{\text{number of clusters}\}$

- $C_m = \{\mathbf{x}_1\}$

- **For**  $i = 2$  to  $N$

- **Find**  $C_k$ :  $d(\mathbf{x}_i, C_k) = \min_{1 \leq j \leq m} d(\mathbf{x}_i, C_j)$

- **If**  $(d(\mathbf{x}_i, C_k) > \theta)$  AND  $(m < q)$  then

- $m = m + 1$

- $C_m = \{\mathbf{x}_i\}$

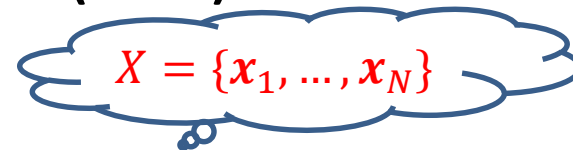
- **Else**

- $C_k = C_k \cup \{\mathbf{x}_i\}$

- Where necessary, update representatives (\*)

- **End** {if}

- **End** {for}



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(\*) When the mean vector  $\mathbf{m}_C$  is used as representative of the cluster  $C$  with  $n_C$  elements, the updating in the light of a new vector  $\mathbf{x}$  becomes

$$\mathbf{m}_C^{new} = (n_C \mathbf{m}_C^{old} + \mathbf{x}) / (n_C + 1)$$

# Sequential clustering algorithms

## Basic Sequential Clustering Algorithm Scheme (BSAS)

### Remarks:

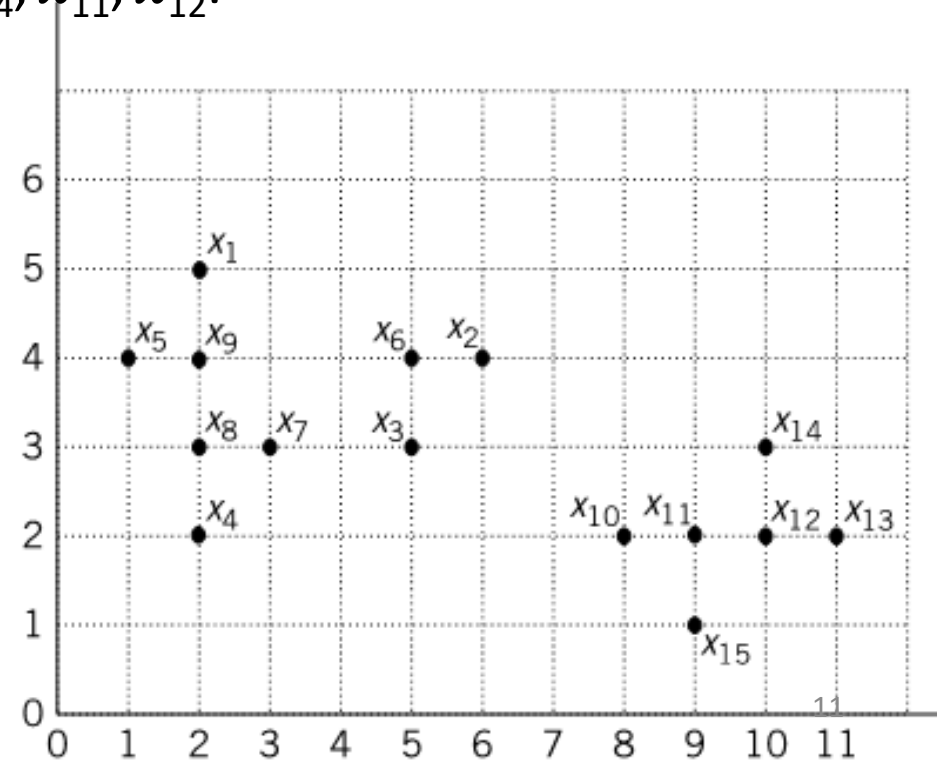
- The **order of presentation of the data** in the algorithm plays important role in the clustering results. **Different order of presentation may lead to totally different clustering results**, in terms of the **number of clusters** as well as the **clusters themselves**.
- The **clustering results** depend on the choice of the value of  $\theta$ .
- In BSAS the **decision** for a vector  $\mathbf{x}$  is **reached prior** to the **final cluster formation**.
- **BSAS** perform a **single pass** on the data. Its complexity is  $O(N)$  (when point representatives are used).
- If clusters are represented by **point representatives**, **compact clusters** are favored.

# Sequential clustering algorithms

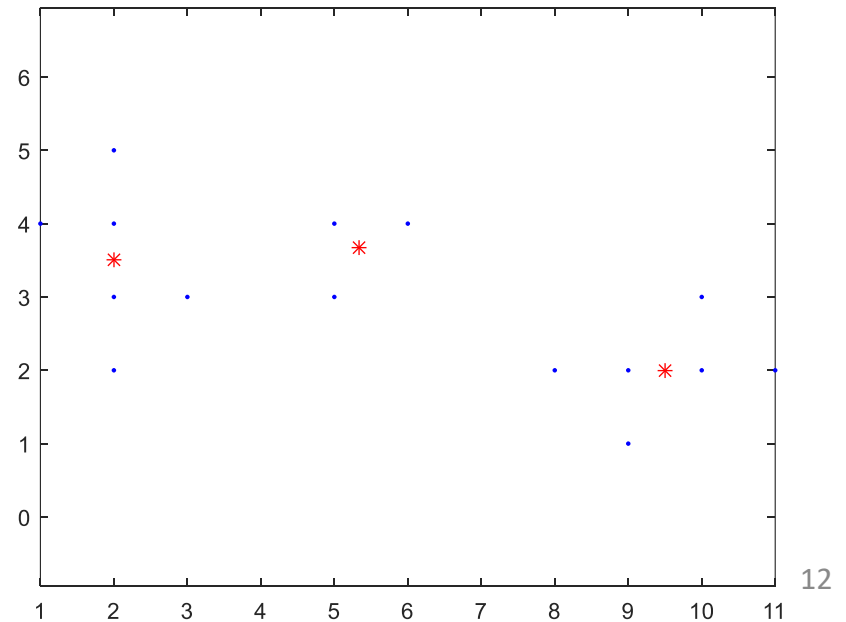
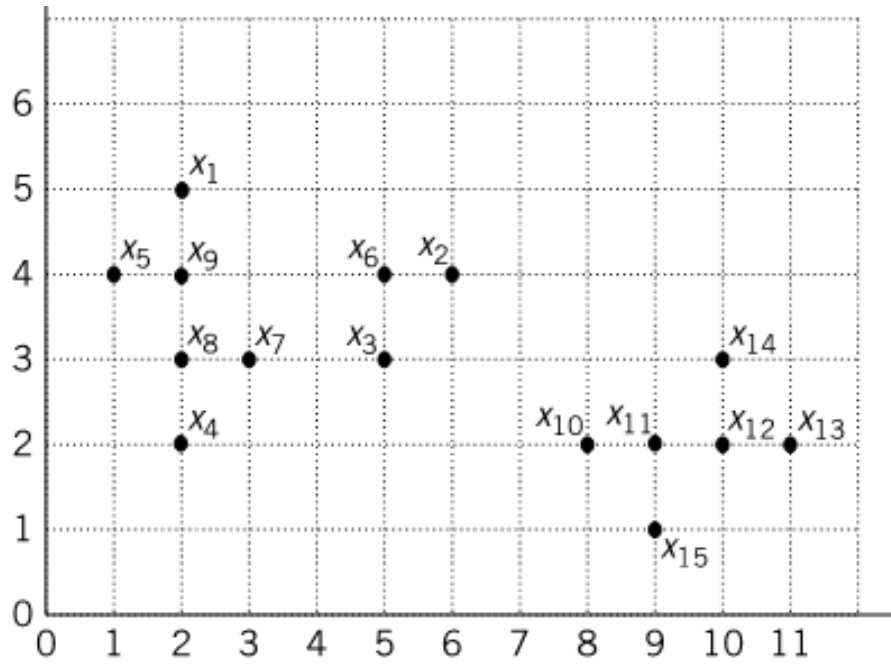
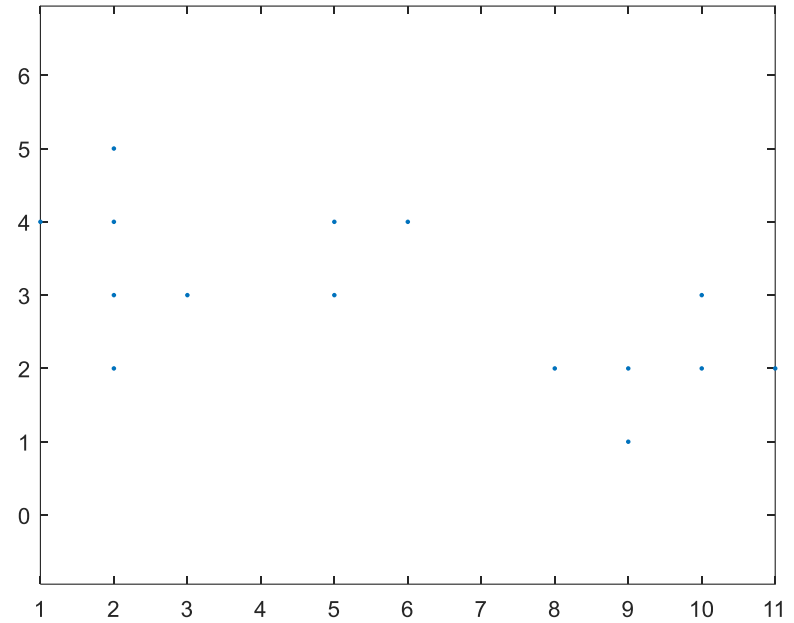
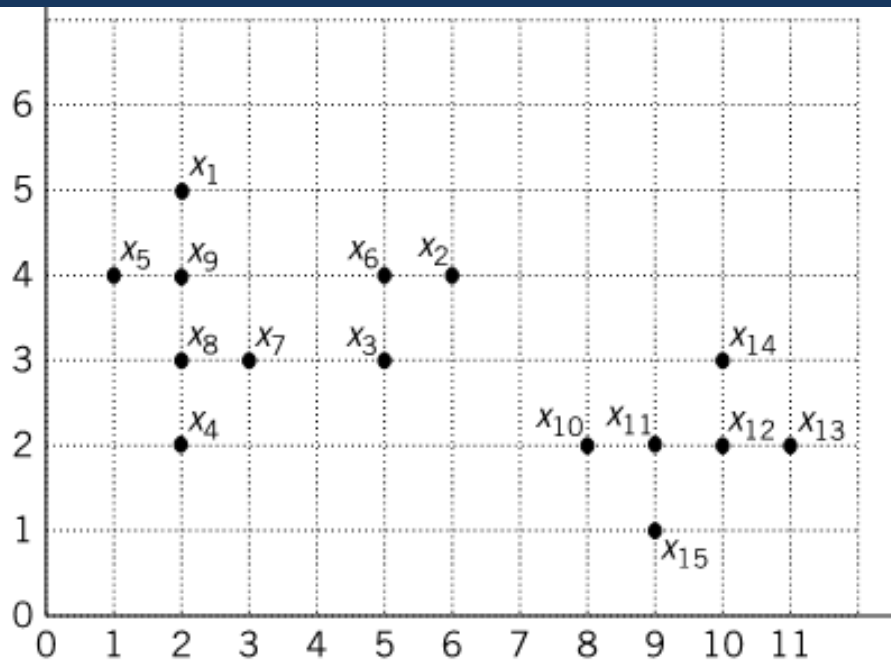
## Example in MATLAB 1:

Consider the data vectors depicted in the figure below and perform a “visual clustering” on it.

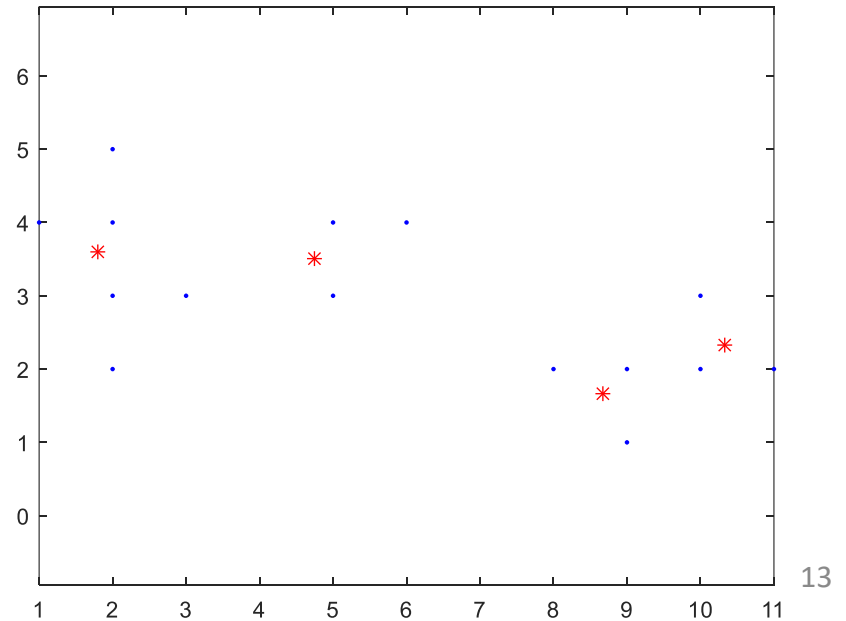
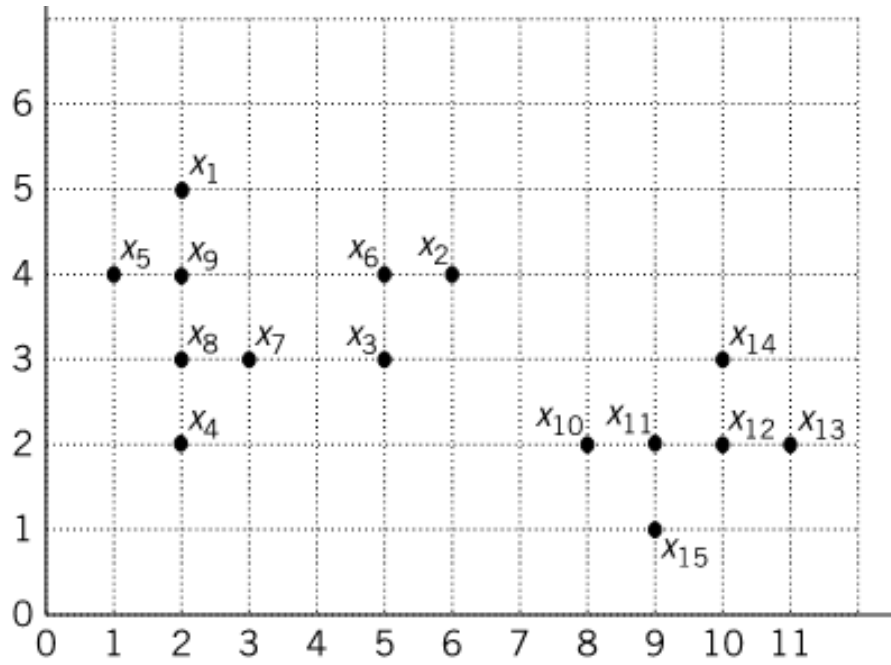
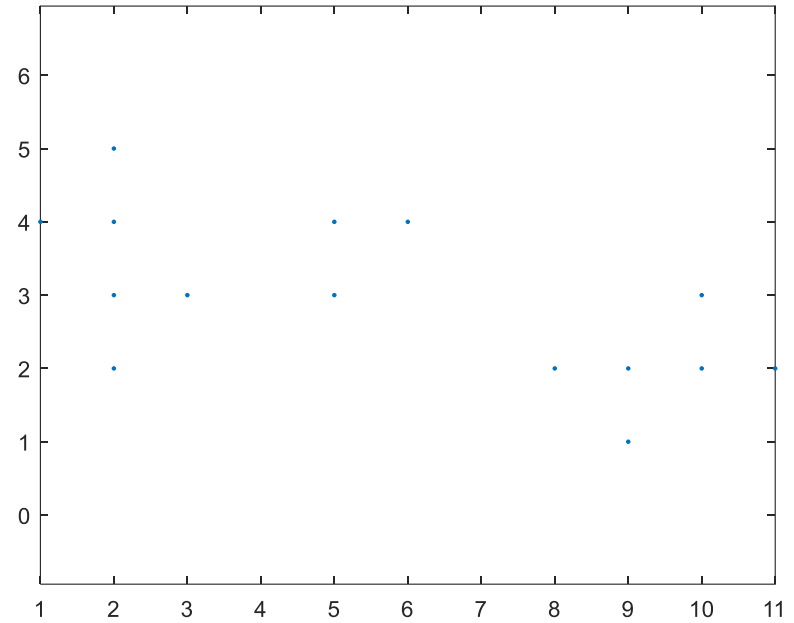
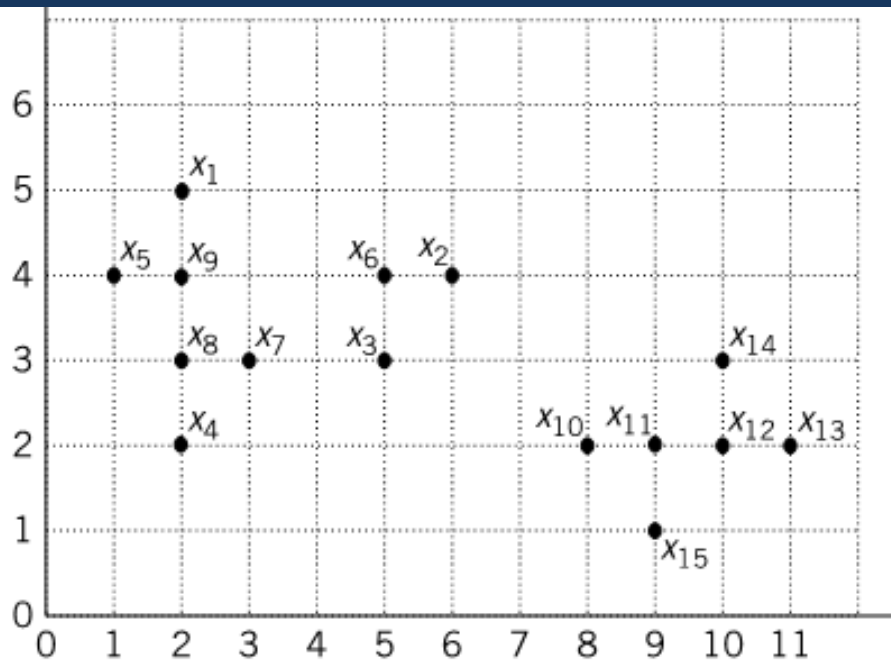
1. Apply the BSAS algorithm on  $X$ , presenting its elements in the order  $x_8, x_6, x_{11}, x_1, x_5, x_2, x_3, x_4, x_7, x_{10}, x_9, x_{12}, x_{13}, x_{14}, x_{15}$ , for  $\theta = 2.5$  and  $q = 15$ .
2. Repeat step 1, now with the order of presentation to the algorithm as  $x_7, x_3, x_1, x_5, x_9, x_6, x_8, x_4, x_2, x_{10}, x_{15}, x_{13}, x_{14}, x_{11}, x_{12}$ .
3. Repeat step 1, now with  $\theta = 1.4$ .
4. Repeat step 1, now with  $q = 2$ .



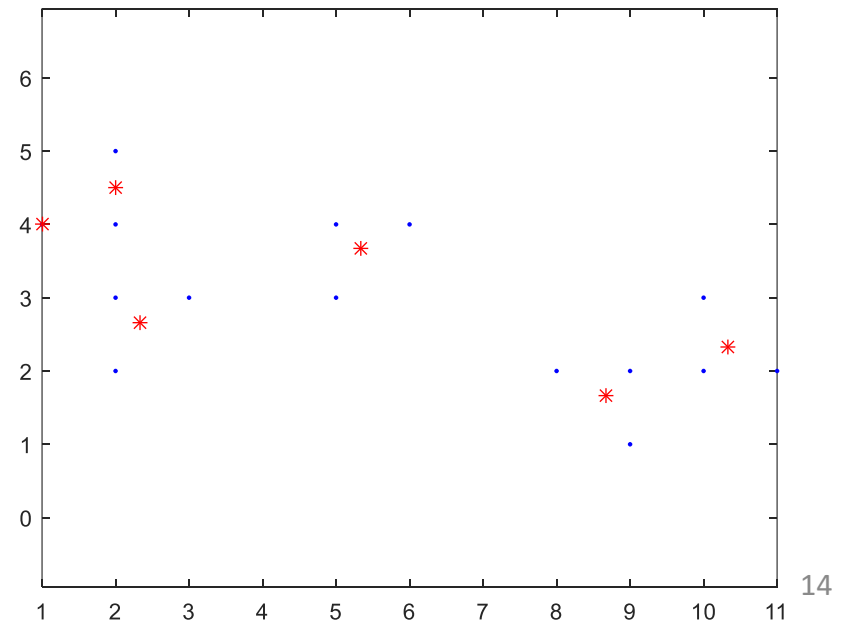
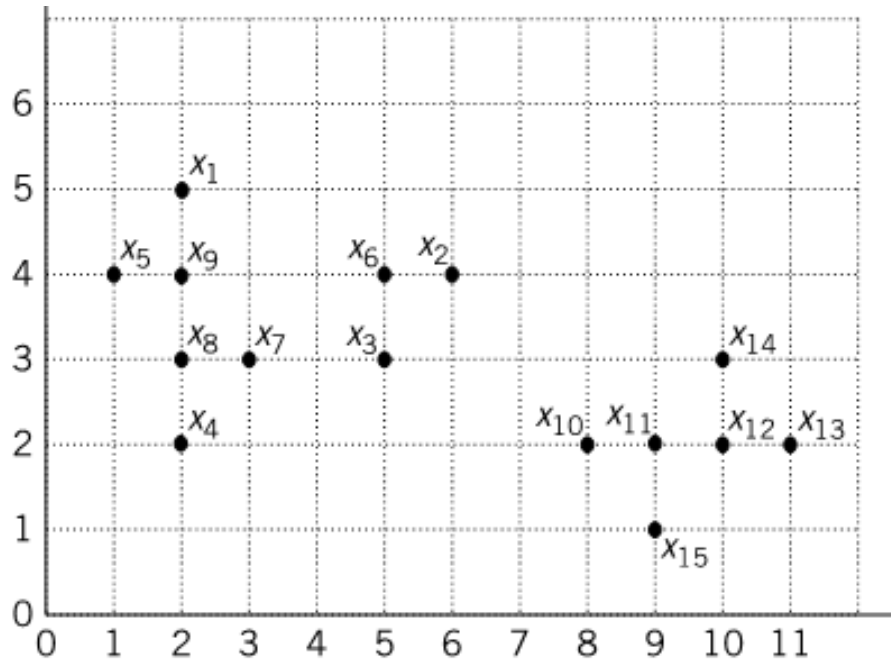
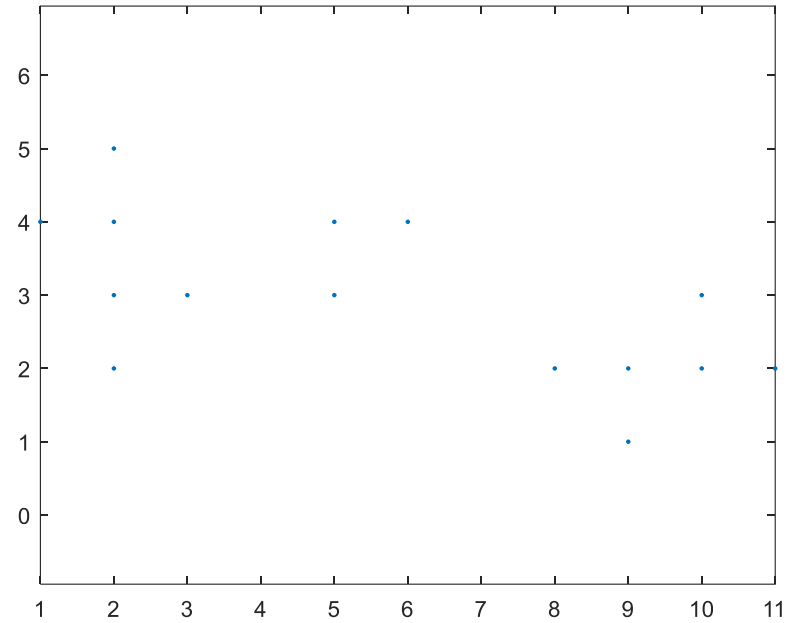
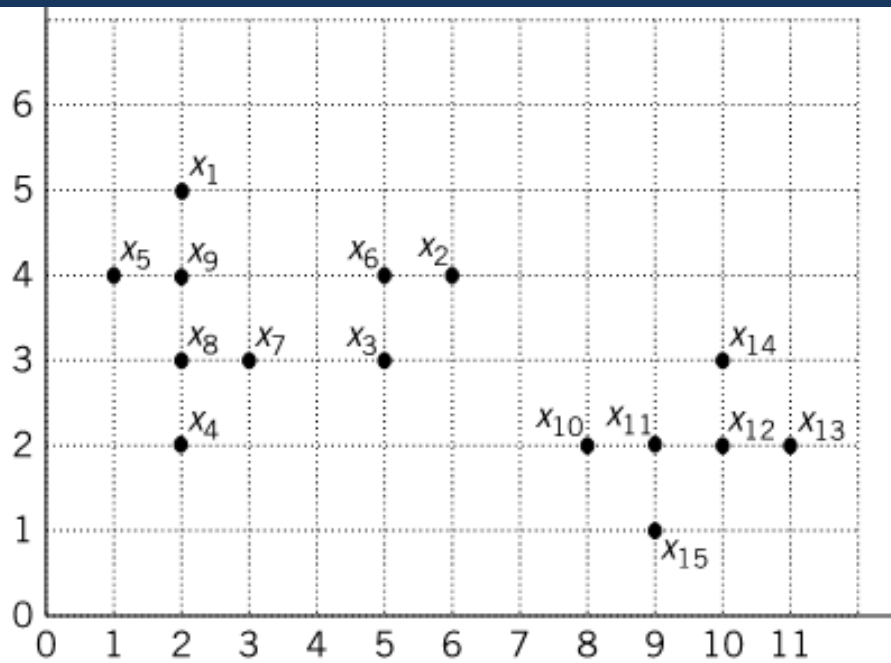
# Sequential clustering algorithms



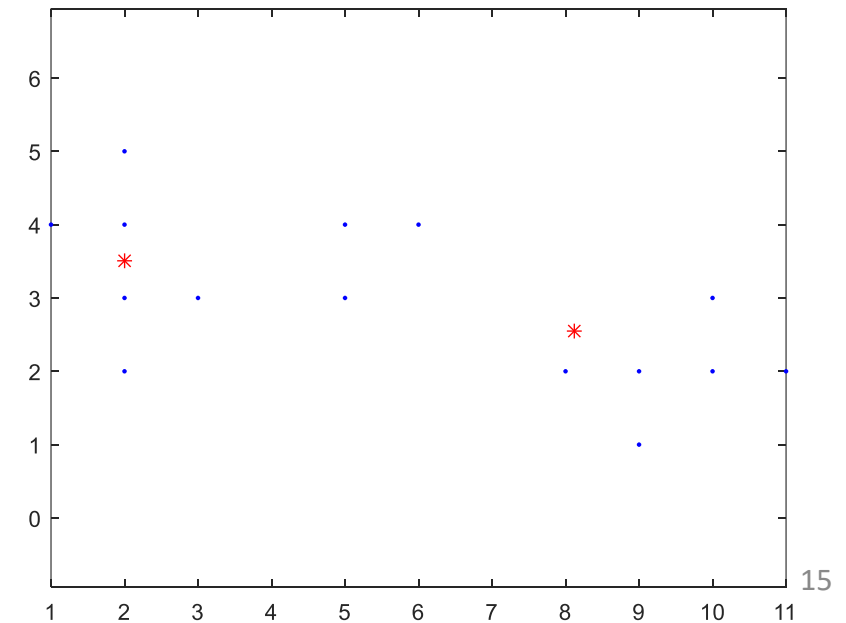
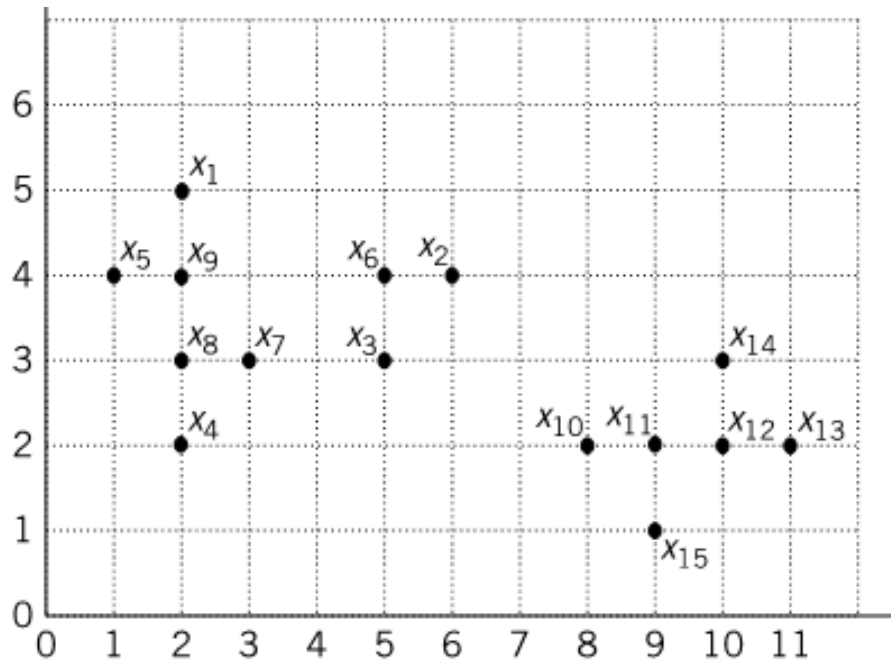
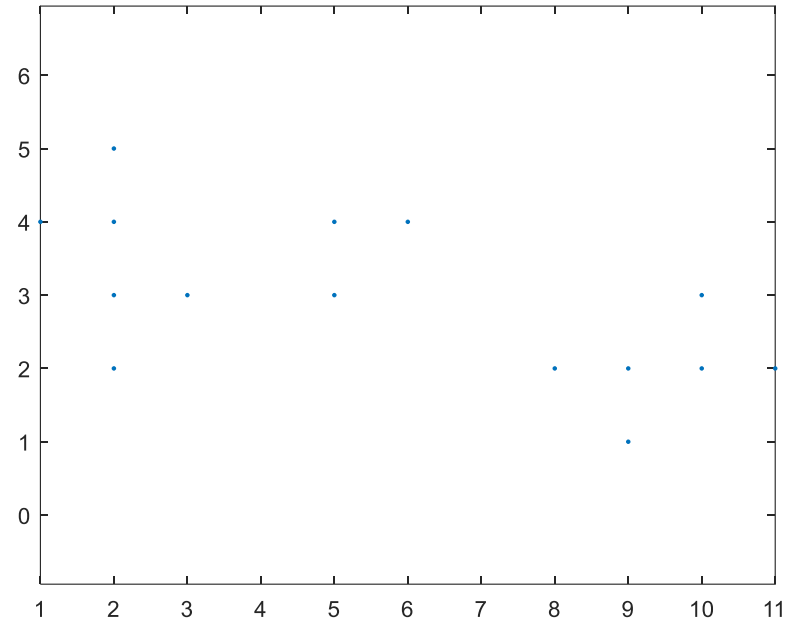
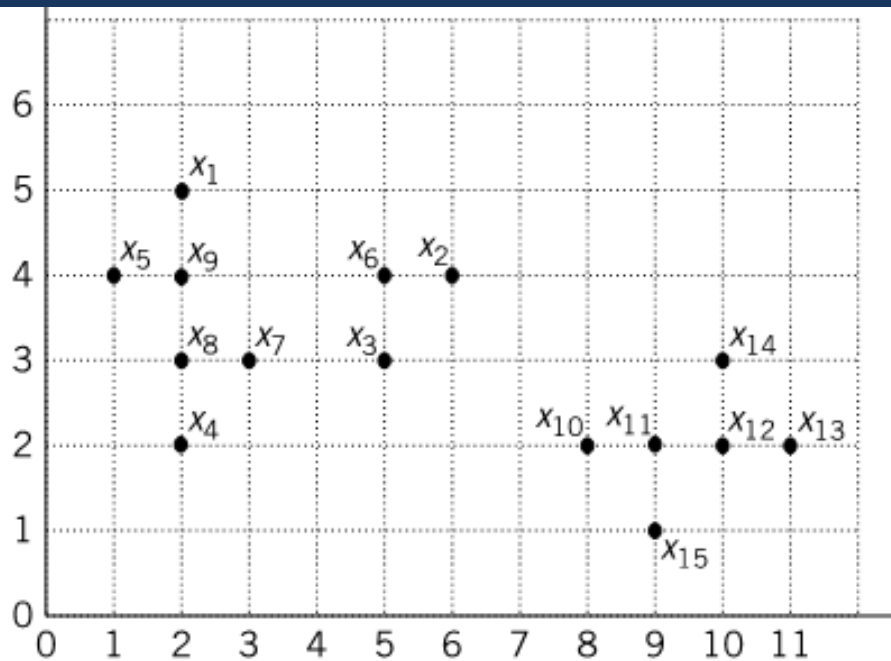
# Sequential clustering algorithms



# Sequential clustering algorithms



# Sequential clustering algorithms



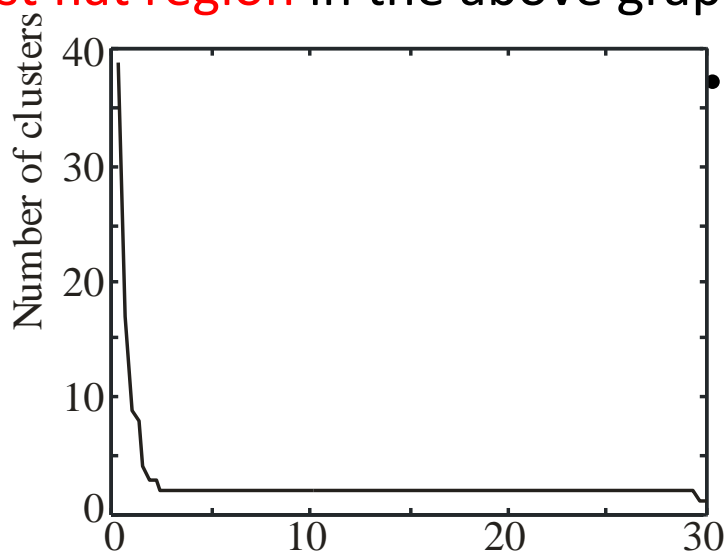
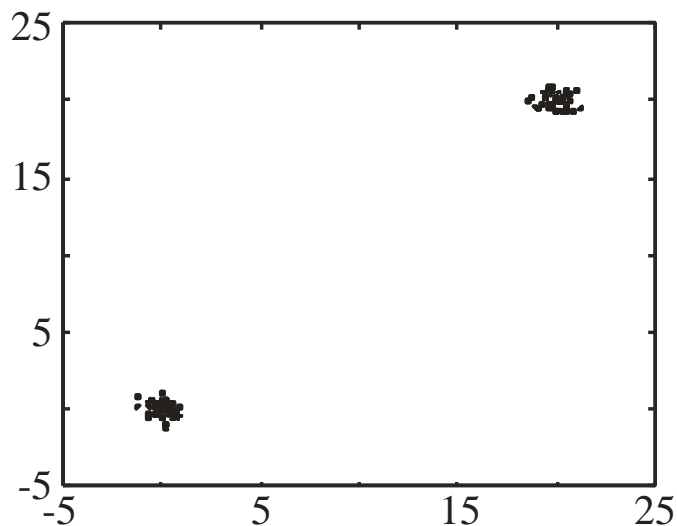
# Sequential clustering algorithms

## Basic Sequential Clustering Algorithm Scheme (BSAS)

### Estimating the number of clusters in the data set:

Let  $BSAS(\theta)$  denote the  $BSAS$  algorithm when the dissimilarity threshold is  $\theta$ .

- For  $\theta = a$  to  $b$  step  $c$ 
  - Run  $s$  times  $BSAS(\theta)$ , each time presenting the data in a different order.
  - Estimate the number of clusters  $m_\theta$ , as the most frequent number resulting from the  $s$  runs of  $BSAS(\theta)$ .
- Next  $\theta$
- Plot  $m_\theta$  versus  $\theta$  and identify the number of clusters  $m$  as the one corresponding to the widest flat region in the above graph.



- Consider as final clustering, the clustering that results for the  $\theta$  in the middle of the widest flat region.

# Sequential clustering algorithms

## MBSAS, a Modification of BSAS

- In **BSAS** a **decision** for a data vector  $x$  is **reached prior** to the **final cluster formation**, which is determined after all vectors have been presented to the algorithm.
- MBSAS deals with this issue, at the cost of processing the data twice.
- **MBSAS** consists of:
  - A **cluster determination phase** (first pass on the data), which is the **same as BSAS** with the **exception** that **no vector is assigned to an already formed cluster**. At the end of this phase, **each cluster consists** of a **single element**.
  - A **pattern classification phase** (second pass on the data), where **each** one of the **unassigned vectors** is **assigned** to its **closest cluster**.

**Exercise:** Write the pseudocode for MBSAS (in the spirit of the BSAS pseudocode).

## Remarks:

- In MBSAS, a decision for a vector  $x$  during the pattern classification phase is reached taking into account all clusters.
- MBSAS is **sensitive** to the **order of presentation** of the vectors.
- MBSAS requires **two passes** on the **data**. Its complexity is  $O(N)$ .

# Sequential clustering algorithms

## Refinement stages

The problem of **closeness of clusters**: “In all the above algorithms it may happen that two formed clusters lie very close to each other”.

(they may be **parts** of the **same physical cluster**)

### A simple merging procedure

(A) **Find**  $C_i, C_j$  ( $i < j$ ) such that  $d(C_i, C_j) = \min_{k,r=1,\dots,m,k \neq r} d(C_k, C_r)$

**If**  $d(C_i, C_j) \leq M_1$  then  $\{ M_1 \text{ is a user-defined threshold} \}$

- **Merge**  $C_i, C_j$  to  $C_i$  and eliminate  $C_j$ .
- If necessary, update the cluster representative of  $C_i$ .
- Rename the clusters  $C_{j+1}, \dots, C_m$  to  $C_j, \dots, C_{m-1}$ , respectively.
- $m = m - 1$
- Go to (A)

**Else**

- Stop

**End {if}**

# Sequential clustering algorithms

## Refinement stages

The problem of **sensitivity to the order of data presentation**:

“A vector  $\underline{x}$  may have been assigned to a cluster  $C_i$  at the current stage but another cluster  $C_j$  may be formed at a later stage that lies closer to  $\underline{x}$ ”

### A simple reassignment procedure

- **For**  $i = 1$  to  $N$ 
  - **Find**  $C_j$  such that  $d(\underline{x}_i, C_j) = \min_{k=1, \dots, m} d(\underline{x}_i, C_k)$
  - **Set**  $b(i) = j$  \{  $b(i)$  is the index of the cluster that lies closest to  $\underline{x}_i$  \}
- **End** {for}
  
- **For**  $j = 1$  to  $m$ 
  - **Set**  $C_j = \{\underline{x}_i \in X: b(i) = j\}$
  - If necessary, update representatives
- **End** {for}

# Sequential clustering algorithms

## Example in MATLAB 2:

Generate and plot a data set  $X_1$ , that consists of  $N = 400$  2-dim. data vectors. These vectors form **four groups**, each one of which contains vectors that stem from Gaussian distributions with **means**  $\mathbf{m}_1 = [0, 0]^T$ ,  $\mathbf{m}_2 = [4, 0]^T$ ,  $\mathbf{m}_3 = [0, 4]^T$ ,  $\mathbf{m}_4 = [5, 4]^T$ , respectively, and respective **covariance matrices**  $S_1 = I$ ,  $S_2 = \begin{bmatrix} 1 & 0.2 \\ 0.2 & 1.5 \end{bmatrix}$ ,  $S_3 = \begin{bmatrix} 1 & 0.4 \\ 0.4 & 1.1 \end{bmatrix}$ ,  $S_4 = \begin{bmatrix} 0.3 & 0.2 \\ 0.2 & 0.5 \end{bmatrix}$ . Then do the following:

1. Determine the number of clusters formed in  $X_1$  by doing the following:
  - a. Determine the maximum,  $d_{max}$ , and the minimum,  $d_{min}$ , distances between any two points in the data set.
  - b. Determine the values of  $\Theta$  for which the BSAS will run. These may be defined as  $\Theta_{min}, \Theta_{min} + s, \Theta_{min} + 2s, \dots, \Theta_{max}$ , where  $\Theta_{min} = 0.25 \frac{d_{min} + d_{max}}{2}$ ,  $\Theta_{max} = 1.75 \frac{d_{min} + d_{max}}{2}$  and  $s = \frac{\Theta_{min} + \Theta_{max}}{n_\Theta}$ ,  $n_\Theta$  is the number of successive values of  $\Theta$  that will be considered. Use  $n_\Theta = 50$ .

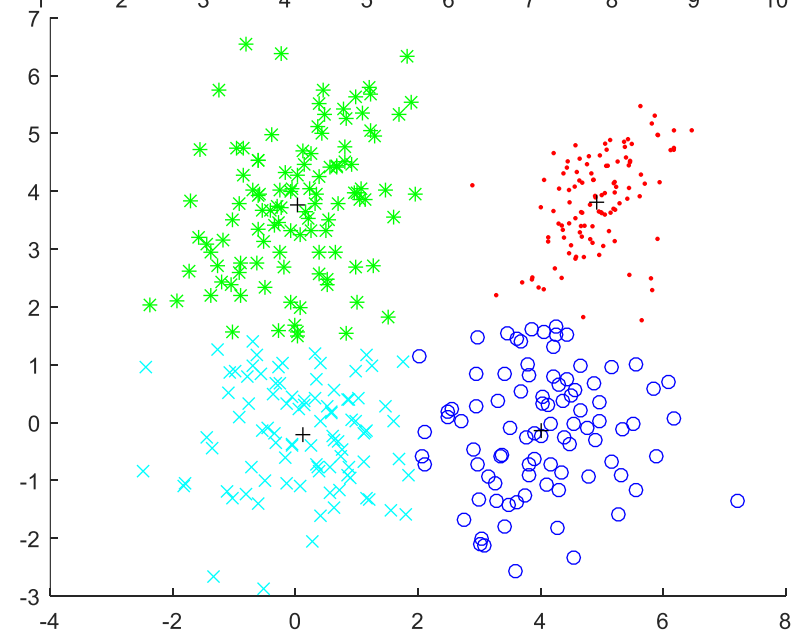
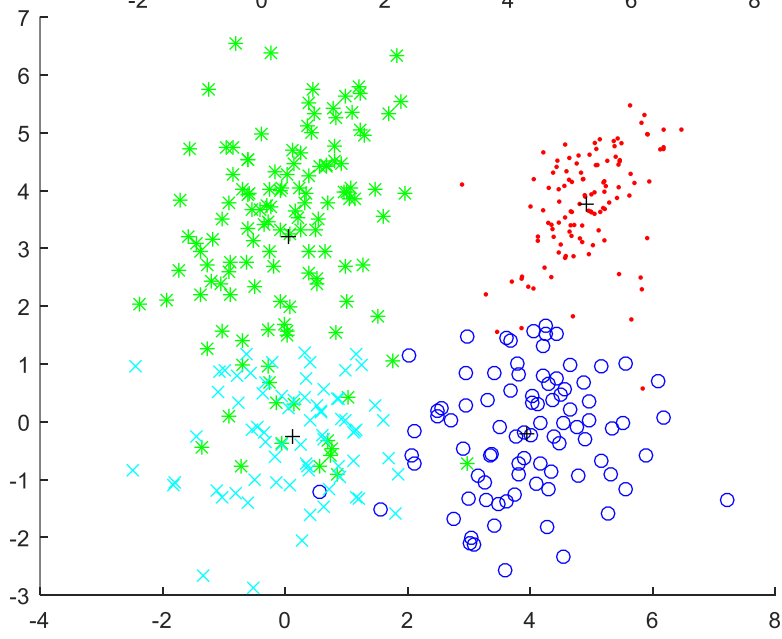
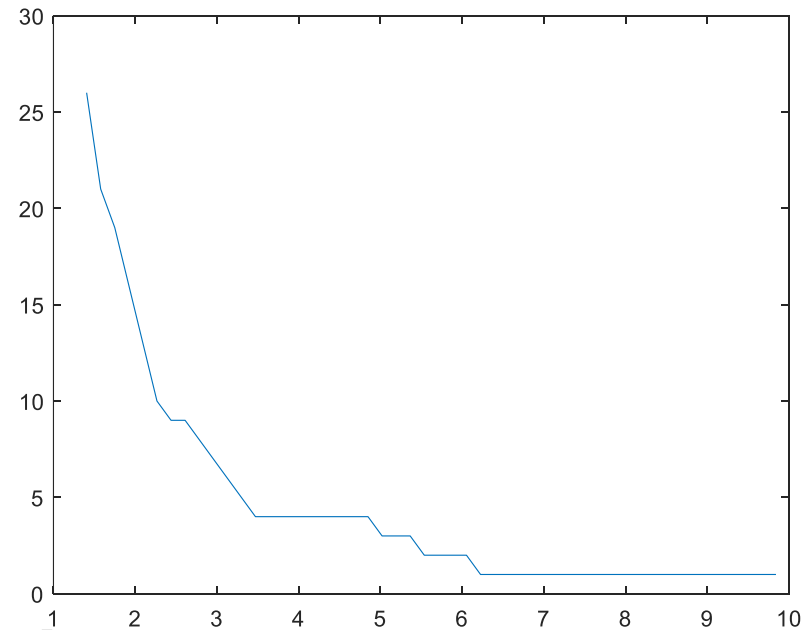
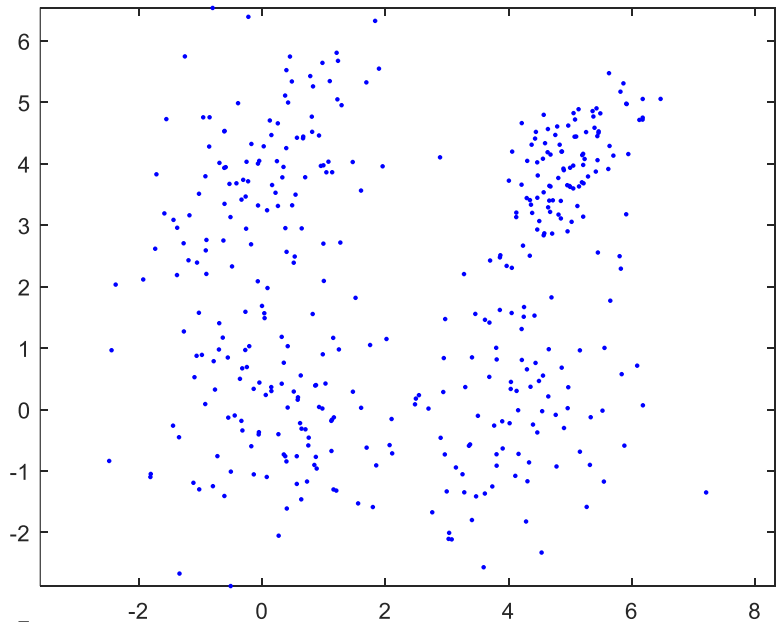
# Sequential clustering algorithms

## Example in MATLAB 2 (cont.):

- c. For each of the previously defined values of  $\Theta$ , run the BSAS algorithm  $n_{times} = 10$ , so that the data vectors are presented with different ordering to BSAS in each run. From the  $n_{times}$  estimates of the number of clusters, select the most frequently met value,  $m_{\theta}$ , as the most accurate. Let  $\mathbf{m}_{tot}$  be the  $n_{\theta}$ -dimensional vector, which contains the  $m_{\theta}$  values.
  - d. Plot  $m_{\theta}$  versus  $\Theta$ . Determine the widest flat region,  $r$ , of  $\Theta$ 's (excluding the one that corresponds to the single-cluster case) and let  $n_r$  be the number of  $\Theta$ 's in  $\{\Theta_{min}, \Theta_{min} + s, \dots, \Theta_{max}\}$  that also lie in  $r$ . If  $n_r$  is "significant" (e.g., greater than 10% of  $n_{\theta}$ ), the corresponding number of clusters,  $m_{best}$ , is selected as the best estimate and the mean of the values of  $\Theta$  in  $r$  is chosen as the corresponding best value for  $\Theta$  ( $\Theta_{best}$ ). Otherwise, the single-cluster clustering is adopted.
2. Run the BSAS algorithm for  $\Theta = \Theta_{best}$  and plot the data set using different colors and symbols for points from different clusters.
  3. Apply the reassignment procedure on the clustering results obtained in the previous step and plot the new clustering.

# Sequential clustering algorithms

## Example in MATLAB 2 (cont.):



# Sequential clustering algorithms

## A two-threshold sequential scheme (TTSAS)

- The formation of the clusters, as well as the assignment of vectors to clusters, is carried out concurrently (like BSAS and unlike MBSAS)
- **Two thresholds**  $\theta_1$  and  $\theta_2$  ( $\theta_1 < \theta_2$ ) are **employed**.
- The **general idea** is the following:

If the distance  $d(x, C)$  of  $x$  from its closest cluster,  $C$ , is **greater** than  $\theta_2$  then:

–A **new cluster** represented by  $x$  is created.

Else if  $d(x, C) < \theta_1$  then

– $x$  is **assigned** to  $C$ .

Else

–The **decision** is **postponed** to a **later stage**.

End {if}

- The unassigned vectors are presented iteratively to the algorithm until all of them are classified.

## Remarks:

- In practice, a few passes ( $\geq 2$ ) of the data set are required.
- TTSAS is less sensitive to the order of data presentation, compared to BSAS.

# Sequential clustering algorithms

## The maxmin algorithm

$W$  may be initialized by (a) the two most distant points or (b) the mean of the data set.

Let  $W$  be the set of all points that have been chosen to define clusters up to the current iteration step. The definition of clusters is carried out as follows:

- For each  $x \in X - W$  determine  $d_x = \min_{z \in W} d(x, z)$
- Determine  $y$ :  $d_y = \max_{x \in X - W} d_x$
- If  $d_y$  is greater than a prespecified threshold ( $\theta$ ) then
  - $y$  defines a new cluster
- else
  - the cluster determination phase of the algorithm terminates.
- End {if}

After the definition of the clusters, each unassigned vector is assigned to its closest cluster.

### Remarks:

- The maxmin algorithm is more computationally demanding than MBSAS.
- Its result is independent of the order of data presentation to the algorithm.
- It is expected to produce better clustering results than MBSAS.
- Its performance may be degraded in the presence of noise.

## Data

$$X = \{\mathbf{x}_j \in R^l, j = 1, \dots, N\}$$

## Basic parameters - notation

- ✓  $\Theta = \{\boldsymbol{\theta}_j, j = 1, \dots, m\}$  ( $\boldsymbol{\theta}_j$  is the **representative** of cluster  $C_j$ ).
- **Proximity** between  $\mathbf{x}_i$  and  $C_j$ :  $d(\mathbf{x}_i, \boldsymbol{\theta}_j)$

# CFO clustering algorithms: A unified view

## Basic parameters – notation (cont.)

✓

$$U = \begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1m} \\ u_{21} & u_{22} & \cdots & u_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ u_{N1} & u_{N2} & \cdots & u_{Nm} \end{bmatrix} \equiv \begin{bmatrix} \mathbf{u}_1^T \\ \mathbf{u}_2^T \\ \vdots \\ \mathbf{u}_N^T \end{bmatrix}$$

In the **probabilistic** case  
 $u_{ij}$  stands for  $P(j|\mathbf{x}_i)$

- $u_{ij} \in [0,1]$  quantifies the “**relation**” between  $\mathbf{x}_i$  and  $C_j$ .
- “**Large**” (“**small**”)  $u_{ij}$  values indicate **close** (**loose**) **relation** between  $\mathbf{x}_i$  and  $C_j$ .

$\Rightarrow u_{ij}$  varies **inversely proportional** wrt  $d(\mathbf{x}_i, \boldsymbol{\theta}_j)$ .

- $\mathbf{u}_i$  : vector containing the  $u_{ij}$ ’s of  $\mathbf{x}_i$  with all clusters.

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(\*) Unless otherwise stated, the case where **cluster representatives** are used is considered.

# CFO clustering algorithms: A unified view

## Aim:

- ✓ To **place** the **representatives** into dense in data regions (**physical clusters**).

## How this is achieved:

- ✓ Via the **minimization** of the following type of cost function (wrt  $\Theta, U$ )

$$J(\Theta, U) = \sum_{i=1}^N \sum_{j=1}^m u_{ij}^q d(\mathbf{x}_i, \boldsymbol{\theta}_j) \quad (q \geq 1)$$

s.t. some **constraints** on  $U, C(U)$ .

For the **probabilistic** case  $d(\mathbf{x}_i, \boldsymbol{\theta}_j)$  is embedded in the **log-likelihood** of suitably defined **exponential** distributions

## Intuition:

- ✓ For **fixed**  $\boldsymbol{\theta}_j$ 's,  $J(\Theta, U)$  is a weighted sum of **fixed** distances  $d(\mathbf{x}_i, \boldsymbol{\theta}_j)$ .
- ⇒ **Minimization** of  $J(\Theta, U)$  wrt  $u_{ij}$  instructs for **large** weights ( $u_{ij}$ ) for **small** distances  $d(\mathbf{x}_i, \boldsymbol{\theta}_j)$ .
- ✓ For **fixed**  $u_{ij}$ 's, **minimization** of  $J(\Theta, U)$  wrt  $\boldsymbol{\theta}_j$ 's leads  $\boldsymbol{\theta}_j$ 's closer to their most relative data points.

# CFO clustering algorithms: A unified view

Basic types of algorithms:

*Constraints on  $U = [u_{ij}]$*

*Partition matrix*

*Membership matrix*

*Compatibility matrix*

**Hard:**

- $u_{ij} \in \{0, 1\}$
- $\sum_{j=1}^m u_{ij} = 1$

**Fuzzy:**

- $u_{ij} \in (0, 1)$
- $\sum_{j=1}^m u_{ij} = 1$

**Possibilistic (>1 choices):**

- $u_{ij} \in (0, 1]$

k-means

FCV

FCL

FOM

PCM

APCH



*k-dim. nonlinear manifold*

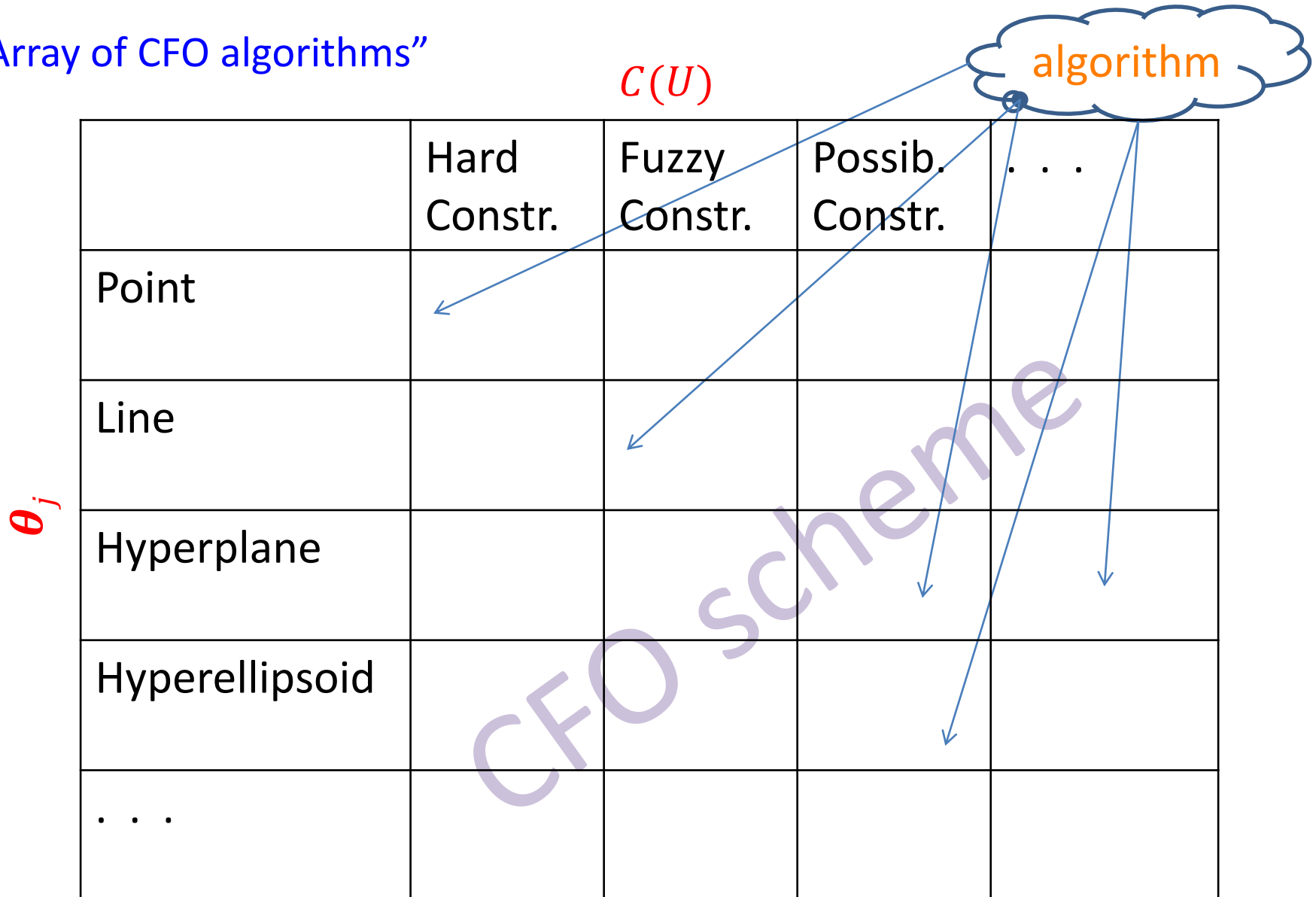
*k-dim. lin. manifold*

*Compact set in k-dim. lin. manifold*

$\Theta = \{\theta_j, j = 1, \dots, m\}$

# CFO clustering algorithms: A unified view

“Array of CFO algorithms”



There are **several unexplored areas** (groups of algorithms) in this array.

# CFO clustering algorithms: A unified view

“Array of CFO algorithms”

$C(U)$

$\theta_j$		Hard Constr.	Fuzzy Constr.	Possib. Constr.	...
	Point	Hard CFO scheme	Fuzzy CFO scheme	Possib. CFO scheme	
	Line				
	Hyperplane				
	Hyperellipsoid				
	...				

# CFO clustering algorithms: A unified view

“Array of CFO algorithms”

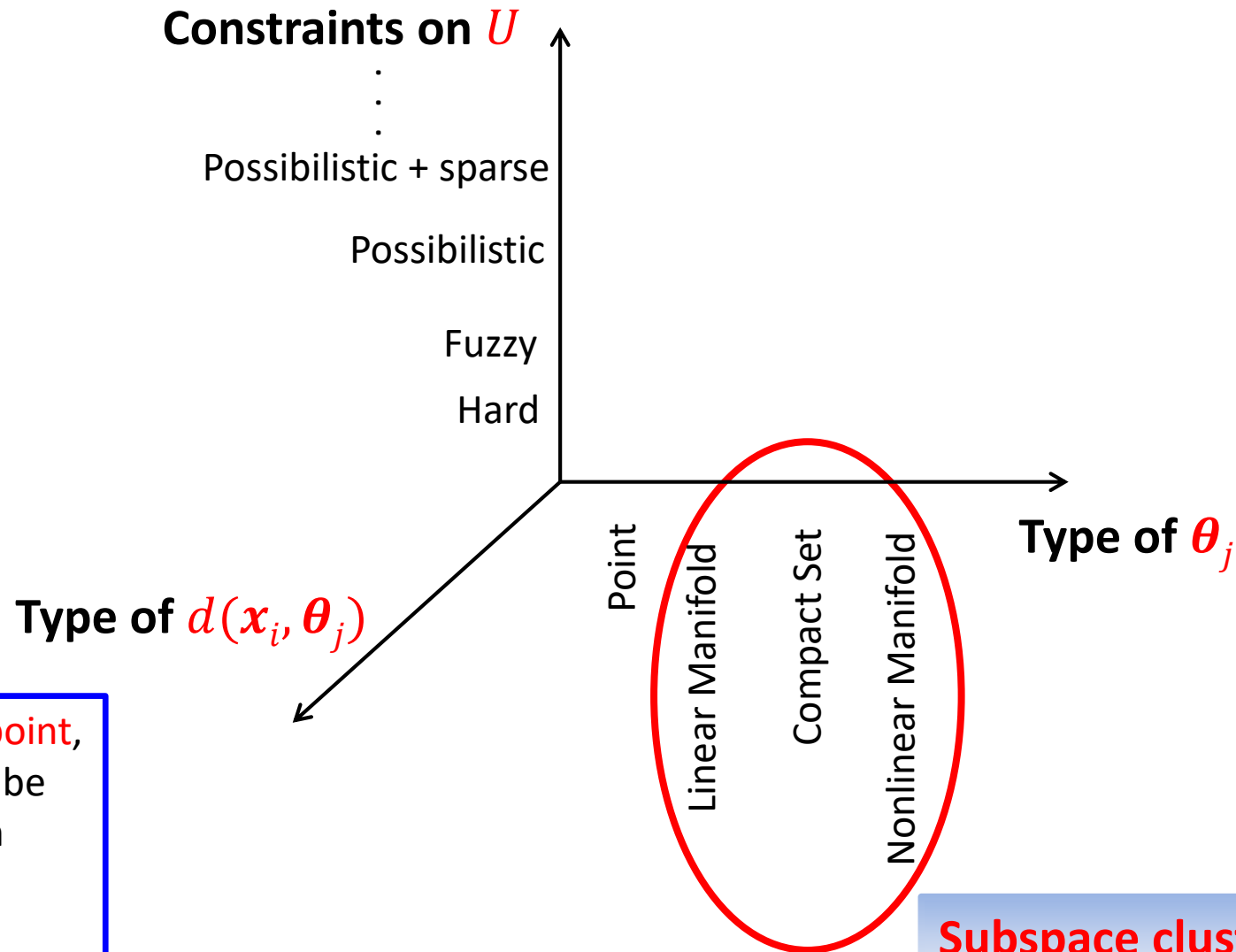
$C(U)$

$\Theta_j$

	Hard Constr.	Fuzzy Constr.	Possib. Constr.	. . .
Point	c-means scheme			
Line	c-lines scheme			
Hyperplane	c-hyperplanes scheme			
Hyperellipsoid	c-hyperellipsoids scheme			
. . .				

# CFO clustering algorithms: A unified view

## CFO clustering algorithms: A loose presentation



E.g.: If  $\theta_j$  is a point,  
 $d(x_i, \theta_j)$  may be

- Sq. Euclidean
- $l_p$  norm
- Mahalanobis

# CFO clustering algorithms: A unified view

## General cost function opt. (CFO) scheme:

- ✓ Initialize  $\Theta = \Theta(0)$
- ✓  $t = 0$
- ✓ **Repeat**
  - $U(t) = \operatorname{argmin}_U J(\Theta(t), U), \text{ s.t. } C(U(t))$
  - $t = t + 1$
  - $\Theta(t) = \operatorname{argmin}_{\Theta} J(\Theta, U(t-1))$
- ✓ **Until convergence**



fixed

# CFO clustering algorithms: A unified view

“Array of CFO algorithms”

$\theta_j$	$C(U)$			
	Hard Constr.	Fuzzy Constr.	Possib. Constr.	. . .
Point				
Line				
Hyperplane				
Hyperellipsoid				
. . .				

# Cost function optimization (CFO) algorithms

## Hard clustering algorithms:

Let  $X = \{x_1, x_2, \dots, x_N\}$  be a set of data points.

Each vector belongs **exclusively** to a single cluster.

Each **cluster** is **represented** by a representative  $\theta_j$  (point repr., hyperplane...).

Let  $\Theta = \{\theta_1, \theta_2, \dots, \theta_m\}$

Define  $u_{ij} = \begin{cases} 1, & \text{if } x_i \in C_j \\ 0, & \text{otherwise} \end{cases}$  and  $U = [u_{ij}]_{N \times m}$

It is  $\sum_{j=1}^m u_{ij} = 1, i = 1, \dots, N$

Define the **cost function**

$$J(U, \Theta) = \sum_{i=1}^N \sum_{j=1}^m u_{ij} d(x_i, \theta_j) = \sum_{j=1}^m \sum_{x_i \in C_j} d(x_i, \theta_j)$$

When  $J(U, \Theta)$  is **minimized**?

# CFO hard clustering algorithms

$$J(U, \theta) = \sum_{i=1}^N \sum_{j=1}^m u_{ij} d(\mathbf{x}_i, \theta_j) = \sum_{j=1}^m \sum_{\mathbf{x}_i \in C_j} d(\mathbf{x}_i, \theta_j)$$

For **fixed  $\theta_j$ 's**: When, for each  $\mathbf{x}_i$ , only its distance from its closest representative is taken into account.

This suggests to **define**  $u_{ij} = \begin{cases} 1, & \text{if } d(\mathbf{x}_i, \theta_j) = \min_{q=1, \dots, m} d(\mathbf{x}_i, \theta_q) \\ 0, & \text{otherwise} \end{cases}$

For **fixed  $u_{ij}$ 's**: Solve the following  $m$  independent problems

$$\min_{\theta_j} \sum_{\mathbf{x}_i \in C_j} d(\mathbf{x}_i, \theta_j) \equiv \min_{\theta_j} \sum_{i=1}^N u_{ij} d(\mathbf{x}_i, \theta_j)$$

Thus, the **Generalized Hard Algorithmic Scheme (GHAS)** is given below

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

- Choose  $\theta_j(0)$  as initial estimates for  $\theta_j, j = 1, \dots, m$ .

- $t = 0$

- Repeat

- For  $i = 1$  to  $N$  % *Determination of the partition*

- o For  $j = 1$  to  $m$

$$u_{ij}(t) = \begin{cases} 1, & \text{if } d(\mathbf{x}_i, \theta_j(t)) = \min_{q=1, \dots, m} d(\mathbf{x}_i, \theta_q(t)) \\ 0, & \text{otherwise} \end{cases}$$

- o End {For- $j$ }

- End {For- $i$ }

–  $t = t + 1$

- For  $j = 1$  to  $m$  % *Parameter updating*

- o Set

$$\theta_j(t) = \operatorname{argmin}_{\theta_j} \sum_{i=1}^N u_{ij}(t-1) d(\mathbf{x}_i, \theta_j), j = 1, \dots, m$$

- End {For- $j$ }

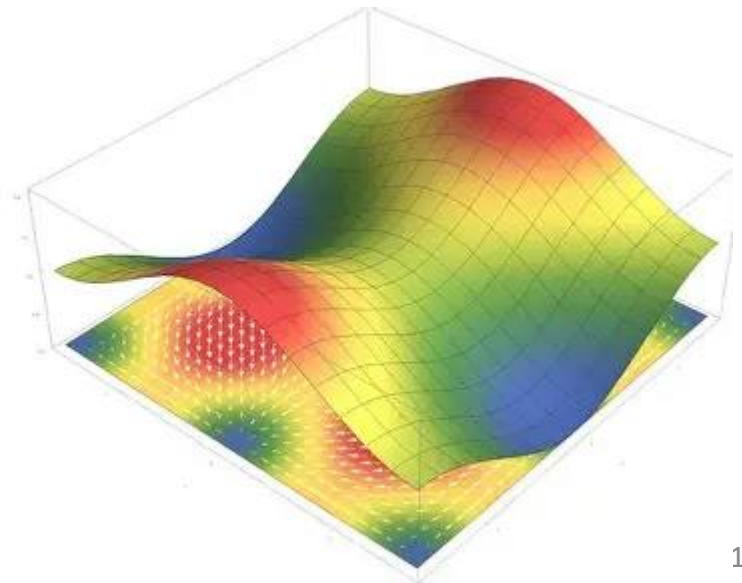
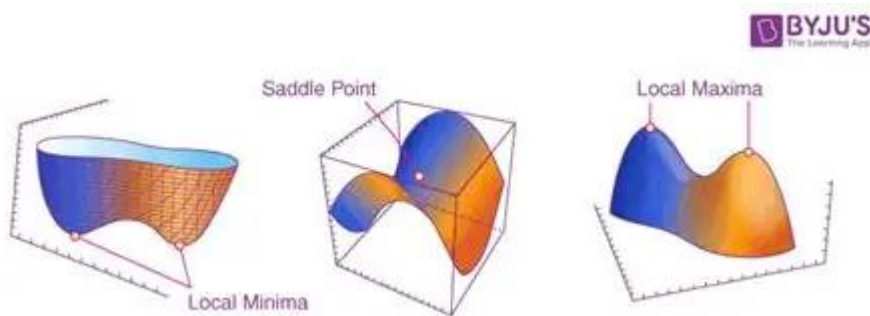
- Until a termination criterion is met.

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### Remarks:

- In the update of each  $\theta_j$ , only the vectors  $x_i$  for which  $u_{ij}(t - 1) = 1$  are used.
- **GHAS** may **terminate** when either
  - $||\theta(t) - \theta(t - 1)|| < \varepsilon$  or
  - $U$  remains **unchanged** for **two successive iterations**.
- The two-step optimization procedure in GHAS **does not necessarily lead to a local minimum** of  $J(U, \theta)$ .



# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

#### General comments

- It is a special case of GHAS where
  - **Point representatives** are **used**.
  - The **squared Euclidean distance** is **employed**.
- The cost function  $J(U, \Theta)$  becomes now
$$J(U, \Theta) = \sum_{i=1}^N \sum_{j=1}^m u_{ij} ||\mathbf{x}_i - \boldsymbol{\theta}_j||^2$$
- Applying GHAS in this case, it turns out that it **converges** to a **minimum** of the **cost function**.
- Isodata **recovers clusters** that are as **compact** as possible.
- For other choices of the distance (including the Euclidean), the algorithm converges but not necessarily to a minimum of  $J(U, \Theta)$ .

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

- Choose arbitrary initial estimates  $\theta_j(0)$  for the  $\theta_j$ 's,  $j=1, \dots, m$ .
- $t = 0$
- **Repeat**

– For  $i = 1$  to  $N$  % *Determination of the partition*

o For  $j=1$  to  $m$

$$u_{ij}(t) = \begin{cases} 1, & \text{if } ||\mathbf{x}_i - \theta_j(t)||^2 = \min_{q=1, \dots, m} ||\mathbf{x}_i - \theta_q(t)||^2 \\ 0, & \text{otherwise} \end{cases}$$

o End {For- $j$ }

– End {For- $i$ }

–  $t = t + 1$

– For  $j = 1$  to  $m$  % *Parameter updating*

o Set

$$\theta_j(t) = \frac{\sum_{i=1}^N u_{ij}(t-1) \mathbf{x}_i}{\sum_{i=1}^N u_{ij}(t-1)}, j = 1, \dots, m$$

– End {For- $j$ }

- **Until** no change in  $\theta_j$ 's occurs between two successive iterations

# CFO hard clustering algorithms

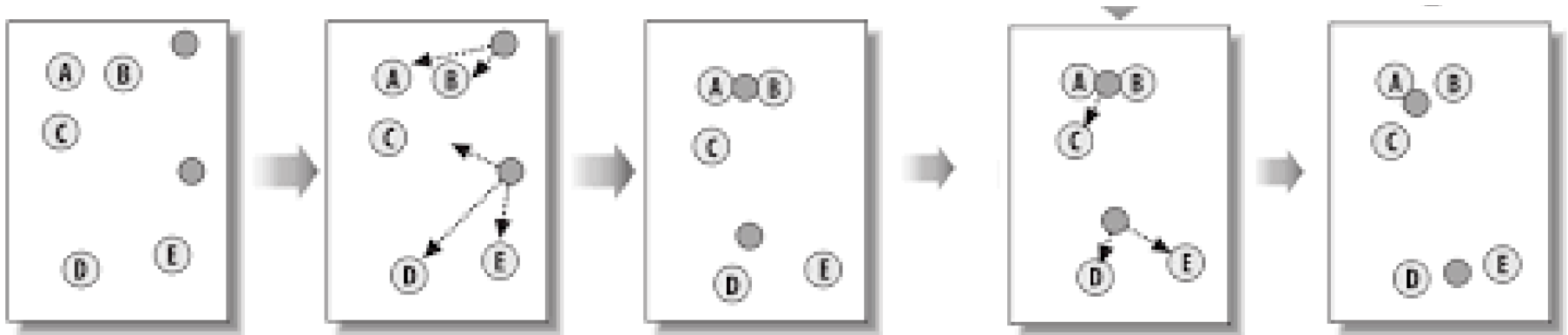
## The k-means case.

Choose arbitrary initial estimates  $\theta_j(0)$  for the  $\theta_j$ 's,  $j = 1, \dots, m$ .

### Repeat

- For  $i = 1$  to  $N$  *Partition determination*
  - o Determine the closest representative, say  $\theta_j$ , for  $x_i$
  - o Set  $u_{ij} = 1$  and  $u_{iq} = 0$ ,  $q = 1, \dots, m$ ,  $q \neq j$ .
- End {For}
- For  $j = 1$  to  $m$  *Parameter updating*
  - o Determine  $\theta_j$  as the mean of the vectors  $x_i \in X$  with  $u_{ij} = 1$ .
- End {For}

**Until** no change in  $\theta_j$ 's occurs between two successive iterations



# CFO hard clustering algorithms

## Remarks

- It is a **batch, single clustering** algorithm
- It is a **hard clustering** algorithm that uses **point representatives**  $\theta_j$  for the clusters  $C_j$ .

- It results from the optimization of the following cost function

$$J(U, \Theta) = \sum_{i=1}^N \sum_{j=1}^m u_{ij} ||\mathbf{x}_i - \boldsymbol{\theta}_j||^2$$

where  $U = [u_{ij}]$  and  $\Theta = \{\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_m\}$

- It is of **iterative** nature.
- **Initially** it places the representatives  $\theta_j$  at **random positions** in space.
- It gradually **moves the representatives** towards the **centers** of the **true clusters**.
- In practice, its **time complexity** is  $\underline{O(q \cdot m \cdot N)}$  ( $q$  is the number of iterations).
- It requires the number of clusters  $m$  to be **known a priori**.

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

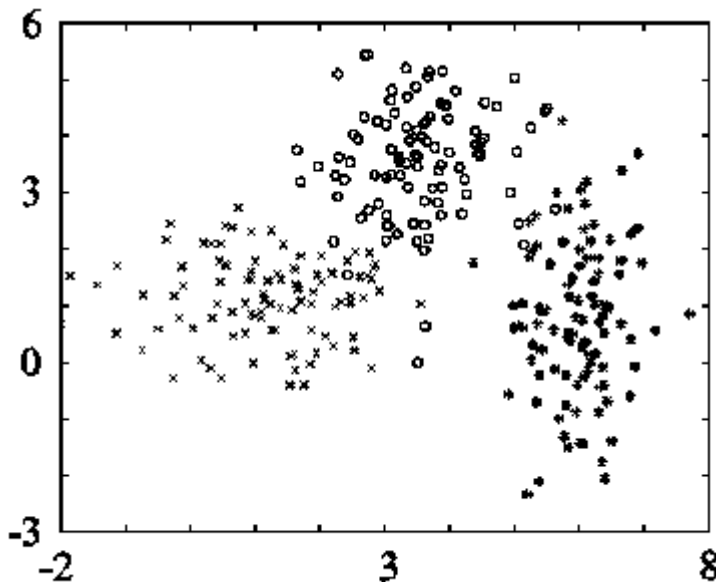
**Example 1:** (a) Consider three two-dimensional normal distributions with mean values:

$$\boldsymbol{\mu}_1 = [1, 1]^T, \boldsymbol{\mu}_2 = [3.5, 3.5]^T, \boldsymbol{\mu}_3 = [6, 1]^T$$

and respective covariance matrices

$$\Sigma_1 = \begin{bmatrix} 1 & -0.3 \\ -0.3 & 1 \end{bmatrix}, \Sigma_2 = \begin{bmatrix} 1 & 0.3 \\ 0.3 & 1 \end{bmatrix}, \Sigma_3 = \begin{bmatrix} 1 & 0.7 \\ 0.7 & 1 \end{bmatrix}$$

Generate a group of **100 vectors** from **each distribution**. These form the data set  **$X$** .



**Confusion matrix** for the results of  $k$ -means.

$$A = \begin{bmatrix} 94 & 3 & 3 \\ 0 & 100 & 0 \\ 9 & 0 & 91 \end{bmatrix}$$

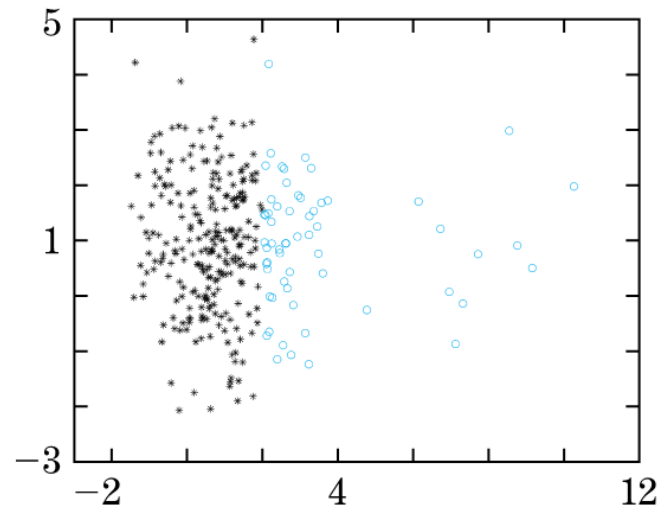
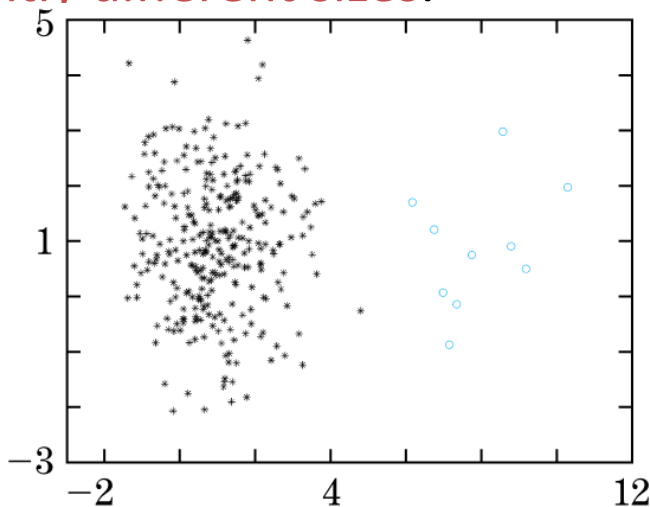
# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

**Example 2:** (i) Consider two 2-dimensional Gaussian distributions  $N(\boldsymbol{\mu}_1, \Sigma_1)$ ,  $N(\boldsymbol{\mu}_2, \Sigma_2)$ , with  $\boldsymbol{\mu}_1 = [1, 1]^T$ ,  $\boldsymbol{\mu}_2 = [8, 1]^T$ ,  $\Sigma_1 = 1.5I$  and  $\Sigma_2 = I$ . (ii) Generate 300 points from the 1<sup>st</sup> distribution and 10 points from the 2<sup>nd</sup> distribution. (iii) Set  $m = 2$  and initialize randomly  $\boldsymbol{\theta}_j$ 's ( $\boldsymbol{\theta}_j \equiv \boldsymbol{\mu}_j$ ).

- After convergence the large group has been split into two clusters.
- Its right part has been assigned to the same cluster with the points of the small group (see figure below).
- This indicates that  $k$ -means cannot deal accurately with clusters having significantly different sizes.



# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

#### Remarks:

- $k$ -means recovers **compact clusters**.
- The computational complexity of the  $k$ -means is  $O(Nmq)$ , where  $q$  is the number of iterations required for convergence. In practice,  $m$  and  $q$  are significantly less than  $N$ , thus,  **$k$ -means becomes eligible for processing large data sets**.
- **Sequential (online) versions** of the  $k$ -means, where the updating of the representatives takes place immediately after the identification of the representative that lies closer to the current input vector  $\mathbf{x}_i$ , have also been proposed.
- A variant of the  $k$ -means results if the number of vectors in each cluster is constrained *a priori*.

#### Further remarks:

Some drawbacks of the original  $k$ -means accompanied with the variants of the  $k$ -means that deal with them are discussed next.

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

**Drawback 1:** *Different initial partitions may lead  $k$ -means to produces different final clusterings, each one corresponding to a different local minimum of the cost function.*

### Strategies for facing drawback 1:

- Single run methods
  - Use a sequential algorithm (discussed previously) to produce initial estimates for  $\theta_j$ 's.
  - Partition randomly the data set into  $m$  subsets and use their means as initial estimates for  $\theta_j$ 's.
- Multiple run methods
  - Create different partitions of  $X$ , run  $k$ -means for each one of them and select the best result (associated with the minimum cost function value).
- Utilization of tools from stochastic optimization techniques (simulated annealing, genetic algorithms etc).

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

**Drawback 2:** *Knowledge of the number of clusters  $m$  is required a priori.*

### Strategies for facing drawback 2:

- Employ splitting, merging and/or discarding operations of the clusters resulting from  $k$ -means.
- Estimate  $m$  as follows:
  - Run a **sequential** algorithm many times for different thresholds of dissimilarity  $\theta$ .
  - Plot  $\theta$  versus the number of clusters and identify the largest plateau in the graph and set  $m$  equal to the value that corresponds to this plateau.

# CFO hard clustering algorithms

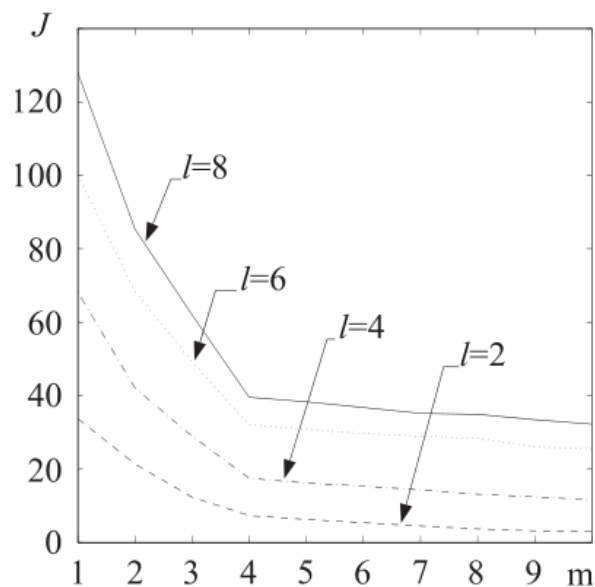
## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

**Drawback 2:** Knowledge of the number of clusters  $m$  is required a priori.

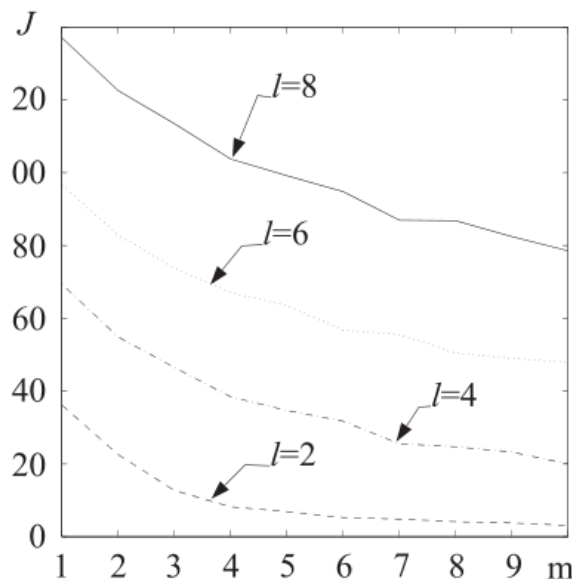
Strategies for facing drawback 2 (cont.):

- Estimate  $m$  as follows:
  - Run the  **$k$ -means** algorithm for different values of the number of clusters  $m$ .
  - For each of the resulting clusterings compute the value of  $J$ .
  - **Plot  $J$  versus** the number of clusters  $m$  and identify the most significant knee in the graph. Its position indicates the number of physical clusters.



Clustered data

Non-clustered data



# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The Isodata or $k$ -Means or $c$ -Means algorithm

**Drawback 3:**  *$k$ -means is sensitive to outliers and noise.*

#### Strategies for facing drawback 3:

- Discard all “small” clusters (they are likely to be formed by outliers).
- Use a  $k$ -medoids algorithm (see below), where a cluster is represented by one of its points.

**Drawback 4:**  *$k$ -means is not suitable for data with nominal (categorical) coordinates.*

#### Strategies for facing drawback 4:

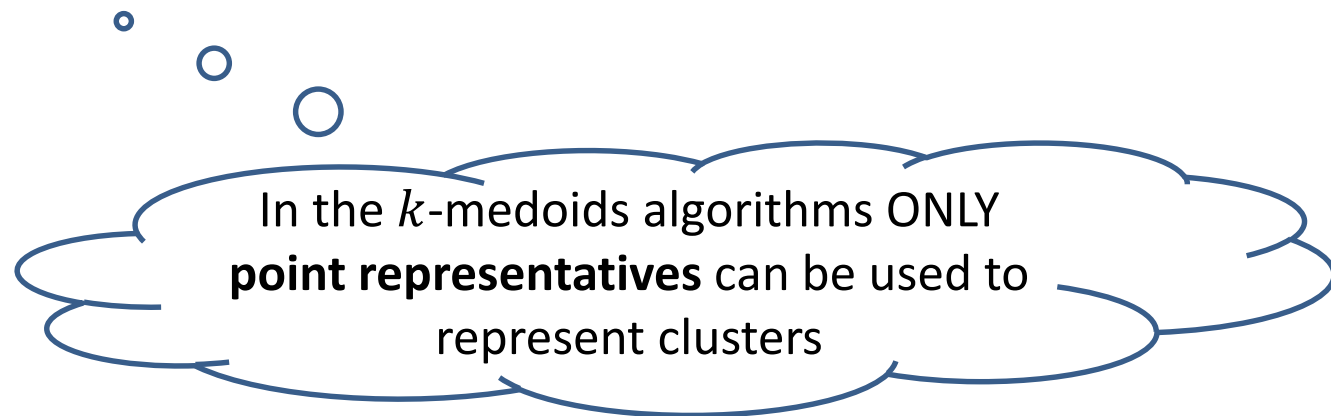
- Use a  $k$ -medoids algorithm.

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### *k*-Medoids Algorithms

- Each cluster is represented by a vector selected **among** the elements of  $X$  (**medoid**).
- A cluster contains
  - Its medoid
  - All vectors in  $X$  that
    - o Are not used as medoids in other clusters
    - o Lie closer to its medoid than the medoids representing other clusters.



# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### *k*-Medoids Algorithms

Let

- $\Theta$  be the **set of medoids** of all clusters,
- $I_\Theta$  the set of **indices** of the points in  $X$  that constitute  $\Theta$  and
- $I_{X-\Theta}$  the set of indices of the points that are **not medoids**.

Obtaining the set of medoids  $\Theta$  that best represents the data set,  $X$  is equivalent to minimizing the following cost function

$$J(\Theta, U) = \sum_{i \in I_{X-\Theta}} \sum_{j \in I_\Theta} u_{ij} d(\mathbf{x}_i, \mathbf{x}_j)$$

with

$$u_{ij} = \begin{cases} 1, & \text{if } d(\mathbf{x}_i, \mathbf{x}_j) = \min_{q \in I_\Theta} d(\mathbf{x}_i, \mathbf{x}_q), \\ 0, & \text{otherwise} \end{cases}, \quad i = 1, \dots, N$$

# CFO hard clustering algorithms

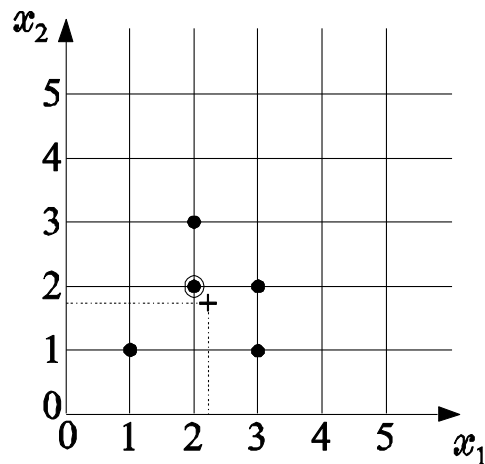
## Generalized Hard Algorithmic Scheme (GHAS)

### *k*-Medoids Algorithms

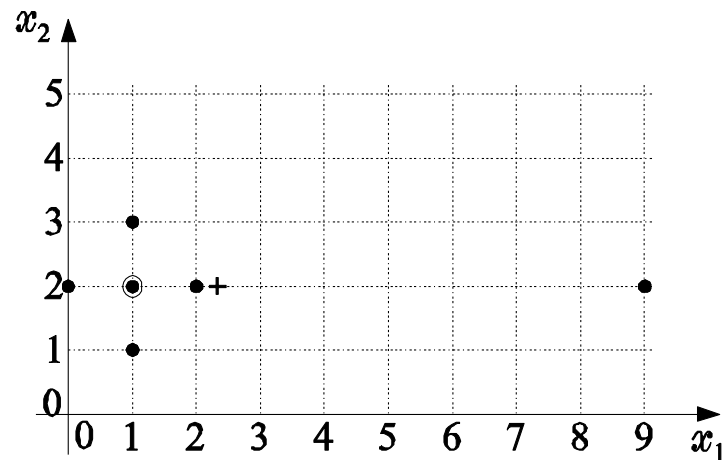
#### Example 3:

(a) The five-point two-dimensional set stems from the discrete domain  $D = \{1, 2, 3, 4, \dots\} \times \{1, 2, 3, 4, \dots\}$ . Its medoid is the circled point and **its mean** is the “+” point, which **does not belong to  $D$** .

(b) In the six-point two-dimensional set, the point (9,2) can be considered as an outlier. While **the outlier affects significantly the mean** of the set, **it does not affect its medoid**.



(a)



(b)

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

Representing clusters with **mean values** vs representing clusters with **medoids**

Mean Values	Medoids
1. Suited only for continuous domains	<b>1. Suited for either cont. or discrete domains</b>
2. Algorithms using means are sensitive to outliers	<b>2. Algorithms using medoids are less sensitive to outliers</b>
<b>3. The mean possesses a clear geometrical and statistical meaning</b>	3. The medoid has not a clear geometrical meaning
<b>4. Algorithms using means are less computationally demanding</b>	4. Algorithms using medoids are more computationally demanding

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### *k*-Medoids Algorithms

#### Algorithms to be considered

- **PAM** (Partitioning Around Medoids)
- **CLARA** (Clustering LARge Applications)
- **CLARANS** (Clustering Large Applications based on RANdomized Search)

#### The PAM algorithm

- The number of clusters  $m$  is **required *a priori***.

## Definitions-preliminaries

- Two sets of medoids  $\Theta$  and  $\Theta'$ , each one consisting of  $m$  elements, are called **neighbors** if they **share**  $m - 1$  elements.
- A set  $\Theta$  of medoids with  $m$  elements can have  $m(N - m)$  neighbors.
- Let  $\Theta_{ij}$  denote the **neighbor** of  $\Theta$  that results if  $x_j, j \in I_{X-\Theta}$  **replaces**  $x_i, i \in I_{\Theta}$ .
- Let  $\Delta J_{ij} = J(\Theta_{ij}, U_{ij}) - J(\Theta, U)$ .

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm

- Determination of  $\Theta$  that best represents the data
  - **Generate** a set  $\Theta$  of  $m$  medoids, randomly selected out of  $X$ .
  - **(A) Determine** the neighbor  $\Theta_{qr}$ ,  $q \in I_{\Theta}$ ,  $r \in I_{X-\Theta}$  among the  $m(N - m)$  neighbors of  $\Theta$  for which  $\Delta J_{qr} = \min_{i \in I_{\Theta}, j \in I_{X-\Theta}} \Delta J_{ij}$ .
  - If  $\Delta J_{qr} < 0$  then
    - $\Delta J_{qr} < 0 \Leftrightarrow J(\Theta_{qr}, U_{qr}) - J(\Theta, U) < 0$
    - $\Leftrightarrow J(\Theta_{qr}, U_{qr}) < J(\Theta, U)$
    - Replace  $\Theta$  by  $\Theta_{qr}$
    - Go to **(A)**
  - End
- Assignment of points to clusters
  - Assign each  $x \in X - \Theta$  to the cluster represented by the closest to  $x$  medoid.

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm

Computation of  $\Delta J_{ij}$ .

It is defined as:

$$\begin{aligned}\Delta J_{ij} &= J(\Theta_{ij}, U_{ij}) - J(\Theta, U) = \sum_{s \in I_{X-\Theta_{ij}}} \sum_{t \in I_{\Theta_{ij}}} u_{st} d(\mathbf{x}_s, \mathbf{x}_t) - \sum_{s \in I_{X-\Theta}} \sum_{t \in I_{\Theta}} u_{st} d(\mathbf{x}_s, \mathbf{x}_t) \\ &\equiv \sum_{h \in I_{X-\Theta}} C_{hij}\end{aligned}$$

where  $C_{hij}$  is the difference in  $J$ , resulting from the (possible) assignment of the vector  $\mathbf{x}_h \in X - \Theta$  from the cluster it currently belongs to another, as a consequence of the replacement of  $\mathbf{x}_i \in \Theta$  by  $\mathbf{x}_j \in X - \Theta$ .

For the computation of  $C_{hij}$  associated with a specific  $\mathbf{x}_h \in X - \Theta$  it is required

- The **distance** of  $\mathbf{x}_h$  from its **closest medoid** in  $\Theta$
- The **distance** of  $\mathbf{x}_h$  from its **next to closest medoid** in  $\Theta$ .
- The **distance** of  $\mathbf{x}_h$  from the **newly inserted medoid** in  $\Theta_{ij}$ ,  $\mathbf{x}_j$ .

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm (cont.)

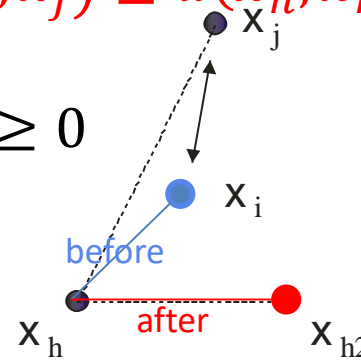
Computation of  $C_{hij}$ :

$\mathbf{x}_h$  belongs to the **cluster** represented by  $\mathbf{x}_i$  ( $\mathbf{x}_{h2} \in \Theta$  denotes the second closest to  $\mathbf{x}_h$  representative) and  $d(\mathbf{x}_h, \mathbf{x}_j) \geq d(\mathbf{x}_h, \mathbf{x}_{h2})$  ( $\geq d(\mathbf{x}_h, \mathbf{x}_i)$ ). Then

$$C_{hij} = d(\mathbf{x}_h, \mathbf{x}_{h2}) - d(\mathbf{x}_h, \mathbf{x}_i) \geq 0$$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta_{ij}, U_{ij})$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta, U)$

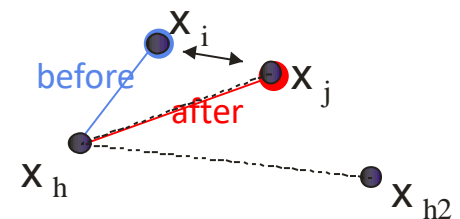
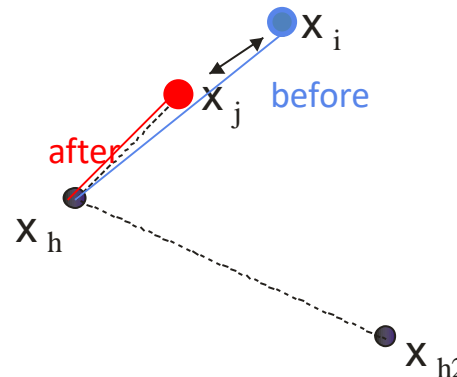


$\mathbf{x}_h$  belongs to the **cluster** represented by  $\mathbf{x}_i$  ( $\mathbf{x}_{h2} \in \Theta$  denotes the second closest to  $\mathbf{x}_h$  representative) and  $d(\mathbf{x}_h, \mathbf{x}_j) \leq d(\mathbf{x}_h, \mathbf{x}_{h2})$ . Then

$$C_{hij} = d(\mathbf{x}_h, \mathbf{x}_j) - d(\mathbf{x}_h, \mathbf{x}_i) (><) 0$$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta_{ij}, U_{ij})$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta, U)$



# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm (cont.)

Computation of  $C_{hij}$  (cont.):

$\mathbf{x}_h$  is not represented by  $\mathbf{x}_i$  ( $\mathbf{x}_{h1}$  denotes the closest to  $\mathbf{x}_h$  medoid) and  $d(\mathbf{x}_h, \mathbf{x}_{h1}) \leq d(\mathbf{x}_h, \mathbf{x}_j)$ . Then

$$C_{hij} = d(\mathbf{x}_h, \mathbf{x}_{h1}) - d(\mathbf{x}_h, \mathbf{x}_{h1}) = 0$$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta_{ij}, U_{ij})$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta, U)$

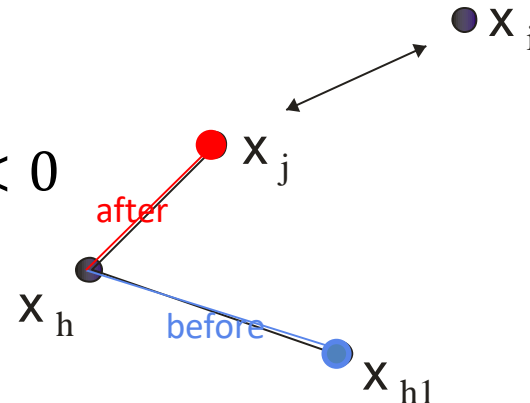


$\mathbf{x}_h$  is not represented by  $\mathbf{x}_i$  ( $\mathbf{x}_{h1}$  denotes the closest to  $\mathbf{x}_h$  medoid) and  $d(\mathbf{x}_h, \mathbf{x}_{h1}) > d(\mathbf{x}_h, \mathbf{x}_j)$ . Then

$$C_{hij} = d(\mathbf{x}_h, \mathbf{x}_j) - d(\mathbf{x}_h, \mathbf{x}_{h1}) < 0$$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta_{ij}, U_{ij})$

Contribution of  
 $\mathbf{x}_h$  to  $J(\Theta, U)$



# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm (cont.)

#### Remarks:

- Experimental results show the PAM works **satisfactorily with small data sets**.
- Its computational complexity is  $O(m(N - m)^2)$ . **Unsuitable for large data sets**.

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

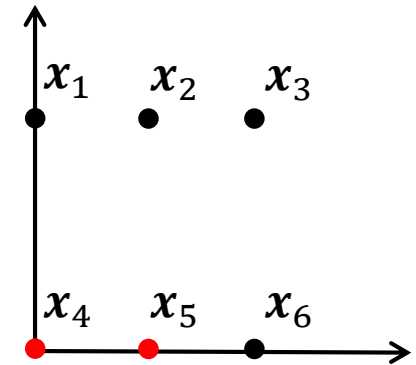
### The PAM algorithm (Example)

**Data set:**  $X = \{x_1, x_2, x_3, x_4, x_5, x_6\}$ , with

$x_1 = [0,3]^T$ ,  $x_2 = [1,3]^T$ ,  $x_3 = [2,3]^T$ ,  $x_4 = [0,0]^T$ ,  $x_5 = [1,0]^T$ ,  $x_6 = [2,0]^T$ .

**Set of medoids:**  $\Theta = \{x_4, x_5\}$

Computation of  $J(\Theta, U)$  (Squared Euclidean distance is considered):



$$\begin{aligned}
 x_1 &\rightarrow d(x_1, x_4) = 9 < 10 = d(x_1, x_5) \rightarrow u_{14} = 1, u_{15} = 0 \\
 x_2 &\rightarrow d(x_2, x_4) = 10 > 9 = d(x_2, x_5) \rightarrow u_{24} = 0, u_{25} = 1 \\
 x_3 &\rightarrow d(x_3, x_4) = 13 > 10 = d(x_3, x_5) \rightarrow u_{34} = 0, u_{35} = 1 \\
 x_4 &\rightarrow d(x_4, x_4) = 0 < 1 = d(x_4, x_5) \rightarrow u_{44} = 1, u_{45} = 0 \\
 x_5 &\rightarrow d(x_5, x_4) = 1 > 0 = d(x_5, x_5) \rightarrow u_{54} = 0, u_{55} = 1 \\
 x_6 &\rightarrow d(x_6, x_4) = 2 > 1 = d(x_6, x_5) \rightarrow u_{64} = 0, u_{65} = 1
 \end{aligned}$$

$$\begin{aligned}
 J(\Theta, U) = & \begin{aligned}
 & u_{14}d(x_1, x_4) + u_{15}d(x_1, x_5) + 1 \cdot 9 + 0 \cdot 10 + \\
 & u_{24}d(x_2, x_4) + u_{25}d(x_2, x_5) + 0 \cdot 10 + 1 \cdot 9 + \\
 & u_{34}d(x_3, x_4) + u_{35}d(x_3, x_5) + 0 \cdot 13 + 1 \cdot 10 + \\
 & u_{44}d(x_4, x_4) + u_{45}d(x_4, x_5) + 1 \cdot 0 + 0 \cdot 1 + \\
 & u_{54}d(x_5, x_4) + u_{55}d(x_5, x_5) + 0 \cdot 1 + 1 \cdot 0 + \\
 & u_{64}d(x_6, x_4) + u_{65}d(x_6, x_5) + 0 \cdot 2 + 1 \cdot 1
 \end{aligned} = 29
 \end{aligned}$$

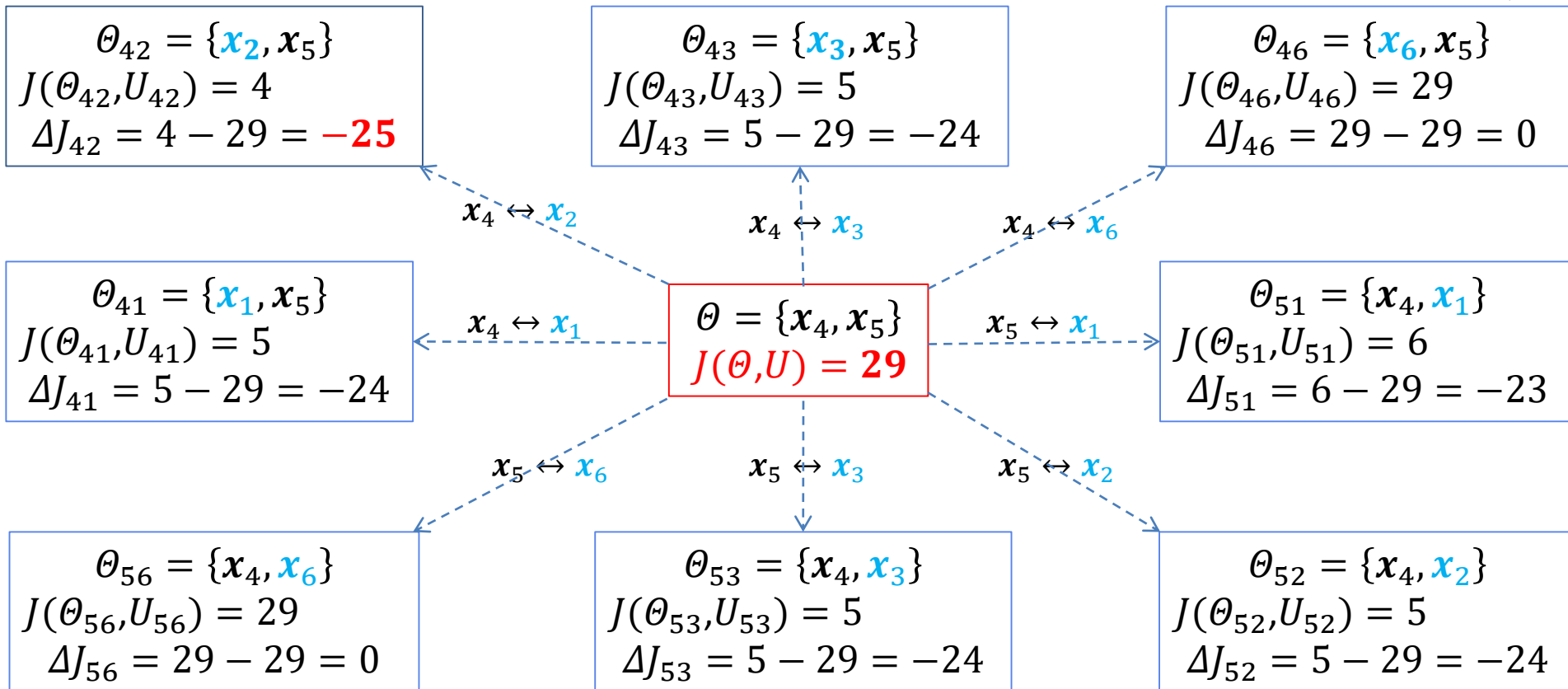
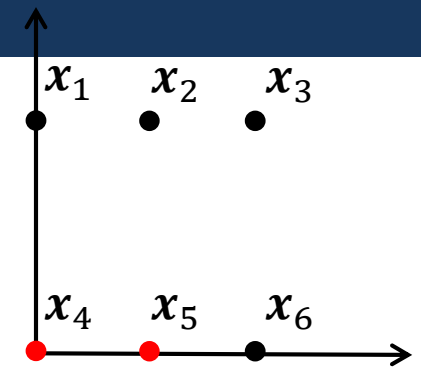
# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm (Example)

**Data set:**  $X = \{x_1, x_2, x_3, x_4, x_5, x_6\}$ , with  
 $x_1 = [0,3]^T$ ,  $x_2 = [1,3]^T$ ,  $x_3 = [2,3]^T$ ,  $x_4 = [0,0]^T$ ,  $x_5 = [1,0]^T$ ,  $x_6 = [2,0]^T$ .

**Set of medoids:**  $\Theta = \{x_4, x_5\}$



It is  $\Delta J_{42} = \min_{i \in I_\Theta, j \in I_{X-\Theta}} \Delta J_{ij} = -25 < 0$

Thus, according to **PAM**,  $\Theta$  will be **replaced** by  $\Theta_{42}$ .

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The PAM algorithm (Example)

**Data set:**  $X = \{x_1, x_2, x_3, x_4, x_5, x_6\}$ , with

$x_1 = [0,3]^T$ ,  $x_2 = [1,3]^T$ ,  $x_3 = [2,3]^T$ ,  $x_4 = [0,0]^T$ ,  $x_5 = [1,0]^T$ ,  $x_6 = [2,0]^T$ .

**Set of medoids:**  $\Theta_{42} = \{x_2, x_5\}$

**Computation of  $J(\Theta_{42}, U_{42})$**  (Squared Euclidean distance is considered):

$x_1 \rightarrow d(x_1, x_2) = 1 < 10 = d(x_1, x_5) \rightarrow u_{12} = 1, u_{15} = 0$

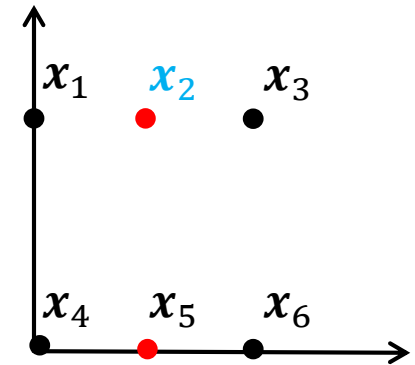
$x_2 \rightarrow d(x_2, x_2) = 0 < 9 = d(x_2, x_5) \rightarrow u_{22} = 1, u_{25} = 0$

$x_3 \rightarrow d(x_3, x_2) = 1 < 10 = d(x_3, x_5) \rightarrow u_{32} = 1, u_{35} = 0$

$x_4 \rightarrow d(x_4, x_2) = 10 > 1 = d(x_4, x_5) \rightarrow u_{42} = 0, u_{45} = 1$

$x_5 \rightarrow d(x_5, x_2) = 9 > 0 = d(x_5, x_5) \rightarrow u_{52} = 0, u_{55} = 1$

$x_6 \rightarrow d(x_6, x_2) = 10 > 1 = d(x_6, x_5) \rightarrow u_{62} = 0, u_{65} = 1$



$$\begin{aligned}
 J(\Theta_{42}, U_{42}) &= u_{12}d(x_1, x_2) + u_{15}d(x_1, x_5) + 1 \cdot 1 + 0 \cdot 10 + \\
 &\quad u_{22}d(x_2, x_2) + u_{25}d(x_2, x_5) + 1 \cdot 0 + 0 \cdot 9 + \\
 &\quad u_{32}d(x_3, x_2) + u_{35}d(x_3, x_5) + 1 \cdot 1 + 0 \cdot 10 + \\
 &\quad u_{42}d(x_4, x_2) + u_{45}d(x_4, x_5) + 0 \cdot 10 + 1 \cdot 1 + \\
 &\quad u_{52}d(x_5, x_2) + u_{55}d(x_5, x_5) + 0 \cdot 9 + 1 \cdot 0 + \\
 &\quad u_{62}d(x_6, x_2) + u_{65}d(x_6, x_5) + 0 \cdot 10 + 1 \cdot 1 \\
 &= 4
 \end{aligned}$$

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

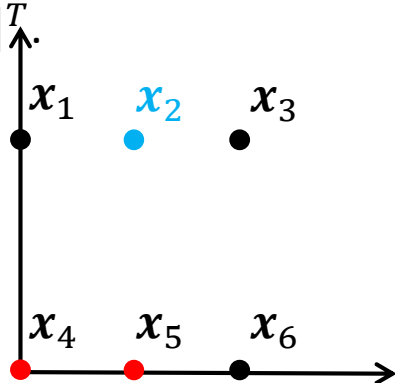
### The PAM algorithm (Example)

**Data set:**  $X = \{x_1, x_2, x_3, x_4, x_5, x_6\}$ , with  
 $x_1 = [0,3]^T, x_2 = [1,3]^T, x_3 = [2,3]^T, x_4 = [0,0]^T, x_5 = [1,0]^T, x_6 = [2,0]^T$

**Sets of medoids:**  $\Theta = \{x_4, x_5\}, \Theta_{42} = \{x_2, x_5\}$

Computation of  $\Delta J_{42}$  as

$\Delta J_{42} = J(\Theta_{42}, U_{42}) - J(\Theta, U) = \sum_{h \in X - \Theta} C_{h42}$  (Sq. Eucl. dist. is used):



	Dist. from Closest repr. in $\Theta =$ $\{x_4, x_5\}$	Dist. from Next closest repr. in $\Theta = \{x_4, x_5\}$	Dist. from closest repr. In $\Theta_{42} = \{x_2, x_5\}$	$C_{h42}$
$x_1$	9 ( $x_4$ )	10 ( $x_5$ )	1 ( $x_2$ )	$1 - 9 = -8$
$x_2$	9 ( $x_5$ )	10 ( $x_4$ )	0 ( $x_2$ )	$0 - 9 = -9$
$x_3$	10 ( $x_5$ )	13 ( $x_4$ )	1 ( $x_2$ )	$1 - 10 = -9$
$x_4$	0 ( $x_4$ )	1 ( $x_5$ )	1 ( $x_5$ )	$1 - 0 = 1$
$x_5$	0 ( $x_5$ )	1 ( $x_4$ )	0 ( $x_5$ )	$0 - 0 = 0$
$x_6$	1 ( $x_5$ )	2 ( $x_4$ )	1 ( $x_5$ )	$1 - 1 = 0$
$\Delta J_{42}$				$-25$

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The CLARA algorithm

- It is more suitable for large data sets.
- **The strategy:**
  - **Draw** randomly a **sample  $X'$**  of size  **$N'$**  from the entire data set.
  - **Run** the **PAM** algorithm to **determine  $\theta'$**  that best represents  $X'$ .
  - Use  $\theta'$  in the place of  $\theta$  to represent the entire data set  $X$ .
- **The rationale:**
  - Assuming that  $X'$  has been selected in a way **representative** of the **statistical distribution** of the **data points** in  $X$ ,  $\theta'$  is expected to be a good approximation of  $\theta$ , which would have been produced if PAM were run on the entire  $X$ .
- **The algorithm:**
  - Draw  $s$  sample subsets of size  $N'$  from  $X$ , denoted by  $X'_1, \dots, X'_s$  (typically  $s = 5, N' = 40 + 2m$ ).
  - Run PAM on each one of them and identify  $\theta'_1, \dots, \theta'_s$ .
  - Choose the set  $\theta'_j$  that minimizes

$$J(\theta, U) = \sum_{i \in I_{X-\theta'}} \sum_{j \in I_{\theta'}} u_{ij} d(\mathbf{x}_i, \mathbf{x}_j)$$

based on the entire data set  $X$ .

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The CLARANS algorithm

- It is more **suitable** for **large data sets**.
- It follows the philosophy of PAM with the difference that only **a randomly selected fraction**  $q(< m(N - m))$  of the **neighbors** of the current medoid set is **considered**.
- It performs several runs ( $s$ ) starting from different initial choices for  $\Theta$ .

### The algorithm:

- For  $i = 1$  to  $s$ 
  - o **Initialize** randomly  $\Theta$ .
  - o **(A) Select** randomly  $q$  neighbors of  $\Theta$ .
  - o For  $j = 1$  to  $q$ 
    - \* **If** the present **neighbor of  $\Theta$**  is **better** than  $\Theta$  (in terms of  $J(\Theta, U)$ ) then
      - **Set  $\Theta$**  equal to **its neighbor**
      - Go to **(A)**
    - \* **End If**
  - o **End For**
  - o Set  $\Theta^i = \Theta$
- **End For**
- **Select** the **best  $\Theta^i$**  with respect to  $J(\Theta, U)$ .
- Based on  $\Theta^i$ , **assign** each  $x \in X - \Theta$  to the cluster whose representative is closest to  $x$

# CFO hard clustering algorithms

## Generalized Hard Algorithmic Scheme (GHAS)

### The CLARANS algorithm (cont.)

#### Remarks:

- **CLARANS** depends on  $q$  and  $s$ . Typically,  $s = 2$  and
$$q = \max(0.125m(N - m), 250)$$
- As  $q$  approaches  $m(N - m)$  CLARANS approaches PAM and the complexity increases.
- CLARANS can also be described in terms of graph theory concepts.
- **CLARANS** unravels **better quality** clusters **than CLARA**.
- In some cases, CLARA is significantly faster than CLARANS.
- **CLARANS** retains its **quadratic computational nature** and thus it is not appropriate for very large data sets.

# Probability and statistics: a brief review

**Random variable (RV):** It models the output of an experiment.

## RV types:

- Discrete
- continuous

## Discrete random variables:

- A **discrete RV**  $x$  can take any value  $x$  from a **finite** or **countably infinite** set  $X$ .
- $X$ : **sample space** or **state space**.
- **Event**: Any **subset** of  $X$ .
- **Elementary or simple event**: A **single element subset** of  $X$ .
- **Example**: Consider the die roll experiment.  $X = \{1, 2, 3, 4, 5, 6\}$
- Events: "Odd number", "number > 3", "2", "5"

Elementary events

# Probability and statistics: a brief review

## Discrete random variables (cont.):

- **Notation:** **Probability** of the **event**  $x=x \in X$ :  $P(x=x) \equiv P(x)$
- $P(\cdot)$ : A function called **probability mass function (pmf)** satisfying
  - ✓  $P(x) \geq 0, \forall x \in X$
  - ✓  $\sum_{x \in X} P(x) = 1$

# Probability and statistics: a brief review

## Discrete random variables (cont.):

*The case of more than one random variables: Definitions*

Discrete RV	$x$	$y$
Sample space	$X=\{x_1, \dots, x_{nx}\}$	$Y=\{y_1, \dots, y_{ny}\}$

**Joint probability:**  $P(x_i, y_j) \equiv P(x=x_i \text{ AND } y=y_j)$

- It corresponds to the case where  $x$  takes the value  $x_i$  **AND**  $y$  takes the value  $y_j$ , **simultaneously**.

**Marginal probabilities:**  $P(x_i) \equiv P(x=x_i)$ ,  $P(y_j) = P(y=y_j)$

- This terminology is used only when more than one rvs are involved.

**Conditional probability:**  $P(x_i | y_j) \equiv P(x=x_i | y=y_j) = P(x_i, y_j) / P(y_j)$

- It corresponds to the case where  $x$  takes the value  $x_i$  **given that**  $y$  takes the value  $y_j$ .

# Probability and statistics: a brief review

## Discrete random variables (cont.):

The case of more than one variables: *Properties*

Discrete RV	$x$	$y$
Sample space	$X = \{x_1, \dots, x_{n_x}\}$	$Y = \{y_1, \dots, y_{n_y}\}$

**Sum rule:**  $P(x) = \sum_{y \in Y} P(x, y), \quad \forall x \in X$

**Product rule:**  $P(x, y) = P(x | y)P(y)$

**Statistical independence:**  $P(x, y) = P(x)P(y)$

A consequence:  $P(x | y) = P(x) \quad P(y | x) = P(y)$

**Bayes rule:**  $P(y | x) = \frac{P(x | y)P(y)}{P(x)}$

It plays a **key role** in **ML**.

or

$$P(y | x) = \frac{P(x | y)P(y)}{\sum_{y \in Y} P(x | y)P(y)}$$

# Probability and statistics: a brief review

## Continuous random variables:

- A **continuous RV**  $x$  can take any value  $x \in R$ .

- **Sample space** or **state space**:  $R$

- **Events**:  $\{x \leq x\}$ ,  $\{x_1 < x \leq x_2\}$ ,  $\{x \geq x\}$

- **Cumulative distribution function (cdf)**:  $F_x(x) = P(x \leq x)$

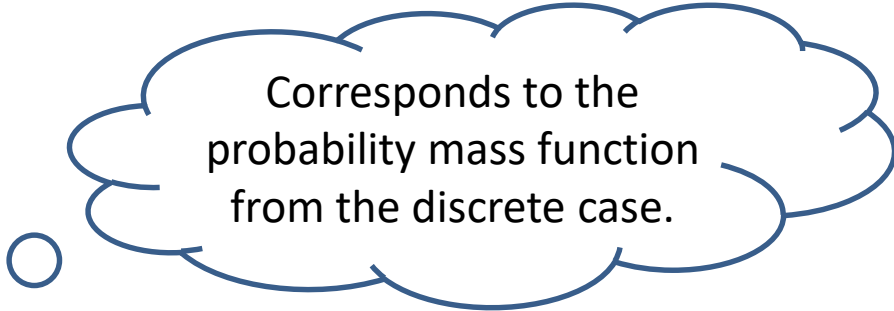
- It is  $F_x(\infty) = P(x < \infty) = 1$

- **Probability of events** in terms of **cdf**:

- $P(x \leq x) = F_x(x)$

- $P(x_1 < x \leq x_2) = P(x \leq x_2) - P(x \leq x_1) = F_x(x_2) - F_x(x_1)$

- $P(x \geq x) = P(x \leq \infty) - P(x \leq x) = 1 - P(x \leq x) = 1 - F_x(x)$



Corresponds to the probability mass function from the discrete case.



It assigns “mass” to events.

# Probability and statistics: a brief review

## Continuous random variables (cont.):

- **Assumption:**  $F_x(x)$  is *continuous* and *differentiable*.

- **Probability density function (pdf):**

$$p_x(x) = \frac{dF_x(x)}{dx}$$

It assigns “mass” to values.

- **cdf in terms of pdf:**

$$F_x(x) = \int_{-\infty}^x p_x(z) dz$$

- **Probability of events in terms of pdf:**

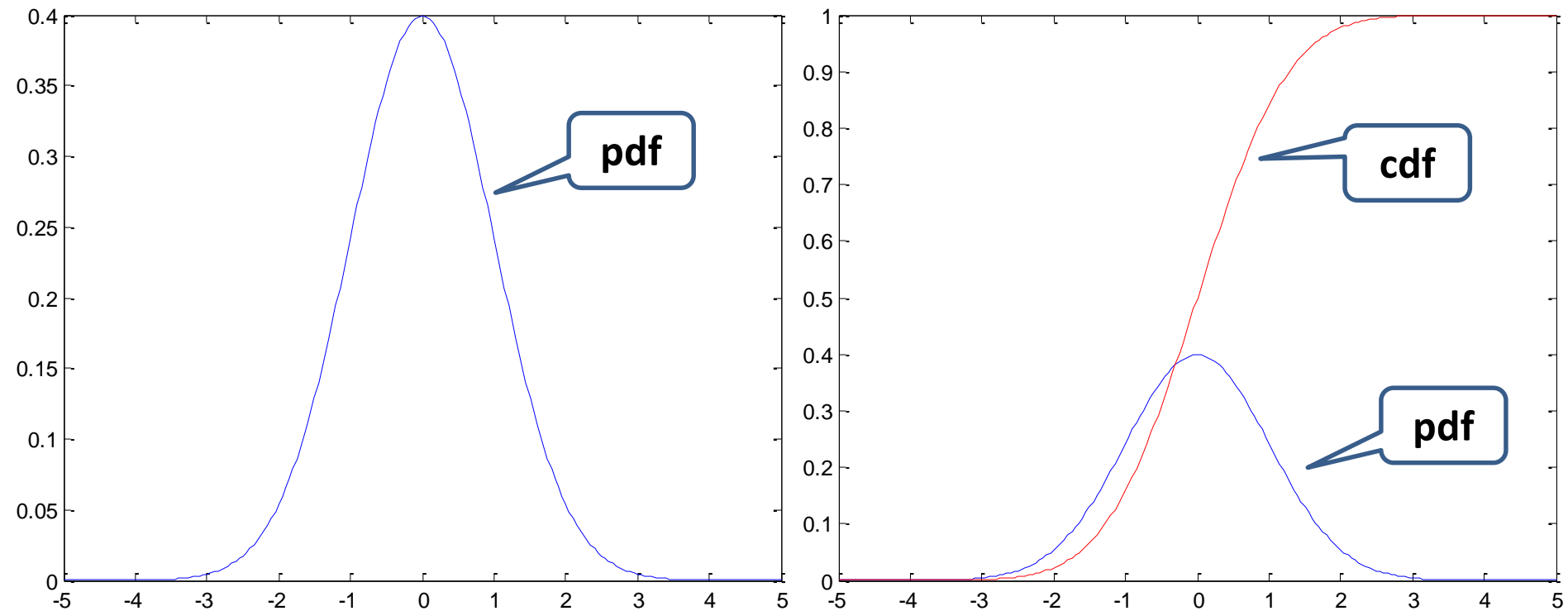
$$\text{➤ } P(x \leq x) = F_x(x) = \int_{-\infty}^x p_x(z) dz$$

$$\text{➤ } P(x_1 < x \leq x_2) = P(x \leq x_2) - P(x \leq x_1) = F_x(x_2) - F_x(x_1) = \int_{x_1}^{x_2} p_x(x) dx$$

$$\text{➤ } P(x \geq x) = P(x \leq \infty) - P(x \leq x) = 1 - P(x \leq x) = 1 - F_x(x) = \int_{-\infty}^x p_x(z) dz$$

# Probability and statistics: a brief review

## Continuous random variables (cont.):



# Probability and statistics: a brief review

## Continuous random variables (cont.):

• Since  $P(-\infty < x < +\infty) = 1$  it is:  $\int_{-\infty}^{+\infty} p_x(x) dx = 1$

• It is  $P(x < x \leq x + \Delta x) = \int_x^{x+\Delta x} p_x(z) dz \approx p_x(x) \Delta x$

As  $\Delta x \rightarrow 0$ ,  $P(x < x < x + \Delta x) = P(x = x) = 0$ .

The **probability** of a **continuous rv** to take a **single value** is **zero**.

The case of more than one variables:

Continuous RV	$x$	$y$
Sample space	$R$	$R$

**NOTE:** All rules stated for the **probability mass function** in the **discrete case** are stated for the **pdf** in the **continuous case**.

### Product rule

$$p(x, y) = p(x | y) p(y)$$

We drop the name of rv from the subscript of  $p$ .

### Sum rule

$$p(x) = \int_{-\infty}^{+\infty} p(x, y) dy$$

# Probability and statistics: a brief review

## Useful quantities related to (continuous) rvs:

For **discrete** rv's, the **integrals** become **summations**.

• Mean (expected) value of a rv  $x$ :  $E[x] = \int_{-\infty}^{+\infty} xp(x)dx$

• Variance of a rv  $x$ :  $\sigma_x^2 = \int_{-\infty}^{+\infty} (x - E[x])^2 p(x)dx = E[(x - E(x))^2]$

• Mean (expected) value of a function of an rv  $x$ :  $E[f(x)] = \int_{-\infty}^{+\infty} f(x)p(x)dx$

• Mean of a function of two rv's  $x, y$ :  $E_{x,y}[f(x, y)] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(x, y)p(x, y)dxdy$

• Conditional mean of an rv  $y$  given  $x = x$ :  $E[y | x] = \int_{-\infty}^{+\infty} yp(y | x)dy$

• It is  $E_{x,y}[f(x, y)] = E_x[E_{y|x}[f(x, y)]]$

• Covariance between two rvs  $x$  and  $y$ :  $\text{cov}(x, y) = E[(x - E[x])(y - E[y])]$

• Correlation between two rv's  $x$  and  $y$ :  $r_{xy} \equiv E(xy) = \text{cov}(x, y) + E[x]E[y]$

• Correlation coefficient  $r_{xy} = \frac{E[x - E[x]](y - E[y])}{\sigma_x \sigma_y}$

# Probability and statistics: a brief review

## Random vectors

- A collection of rvs:  $\mathbf{x} = [x_1, x_2, \dots, x_l]^T$

- Probability density function (pdf) of  $\mathbf{x}$ : The joint pdf of  $x_1, x_2, \dots, x_l$ .  
 $p(\mathbf{x}) = p(x_1, x_2, \dots, x_l)$

- Covariance matrix of  $\mathbf{x}$ :

$$\text{cov}(\mathbf{x}) = E[(\mathbf{x} - E[\mathbf{x}])(\mathbf{x} - E[\mathbf{x}])^T] = \begin{bmatrix} \text{cov}(x_1, x_1) & \cdots & \text{cov}(x_1, x_l) \\ \vdots & \ddots & \vdots \\ \text{cov}(x_l, x_1) & \cdots & \text{cov}(x_l, x_l) \end{bmatrix}$$

- Correlation matrix of  $\mathbf{x}$ :  $R_{\mathbf{x}} = E[\mathbf{x}\mathbf{x}^T] = \begin{bmatrix} E(x_1 x_1) & \cdots & E(x_1 x_l) \\ \vdots & \ddots & \vdots \\ E(x_l x_1) & \cdots & E(x_l x_l) \end{bmatrix}$

- It is  $R_{\mathbf{x}} \equiv E[\mathbf{x}\mathbf{x}^T] = \text{cov}(\mathbf{x}) + E[\mathbf{x}]E[\mathbf{x}^T]$

**Exercise:** Prove this identity

# Probability and statistics: a brief review

## Random vectors (cont.)

**Exercise:** Prove these statements

• Remark: Both  $R_{\mathbf{x}}$  and  $\text{cov}(\mathbf{x})$  are **symmetric** and **positive definite**  $l \times l$  matrices.

A square matrix  
 $A$  is **symmetric**  
iff  $A^T = A$ .

A square matrix  
 $A$  is **positive  
definite** iff  
 $\mathbf{z}^T A \mathbf{z} > 0, \forall \mathbf{z} \in \mathbb{R}^l$ .

# Probability and statistics: a brief review

- One dim. normal (Gaussian) distribution  $x \sim N(\mu, \sigma^2)$  or  $N(x|\mu, \sigma^2)$  :

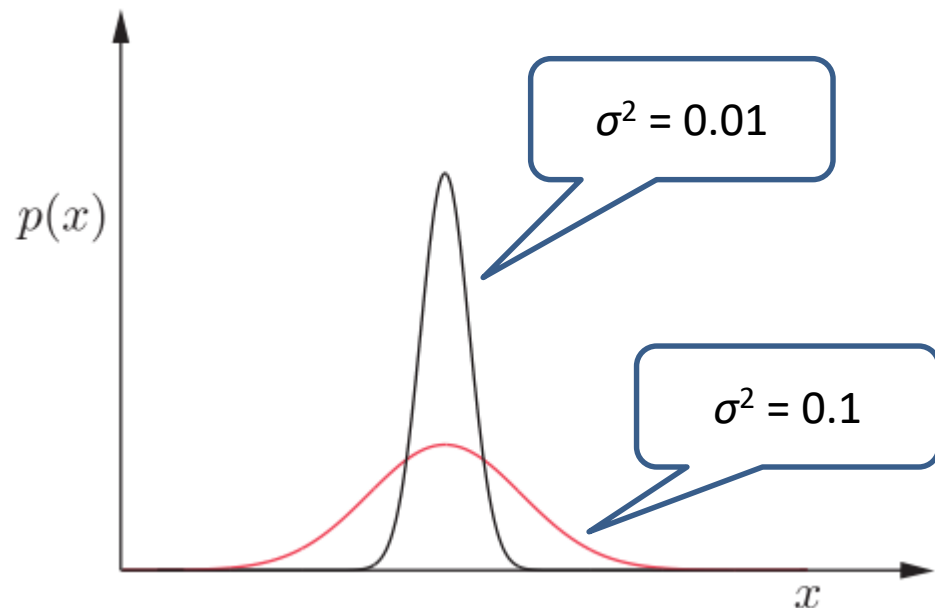
- Sample space:  $\mathcal{R}$

- It is

- $p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$

- $E[x] = \mu$

- $\sigma_x^2 = \sigma^2$ .



# Probability and statistics: a brief review

- Multi dim. normal (Gaussian) distribution  $\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$  or  $N(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$ :

- $l$ -dim. case

- It is

- $p(\mathbf{x}) = \frac{1}{(2\pi)^{l/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}-\boldsymbol{\mu})}{2}\right)$

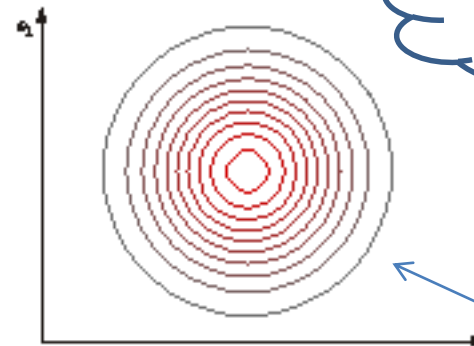
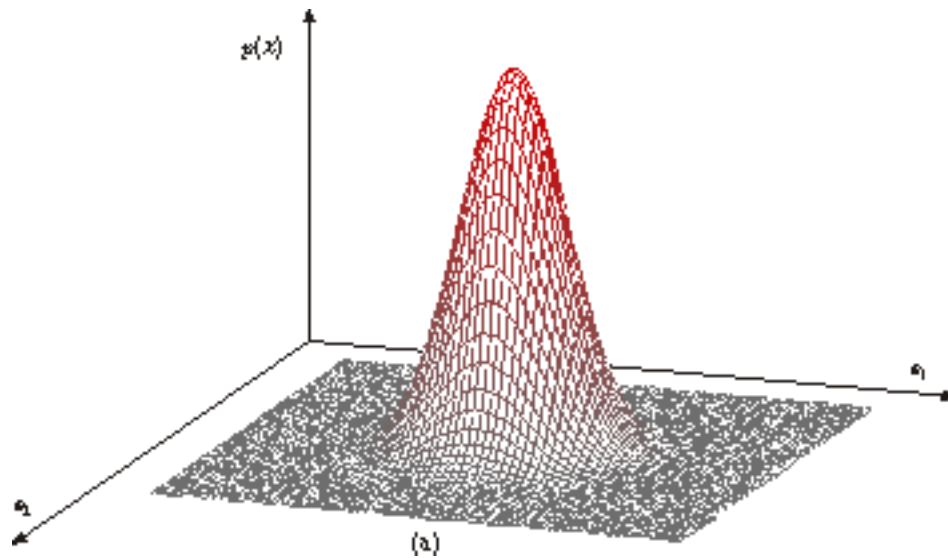
- $E[\mathbf{x}] = \boldsymbol{\mu}$

- $cov(\mathbf{x}) = \boldsymbol{\Sigma}.$

(\*) For the 2-d case  $\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}$

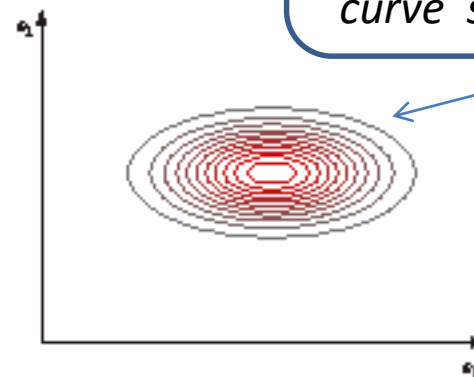
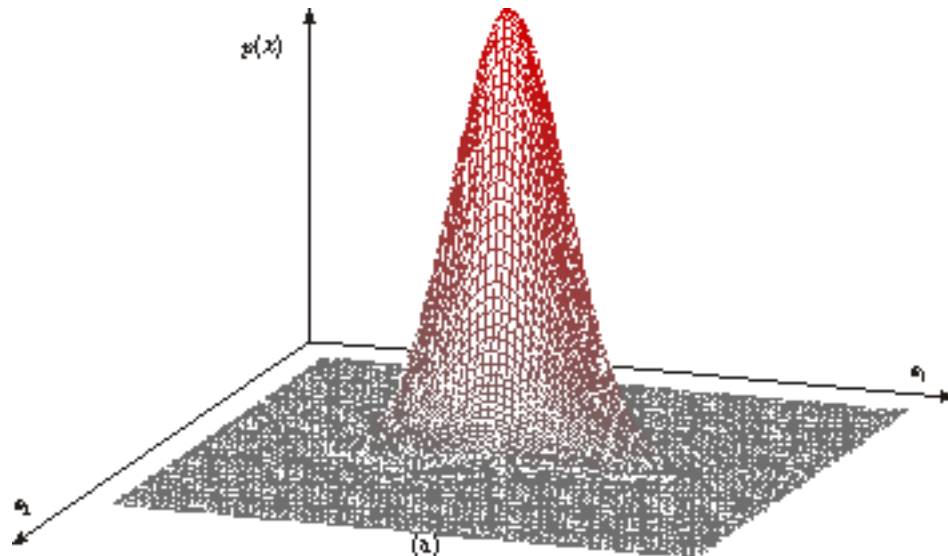
# Probability and statistics: a brief review

- Multi dim. normal (Gaussian) distribution  $\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$  or  $N(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$ :



$$\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}$$

$\boldsymbol{\Sigma}$ : diagonal with  $\sigma_1^2 = \sigma_2^2$



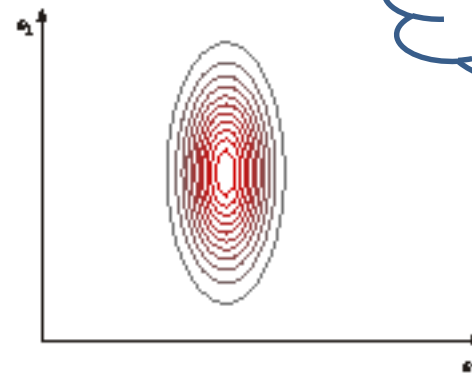
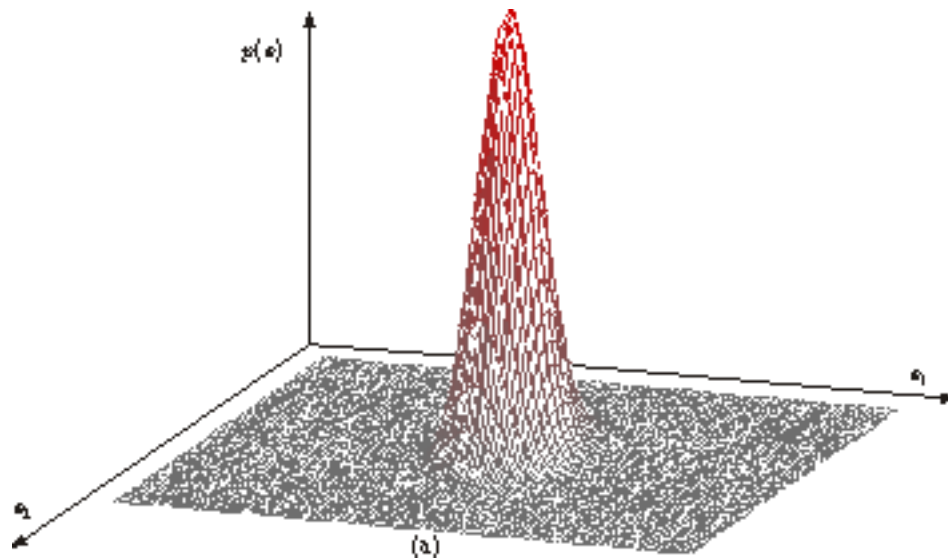
Isovalued curves:

- $(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) = \text{const.}$
- All points on each isovalue curve share the value  $p(\mathbf{x})$ .

$\boldsymbol{\Sigma}$ : diagonal with  $\sigma_1^2 \gg \sigma_2^2$

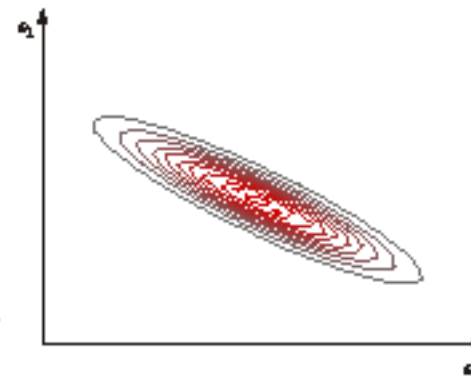
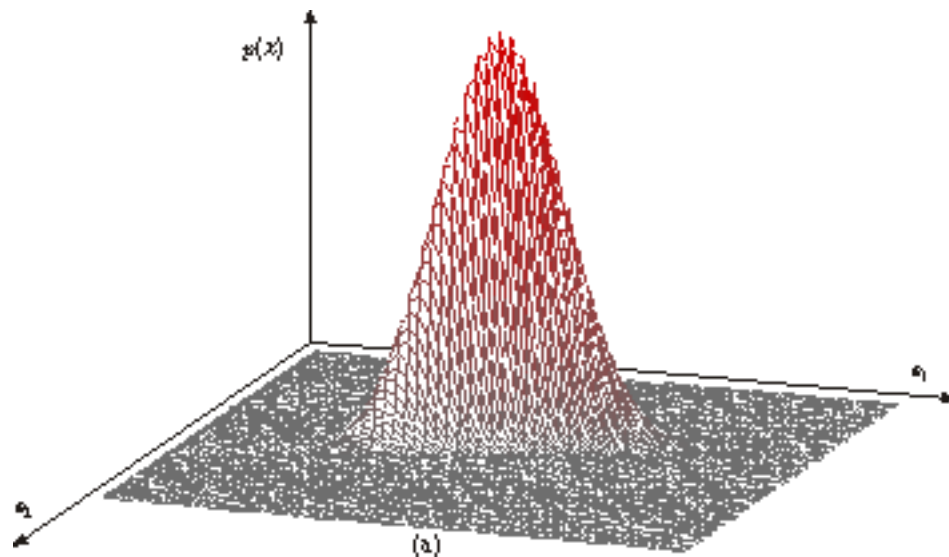
# Probability and statistics: a brief review

- Multi dim. normal (Gaussian) distribution  $\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$  or  $N(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$ :



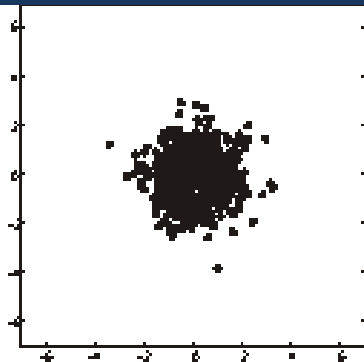
$$\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}$$

$\boldsymbol{\Sigma}$ : diagonal  
with  $\sigma_1^2 \ll \sigma_2^2$

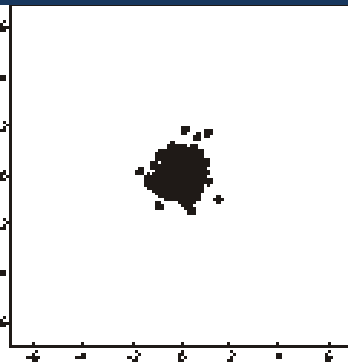


$\boldsymbol{\Sigma}$ : non diagonal

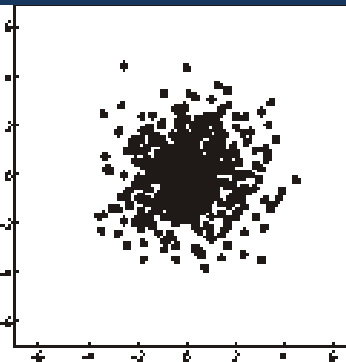
# Probability and statistics: a brief review



(a)



(b)



(c)

$$\Sigma = \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}$$

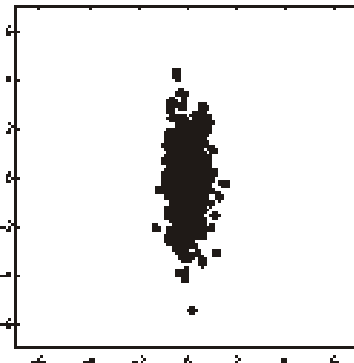
(a)  $\sigma_1^2 = \sigma_2^2 = 1, \sigma_{12} = 0$

(b)  $\sigma_1^2 = \sigma_2^2 = 0.2, \sigma_{12} = 0$

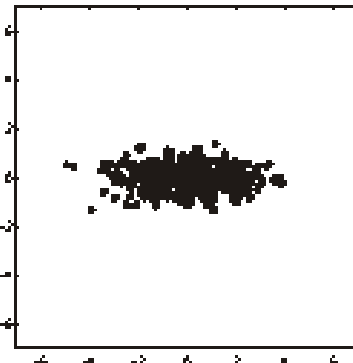
(c)  $\sigma_1^2 = \sigma_2^2 = 2, \sigma_{12} = 0$

(d)  $\sigma_1^2 = 0.2, \sigma_2^2 = 2, \sigma_{12} = 0$

(e)  $\sigma_1^2 = 2, \sigma_2^2 = 0.2, \sigma_{12} = 0$



(d)

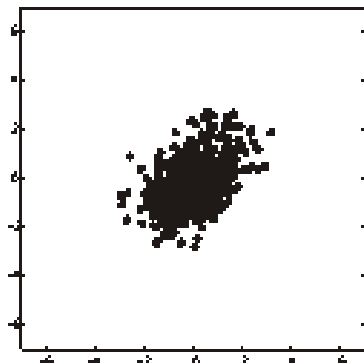


(e)

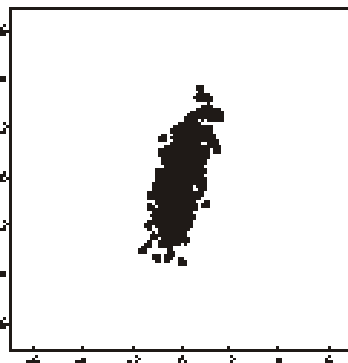
(f)  $\sigma_1^2 = \sigma_2^2 = 1, \sigma_{12} = 0.5$

(g)  $\sigma_1^2 = 0.3, \sigma_2^2 = 2, \sigma_{12} = 0.5$

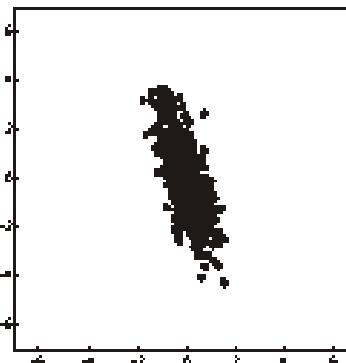
(h)  $\sigma_1^2 = 0.3, \sigma_2^2 = 2, \sigma_{12} = -0.5$



(f)



(g)



(h)

# Probability and statistics: a brief review

## Continuous RV distributions (cont.)

### • Multi dim. normal (Gaussian) distribution $\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ or $N(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$ :

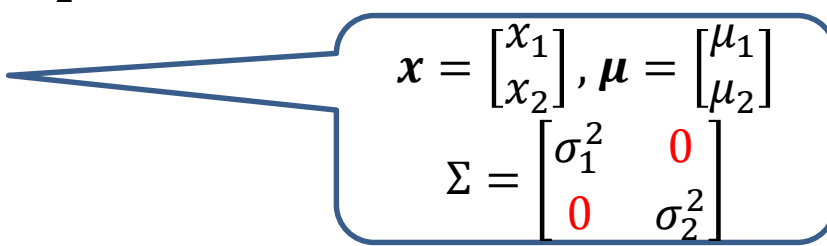
From 1-dim.  $\rightarrow$  2-dim. case.

■ **1-dim. case:**  $p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) = \frac{1}{(2\pi)^{1/2}\sigma} \exp\left(-\frac{(x-\mu)\sigma^{-2}(x-\mu)}{2}\right)$

■ A **first extension** to the 2-dim. case (**independent** rv's):

■  $p(x_1, x_2) = p_1(x_1) \cdot p_2(x_2) =$

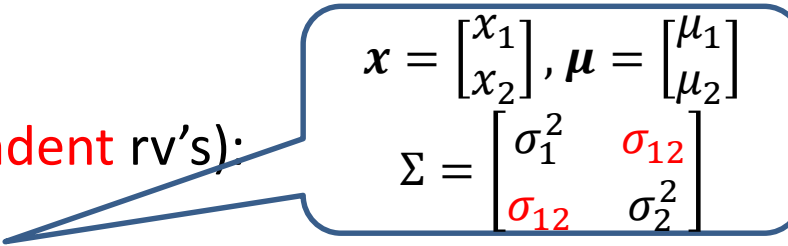
■  $\frac{1}{(2\pi)^{1/2} \cdot \sigma_1} \exp\left(-\frac{(x_1 - \mu_1)\sigma_1^{-2}(x_1 - \mu_1)}{2}\right) \cdot \frac{1}{(2\pi)^{1/2} \cdot \sigma_2} \exp\left(-\frac{(x_2 - \mu_2)\sigma_2^{-2}(x_2 - \mu_2)}{2}\right) =$   
 $\frac{1}{(2\pi)|\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})}{2}\right)$



$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$   
 $\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$

■ The **final extension** to the 2-dim. case (**dependent** rv's):

■  $p(x_1, x_2) = \frac{1}{(2\pi)|\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})}{2}\right)$



$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$   
 $\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}$

# Probability and statistics: a brief review

• Multi dim. normal (Gaussian) distribution  $x \sim N(\mu, \Sigma)$  or  $N(x | \mu, \Sigma)$  :

## ▪ Properties

1. If the covariance matrix  $\Sigma$  is **diagonal**, then, the **rv's**  $x_1, \dots, x_l$  comprising  $\mathbf{x}$  are **statistically independent**. It is

$$p(\mathbf{x}) = \prod_{i=1}^l p_i(x_i) = \prod_{i=1}^l \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp\left(-\frac{(x_i - \mu_i)^2}{2\sigma_i^2}\right)$$

2. Central limit theorem:

Let:

▪  $\mathbf{x}_1, \dots, \mathbf{x}_r$  independent rvs following different distributions

▪  $\mu_i, \sigma_i^2$  mean and variance of  $\mathbf{x}_i$ .

▪ Define  $\mathbf{x} = x_1 + \dots + x_r$ ,  $\mu = \mu_1 + \dots + \mu_r$ ,  $\sigma^2 = \sigma_1^2 + \dots + \sigma_r^2$ .

▪ Define  $\mathbf{z} = (\mathbf{x} - \mu)/\sigma$ .

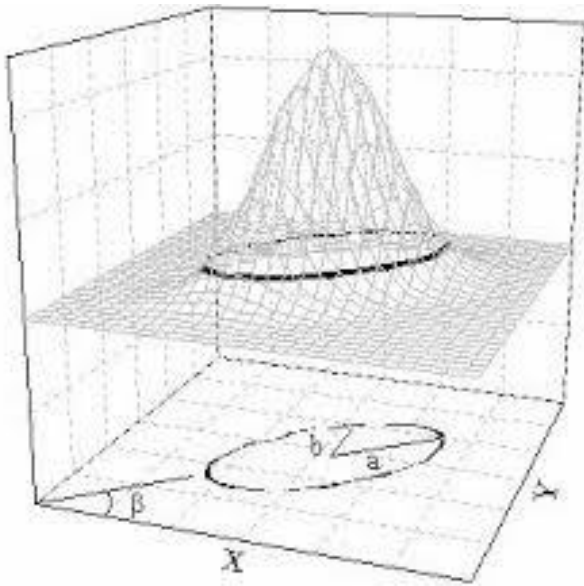
Then

▪  $p(\mathbf{z}) \rightarrow N(\mathbf{z}|0,1)$ , as  $r \rightarrow \infty$

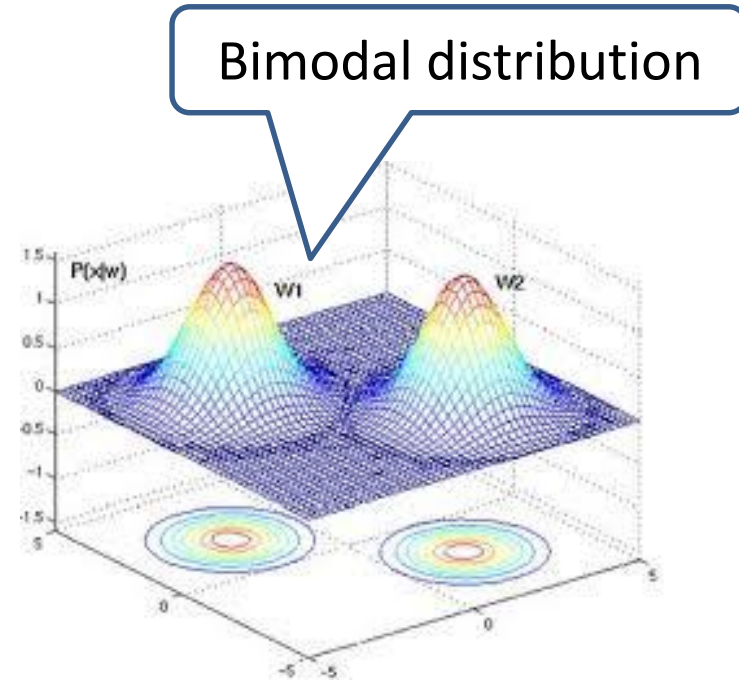
# Probability and statistics: a brief review

## Continuous RV distributions (cont.)

### ▪ Other examples of multi-dimensional pdfs



Two-dim. pdfs



# Probability and statistics: a brief review

## Likelihood function

- Let  $X = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\}$  a set of independent data vectors
- Let  $p_{\theta}(\cdot)$  be a pdf belonging to a **known parametric set of pdf functions** of parameter vector  $\theta$ .
- $p(\mathbf{x}) = p_{\theta}(\mathbf{x}) \equiv p(\mathbf{x}; \theta)$ .

### Examples:

- If  $p_{\theta}(\mathbf{x})$  is **normal** distribution **parameterized** on the mean vector  $\mu$ ,  $\theta$  will simply be  $\mu$ .
- If  $p_{\theta}(\mathbf{x})$  is **normal** distribution **parameterized** on both the mean vector  $\mu$  and the cov. matrix  $\Sigma$ ,  $\theta$  will contain the coordinates of both  $\mu$  and  $\Sigma$ .

**Likelihood function** of  $\theta$  wrt  $X$ :  $p(X; \theta) = p(\mathbf{x}_1, \dots, \mathbf{x}_N; \theta) = \prod_{i=1}^N p(\mathbf{x}_i; \theta)$

**Log-likelihood function** of  $\theta$  wrt  $X$ :

$$L(\theta) = \ln p(X; \theta) = \ln p(\mathbf{x}_1, \dots, \mathbf{x}_N; \theta) = \sum_{i=1}^N \ln p(\mathbf{x}_i; \theta)$$

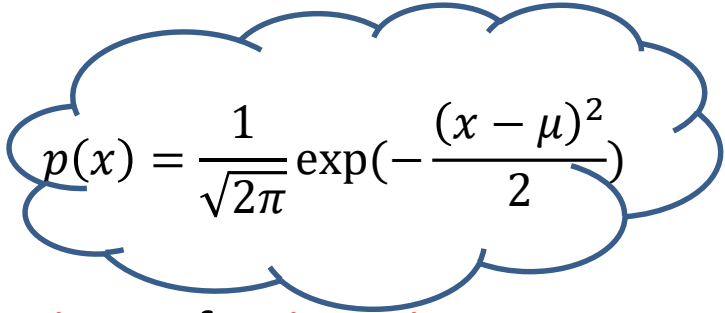
# Probability and statistics: a brief review

## Likelihood function

### Example:

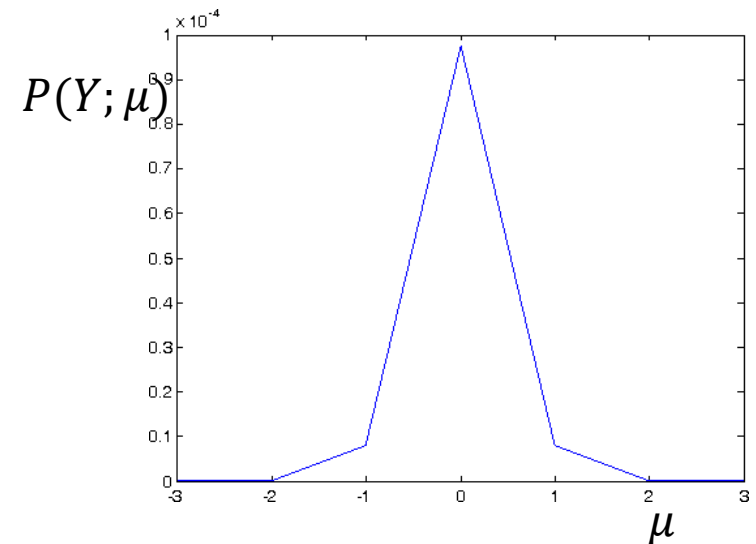
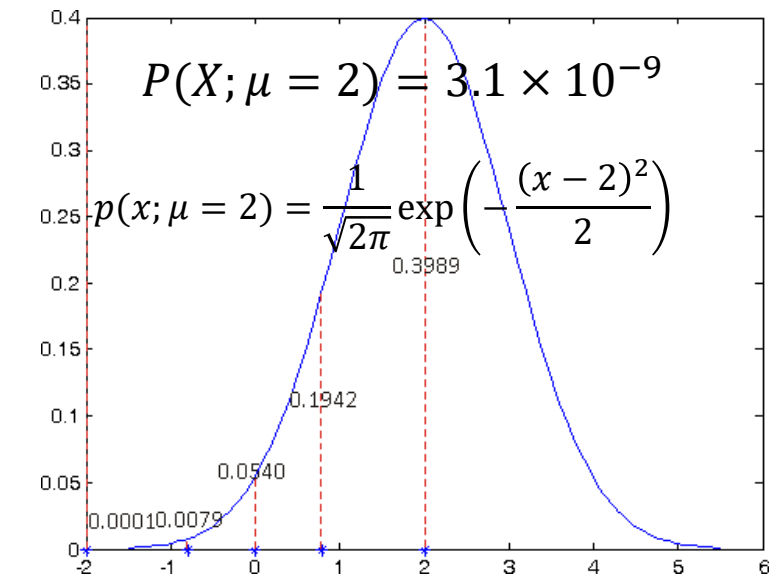
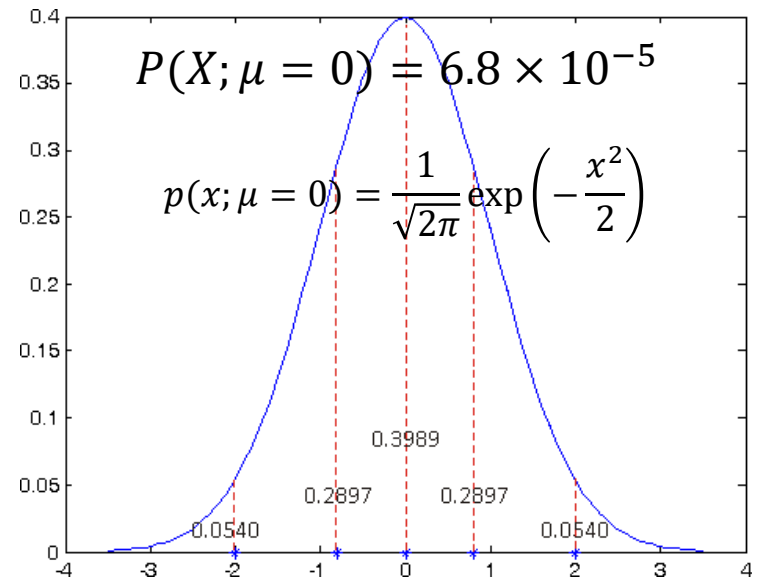
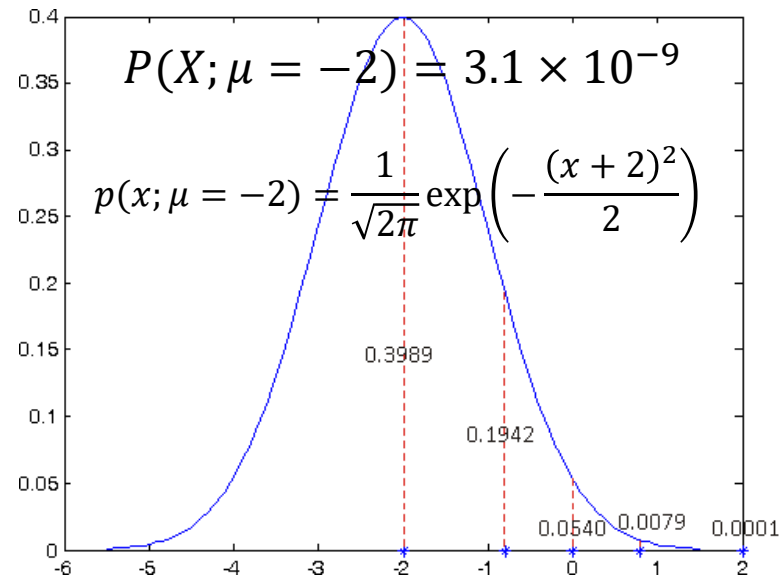
- $X = \{-2, -1, 0, 1, 2\}$
- Consider the **parametric set** of **normal distributions** of **unit variance**, parameterized on  $\mu$ .
- The likelihood of  $\mu$  wrt  $X$  is

$$p(X; \mu) = p(-2, -1, 0, 1, 2; \mu) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(-2-\mu)^2}{2}\right) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(-1-\mu)^2}{2}\right) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(0-\mu)^2}{2}\right) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(1-\mu)^2}{2}\right) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(2-\mu)^2}{2}\right)$$


$$p(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2}\right)$$

# Probability and statistics: a brief review

## Likelihood function



# Probabilistic CFO clustering algorithms

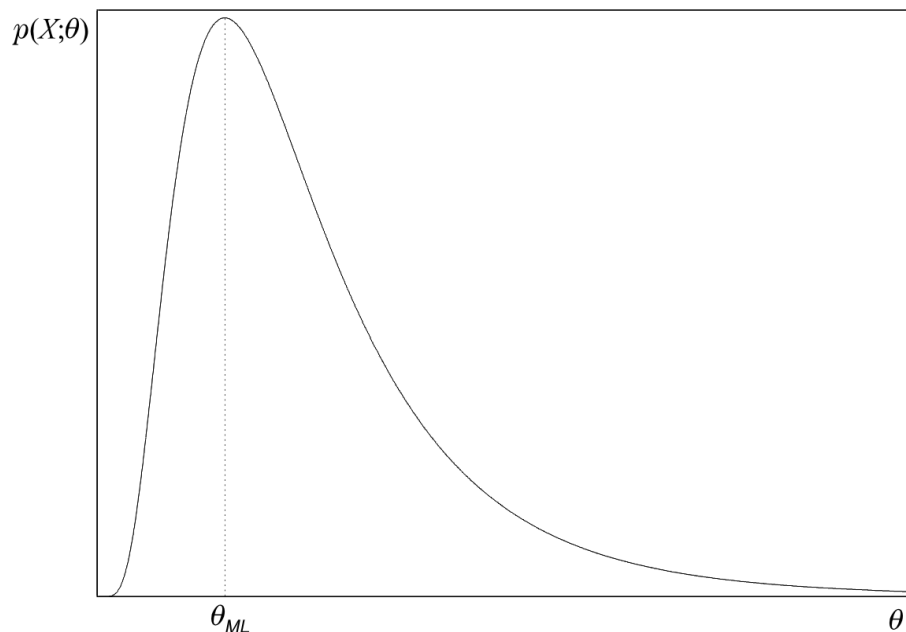
## Maximum likelihood (ML) method:

Given a set of independent data vectors  $Y = \{x_1, x_2, \dots, x_N\}$ ,  
**estimate** the parameter vector  $\theta$  as the **maximum** of the **likelihood** ( $p(Y; \theta)$ ) or  
the **log-likelihood** ( $L(\theta)$ ) function.

$$\hat{\theta}_{ML} = \operatorname{argmax}_{\theta} p(Y; \theta)$$

→

$$\hat{\theta}_{ML}: \frac{\partial L(\theta)}{\partial \theta} = \sum_{k=1}^N \frac{1}{p(x_k; \theta)} \frac{\partial p(x_k; \theta)}{\partial \theta} = \mathbf{0}$$



Since  $\ln(\cdot)$  is an **increasing**  
**function**,  $p(Y; \theta)$  and  $L(\theta)$   
share the **same maxima**.

# Probabilistic CFO clustering algorithms

## Maximum likelihood (ML) method:

### Assuming that

- the chosen model  $p(\mathbf{x}; \boldsymbol{\theta})$  is **correct** and
- there **exists** a true parameter  $\boldsymbol{\theta}_o$ ,

### the ML estimator

- (a) is **asymptotically unbiased**  $\lim_{N \rightarrow \infty} E[\hat{\boldsymbol{\theta}}_{ML}] = \boldsymbol{\theta}_o$
- (b) is **asymptotically consistent**  $\lim_{N \rightarrow \infty} Prob\{\|\hat{\boldsymbol{\theta}}_{ML} - \boldsymbol{\theta}_o\|\} = 0$
- (c) is **asymptotically efficient** (it achieves the **Cramer-Rao** lower **bound**)

The **pdf** of the ML estimator **approaches** the **normal distribution** with mean  $\boldsymbol{\theta}_o$ , as  $N \rightarrow \infty$ .

# Maximum likelihood method

## Example 1:

-Let  $Y$  be a set of  $N$  (independent from each other) data points,  $\mathbf{x}_i$ ,  $i = 1, \dots, N$ , generated by a normal distribution  $p(\mathbf{x}; \boldsymbol{\theta})$  of known covariance matrix and unknown mean.

-Determine the ML estimate of the mean  $\boldsymbol{\mu}$  of  $p(\mathbf{x}; \boldsymbol{\theta})$ , based on  $Y$ .

## Solution:

-The unknown parameter vector in this case is the mean vector  $\boldsymbol{\mu}$ , i.e.  $\boldsymbol{\theta} \equiv \boldsymbol{\mu}$ .

-It is

$$p(\mathbf{x}; \boldsymbol{\theta}) \equiv p(\mathbf{x}; \boldsymbol{\mu}) = \frac{1}{(2\pi)^{l/2} |\Sigma|^{1/2}} \cdot \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) \Rightarrow$$

$$\ln p(\mathbf{x}; \boldsymbol{\mu}) = \ln \frac{1}{(2\pi)^{l/2} |\Sigma|^{1/2}} - \frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu}) = C - \frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})$$

Then

$$L(\boldsymbol{\mu}) = \sum_{i=1}^N \ln p(\mathbf{x}_i; \boldsymbol{\mu}) = NC - \frac{1}{2} \sum_{i=1}^N (\mathbf{x}_i - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x}_i - \boldsymbol{\mu})$$

# Maximum likelihood method

## Example 1 (cont.):

Setting the **gradient** of  $L(\boldsymbol{\mu})$  wrt  $\boldsymbol{\mu}$  equal to  $\mathbf{0}$  we have

$$\frac{\partial L(\boldsymbol{\mu})}{\partial \boldsymbol{\mu}} = \frac{\partial}{\partial \boldsymbol{\mu}} \left( NC - \frac{1}{2} \sum_{i=1}^N (\mathbf{x}_i - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) \right) = \mathbf{0} \Leftrightarrow$$

$$\sum_{i=1}^N \Sigma^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) = \mathbf{0} \Leftrightarrow \sum_{i=1}^N (\mathbf{x}_i - \boldsymbol{\mu}) = \mathbf{0} \Leftrightarrow \sum_{i=1}^N \mathbf{x}_i - N\boldsymbol{\mu} = \mathbf{0}$$

$$\boldsymbol{\mu}_{ML} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i$$

**Remark:** The **ML estimate** for the **covariance matrix** is

$$\Sigma_{ML} = \frac{1}{N} \sum_{i=1}^N (\mathbf{x}_i - \boldsymbol{\mu})(\mathbf{x}_i - \boldsymbol{\mu})^T$$