Clustering algorithms

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Unit 2

- Proximity functions between vectors
- Proximity functions between sets
- Proximity functions between a point and a set

(A) Between vectors

(1) Dissimilarity measure (between vectors of X) is a function

$$d: X \times X \to \Re$$

with the following properties

1.
$$\exists d_0 \in \Re: \mathbf{0} \leq d_0 \leq d(x, y) < +\infty, \forall x, y \in X$$

2.
$$d(\mathbf{x}, \mathbf{x}) = d_0, \forall \mathbf{x} \in X$$

3. $d(x, y) = d(y, x), \forall x, y \in X$

Examples: Euclidean distance, Manhattan distance etc.

If in addition:

4.
$$d(x, y) = d_0 \Leftrightarrow x = y$$

5.
$$d(x, z) \le d(x, y) + d(y, z), \forall x, y, z \in X$$
 (triangular inequality)

d is called **metric** dissimilarity measure.

(A) Between vectors

(2) Similarity measure (between vectors of X) is a function

$$s: X \times X \to \Re$$

Examples: inner product, Tanimoto distance etc.

with the following properties

1.
$$\exists s_0 \in \Re: 0 \leq s(x, y) \leq s_0 < +\infty, \forall x, y \in X$$

2.
$$s(x, x) = s_0, \forall x \in X$$

3.
$$s(x, y) = s(y, x), \forall x, y \in X$$

If in addition:

4.
$$s(x, y) = s_0 \Leftrightarrow x = y$$

5.
$$\frac{1}{s(x,z)} \le \frac{1}{s(x,y)} + \frac{1}{s(y,z)}, \forall x, y, z \in X$$

NOTE:

Similarity measures and dissimilarity measures are also referred as proximity measures.

NOTATION:

- Similarity measure: s dissimilarity measure: d
- proximity measures:

s is called **metric** similarity measure.

Exercise:

Consider the case where the elements of *X* are **scalars**.

Which of the following is

- (a) a dissimilarity measure,
- **(b)** a **metric** dissimilarity measure?

1.
$$d_1(x, y) = |x - y|$$

2.
$$d_2(x,y) = |x^2 - y^2|$$

3.
$$d_3(x, y) = \cos(x - y)$$

4.
$$d_4(x, y) = \sin(|x - y|)$$

(B) Between sets

Let
$$D_i \subset X$$
, $i = 1, ..., k$, and $U = \{D_1, ..., D_k\}$.

A **proximity measure** (similarity or dissimilarity) \wp on U is a function $\wp: U \times U \to \Re$

For dissimilarity measure the following properties should hold

1.
$$\exists d_0 \in \Re: 0 \le d_0 \le d(D_i, D_j) < +\infty, \forall D_i, D_j \in X$$

2.
$$d(D_i, D_i) = d_0, \forall D_i \in X$$

3.
$$d(D_i, D_j) = d(D_j, D_i), \forall D_i, D_j \in X$$

Question: What is the definition when \wp stands for a similarity measure?

If in addition:

$$4. \quad d(D_i, D_j) = d_0 \iff D_i = D_j$$

5.
$$d(D_i, D_k) \le d(D_i, D_j) + d(D_j, D_k), \forall D_i, D_j, D_k \in X$$

d is called **metric** dissimilarity measure.

(B) Between sets

NOTE: The **definition** of the <u>proximity functions between sets</u> **passes through** the definition of <u>proximity functions between a point and a set</u>.

Roadmap for the next few slides:

Proximity functions between a point and a set

- Nonparametric case
- Parametric case
 - Point representatives
 - Mean vector
 - Mean center
 - Median center
 - > Hyperplane representatives
 - > Hypersphere representatives
 - **>** ..

(B) Between sets

NOTE: The **definition** of the <u>proximity functions between sets</u> **passes through** the definition of <u>proximity functions between a point and a set</u>.

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Proximity functions between a point and a set

Remark: Having in mind that a cluster is actually a set C, a proximity function between a point x and a set C actually quantifies the resemblance/relation of \boldsymbol{x} with the cluster \boldsymbol{C} .

Let
$$X = \{x_1, \dots, x_N\}$$
 and $\mathbf{x} \in X$, $\mathbf{C} \subset X$

Definitions of $\wp(x,C)$:

(a) All points of C contribute to the definition of $\wp(x,C)$ (nonparametric repr.). $d^{ps}_{max}(x,C) = max_{y \in C}d(x,y)$ $s^{ps}_{max}(x,C) = max_{y \in C}s(x,y)$

Max proximity function

$$\wp^{ps}_{max}(\mathbf{x}, C) = max_{\mathbf{y} \in C} \wp(\mathbf{x}, \mathbf{y})$$

Min proximity function

$$\wp^{ps}_{min}(x,C) = min_{y \in C} \wp(x,y)$$

Average proximity function

$$d^{ps}_{avg}(x,C) = \frac{1}{n_c} \sum_{y \in C} d(x,y)$$
unction
$$s^{ps}_{avg}(x,C) = \frac{1}{n_c} \sum_{y \in C} s(x,y)$$

$$p^{ps}_{avg}(x,C) = \frac{1}{n_c} \sum_{y \in C} s(x,y)$$

$$n_C \text{ is the cardinality of } C.$$

$$d^{ps}_{min}(x,C) = min_{y \in C}d(x,y)$$

$$s^{ps}_{min}(x,C) = min_{y \in C}s(x,y)$$

$$s \in C \mathscr{D}(x,y)$$

(B) Between sets

NOTE: The **definition** of the <u>proximity functions between sets</u> **passes through** the definition of <u>proximity functions between a point and a set</u>.

Roadmap for the next few slides:

Proximity functions between a point and a set

- Nonparametric case
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 - > Hypersphere representatives
 - > ...

Proximity functions between a point and a set

Definitions of $\wp(x,C)$ (cont.):

(b) A representative of C, r_C , contributes to the definition of $\wp(x,C)$ (parametric repr.).

$$\wp(\mathbf{x},C)=\wp(\mathbf{x},r_C)$$

In this case

Typical **point** representatives are:

The mean vector

 n_C is the cardinality of C.

d: dissimilarity

$$\boldsymbol{m}_p = \frac{1}{n_C} \sum_{\mathbf{y} \in C} \mathbf{y}$$

The mean center

$$m_C \in C$$
: $\sum_{y \in C} d(m_C, y) \le \sum_{y \in C} d(z, y), \forall z \in C$

The median center

$$m_{med} \in C: med(d(m_{med}, y)|y \in C) \leq med(d(z, y)|y \in C), \forall z \in C$$

NOTE: Other representatives (e.g., hyperplanes, hyperspheres) are useful in certain applications (e.g., object identification using clustering techniques).

Proximity functions between a point and a set

Definitions of $\wp(x,C)$ (cont.):

(b) A representative of C, r_C , contributes to the definition of $\wp(x,C)$. In this case $\wp(x,C)=\wp(x,r_C)$

Exercise 5: Let $C = \{x_1, x_2, x_3, x_4, x_5\}$, where $\mathbf{x_1} = [1,1]^T$, $\mathbf{x_2} = [3,1]^T$, $\mathbf{x_3} = [1,2]^T$, $\mathbf{x_4} = [1,3]^T$, $\mathbf{x_5} = [3,3]^T$. All points lie in the discrete space $\{0,1,2,\ldots,6\}^2$. Use the Euclidean distance to measure the dissimilarity between two vectors in C.

- (a) Determine the mean vector, the mean center and the median center of C.
- (b) Compute the distance of point $\mathbf{x} = [6,4]^T$ from \mathbf{C} using the above defined representatives (where it is valid).

(B) Between sets

NOTE: The **definition** of the <u>proximity functions between sets</u> **passes through** the definition of <u>proximity functions between a point and a set</u>.

Roadmap for the next few slides:

Proximity functions between a point and a set

Nonparametric case

Parametric case

- Point representatives
 - Mean vector
 - Mean center
 - Median center
- Hyperplane representatives
- > Hypersphere representatives
- > ..

Proximity functions between a point and a set

Definitions of $\wp(x, C)$ (cont.):

(b) A representative of C, r_C , contributes to the definition of $\wp(x,C)$.

In this case
$$\wp(x,C) = \wp(x,r_C)$$

Linear-shaped clusters:

- Such clusters occur e.g., in computer vision applications.
- In this case, a hyperplane is a better representative of such clusters
- Equation of a hyperplane *H*:

$$\sum_{j=1}^{l} a_j x_j + a_0 = \mathbf{a}^T \mathbf{x} + a_0 = 0$$

where $\mathbf{x} = [x_1, x_2, ..., x_l]^T$, $\mathbf{a} = [a_1, a_2, ..., a_l]^T$ is the direction vector of \mathbf{H} and \mathbf{a}_0 is its offset.

- Distance of a point x from $H: d(x, H) = min_{z \in H} d(x, z)$
- If d(x, z) is the Euclidean distance, it is

$$d(x, H) = \frac{|a^T x + a_0|}{||a||} \qquad ||a|| = \sqrt{\sum_{j=1}^{l} \alpha_j^2}$$

Proximity functions between a point and a set

Definitions of $\wp(x, C)$ (cont.):

(b) A representative of C, r_C , contributes to the definition of $\wp(x,C)$.

In this case
$$\wp(x,C) = \wp(x,r_C)$$

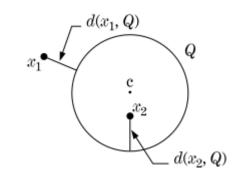
Hyperspherical clusters:

- Such clusters occur e.g., in computer vision applications.
- In this case, a hypersphere is a better representative of such clusters
- Equation of a hypersphere Q:

$$(\mathbf{x} - \mathbf{c})^T (\mathbf{x} - \mathbf{c}) = r^2$$

 $(x-c)^T(x-c)=r^2$ where $x=[x_1,x_2,...,x_l]^T$, $\mathbf{c}=[c_1,c_2,...,c_l]^T$ is the center of \mathbf{Q} and \mathbf{r} is its radius.

- Distance of a point ${m x}$ from ${m Q}$: ${m d}({m x},{m Q})=min_{{m z}\in Q}d({m x},{m z})$
- For Euclidean distance between two points, d(x, Q) has a geometric insight.



However, other non-geometric alternatives have also been proposed.

Proximity functions between two sets

Remark: Having in mind that a cluster is actually a set C, a proximity function between two sets actually quantifies the resemblance/relation between two clusters.

Let
$$X = \{x_1, ..., x_N\}$$
 and $D_i, D_j \subset X$ with $n_i = |D_i|, n_j = |D_j|$.

Definitions of $\wp(D_i, D_i)$:

(a) All points of each set **contribute** to the definition of $\wp(D_i, D_i)$.

unction
$$S^{SS}_{max}(D_i, D_j) = max_{x \in D_i, y \in D_j} S(x, y)$$
$$S^{SS}_{max}(D_i, D_j) = max_{x \in D_i, y \in D_j} S(x, y)$$

Min proximity function

Inction
$$s^{ss}_{min}(D_i, D_j) = min_{x \in D_i, y \in D_j} s(x, y)$$
$$\mathscr{D}^{ss}_{min}(D_i, D_j) = min_{x \in D_i, y \in D_j} \mathscr{D}(x, y)$$

sity function
$$s^{ss}_{avg}(D_i, D_j) = \frac{1}{n_i n_j} \sum_{x \in D_i} \sum_{y \in D_i} s(x, y)$$

$$\delta^{ss}_{avg}(D_i, D_j) = \frac{1}{n_i n_j} \sum_{x \in D_i} \sum_{y \in D_i} \delta(x, y)$$
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 $d^{ss}_{max}(D_i, D_j) = max_{x \in D_i, y \in D_j} d(x, y)$

 $d^{SS}_{min}(D_i, D_j) = min_{x \in D_i, y \in D_j} d(x, y)$

 $d^{SS}_{avg}(D_i, D_j) = \frac{1}{n_i n_i} \sum_{x \in D_i} \sum_{y \in D_i} d(x, y)$

Proximity functions between two sets

Definitions of $\wp(D_i, D_i)$ (cont.):

- (b) Each set D_i is represented by a point representative m_i .
- Mean proximity function

$$\mathcal{D}^{SS}_{mean}(D_i, D_j) = \mathcal{D}(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

$$d^{SS}_{mean}(D_i, D_j) = d(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

$$s^{SS}_{mean}(D_i, D_j) = s(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

$$-\mathcal{D}^{SS}_{e}(D_i, D_j) = \sqrt{\frac{n_i n_j}{n_i + n_j}} \mathcal{D}(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

$$d^{SS}_{e}(D_i, D_j) = \sqrt{\frac{n_i n_j}{n_i + n_j}} d(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

$$s^{SS}_{e}(D_i, D_j) = \sqrt{\frac{n_i n_j}{n_i + n_j}} d(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

$$s^{SS}_{e}(D_i, D_j) = \sqrt{\frac{n_i n_j}{n_i + n_j}} s(\boldsymbol{m}_i, \boldsymbol{m}_j)$$

NOTE: Proximity functions between a vector \mathbf{x} and a set \mathbf{C} may be derived from the above functions if we set $D_i = {\mathbf{x}}$.

In the sequel we consider the cases:

- (A) Real-valued vectors **dissimilarity** measures (DMs)
- $\mathbf{x} = [x_1, \dots, x_l]^T$ $\mathbf{y} = [y_1, \dots, y_l]^T$
- (B) Real-valued vectors **similarity** measures (SMs)
- (C) Discrete-valued vectors **similarity-dissimilarity** measures
- (D) Mixed-valued vectors **dissimilarity** and **similarity** measures

NOTE: Some of the measures below may seem "weird". However, they have been tailored for certain types of applications.

(A) Real-valued vectors – dissimilarity measures (DMs)

• Weighted l_p metric DMs

DMs
$$d_p(\boldsymbol{x}, \boldsymbol{y}) = \left(\sum_{i=1}^l w_i |x_i - y_i|^p\right)^{1/p}$$

Interesting instances are obtained for:

$$p = 1 \rightarrow d_1(x, y) = \sum_{i=1}^l w_i |x_i - y_i|$$
 (l_1 or Manhattan or city block dist.)

$$p=2 \rightarrow d_2(\mathbf{x},\mathbf{y}) = \sqrt{\sum_{i=1}^l w_i (x_i - y_i)^2}$$
 (l_2 or Euclidean distance)

$$p = \infty \rightarrow d_{\infty}(\mathbf{x}, \mathbf{y}) = \max_{i=1,\dots,l} w_i |x_i - y_i| (l_{\infty} \text{ or maximum distance})$$

NOTES:

 \checkmark For $w_i = 1$, we obtain the unweighted versions of the l_p metrics.

$$\checkmark$$
 It holds: $d_{\infty}(x, y) \leq d_{2}(x, y) \leq d_{1}(x, y)$

(A) Real-valued vectors – dissimilarity measures (DMs)

Mahalanobis distance

$$d(\mathbf{x}, \mathbf{y}) = \sqrt{(\mathbf{x} - \mathbf{y})^T B(\mathbf{x} - \mathbf{y})}$$

$$\mathbf{x} = [x_1, ..., x_l]^T$$

$$\mathbf{y} = [y_1, ..., y_l]^T$$

B is symmetric, positive definite matrix

• Other measures

$$-d_G(\mathbf{x}, \mathbf{y}) = -log_{10} \left(1 - \frac{1}{l} \sum_{i=1}^{l} \frac{|x_i - y_i|}{|b_i - a_i|} \right)$$

 Features may take positive and/or negative values

•Normalization per feature:

$$0 \le \frac{|x_i - y_i|}{|b_i - a_i|} \le 1$$

where b_i and a_i are the maximum and the minimum values of the i-th feature, among the vectors of X (dependence on the current data set)

$$-d_Q(\mathbf{x}, \mathbf{y}) = \sqrt{\frac{1}{l} \sum_{i=1}^{l} \left(\frac{x_i - y_i}{x_i + y_i}\right)^2}$$

- Features may take only non-negative values
- •Normalization per feature:

$$0 \le \frac{|x_i - y_i|}{x_i + y_i} \le 1$$

(B) Real-valued vectors –similarity measures (SMs)

• Inner product

$$\mathbf{x} = [x_1, \dots, x_l]^T$$

$$\mathbf{y} = [y_1, \dots, y_l]^T$$

$$s_{inner}(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbf{y} = \sum_{i=1}^l x_i y_i$$

- It is usually used either (i) for non-negative valued vectors or (ii) for normalized vectors, i.e., $||x|| = \rho$.
- Concerning (ii), in order to comply with the non-negativity requirement in the definition of the similarity measure, we may consider the similarity measure s_{inner}(x, y) + ρ²

Cosine similarity measure

$$s_{cosine}(x, y) = \frac{x^T y}{||x|| \cdot ||y||}$$

where
$$||x|| = \sqrt{x^T x} = \sqrt{\sum_{i=1}^l x_i^2}$$
 and $||y|| = \sqrt{y^T y} = \sqrt{\sum_{i=1}^l y_i^2}$.

- (B) Real-valued vectors -similarity measures (SMs)
- Pearson's correlation coefficient

$$r_{Pearson}(x, y) = \frac{x_d^T y_d}{||x_d|| \cdot ||y_d||} \in [-1, 1]$$

where
$$\mathbf{x}_d = [x_1 - \bar{x}, ..., x_l - \bar{x}]^T$$
, $\mathbf{y}_d = [y_1 - \bar{y}, ..., y_l - \bar{y}]^T$ with $\bar{x} = \frac{1}{l} \sum_{i=1}^l x_i$ and $\bar{y} = \frac{1}{l} \sum_{i=1}^l y_i$, respectively.

A related dissimilarity measure:

$$D(x, y) = \frac{1 - r_{Pearson}(x, y)}{2} \in [0, 1]$$

 $\mathbf{x} = [x_1, \dots, x_l]^T$ $\mathbf{y} = [y_1, \dots, y_l]^T$

(covariance)

between x, 3

(B) Real-valued vectors –similarity measures (SMs)

Tanimoto distance

$$\mathbf{x} = [x_1, \dots, x_l]^T$$

$$\mathbf{y} = [y_1, \dots, y_l]^T$$

$$s_T(x, y) = \frac{x^T y}{||x||^2 + ||y||^2 - x^T y}$$

Algebraic manipulations give

$$s_T(\mathbf{x}, \mathbf{y}) = \frac{1}{1 + \frac{(\mathbf{x} - \mathbf{y})^T (\mathbf{x} - \mathbf{y})}{\mathbf{x}^T \mathbf{y}}}$$

The larger the agreement between x, y, the larger the $s_T(x,y)$.

NOTE: $s_T(x, y)$ is inversely proportional to the Euclidean distance and proportional to the inner product.

Other measure:

$$s_C(x, y) = 1 - \frac{\sqrt{(x - y)^T (x - y)}}{||x|| + ||y||} \in [0, 1]$$

(C) Discrete-valued vectors – similarity & dissimilarity measures (SMs-DMs)

Let F_i be the **discrete** set of values the *i*-th feature (nominal/categorical

attribute) can take

and n_i be its cardinality, i = 1, ..., l.

$$\mathbf{x} = [x_1, \dots, x_l]^T$$

$$\mathbf{y} = [y_1, \dots, y_l]^T$$

Consider two *l*-dimensional vectors

$$\mathbf{x} = [x_1, x_2, ..., x_k, ..., x_l]^T \in F_1 \times F_2 \times ... \times F_k \times ... \times F_l$$

$$\mathbf{y} = [y_1, y_2, ..., y_k, ..., y_l]^T \in F_1 \times F_2 \times ... \times F_k \times ... \times F_l$$

The similarity measure s(x, y) is defined as

$$s(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^{l} w_k s_k(x_k, y_k)$$

where $s_k(x_k, y_k)$ is the **feature** similarity measure between the values x_k, y_k of the k-th feature.

Thus, in order to define s(x, y), we need to **define** $s_k(x_k, y_k)$.

(C) Discrete-valued vectors – similarity & dissimilarity measures (SMs-DMs)

Example: Let l=3 and

$$F_1 = \{a, b, c\}$$

 $F_2 = \{1, 2, 3, 4\}$
 $F_3 = \{A, B, C\}$

 $\mathbf{x} = [x_1, \dots, x_l]^T$ $\mathbf{y} = [y_1, \dots, y_l]^T$

Consider the vectors:

$$\mathbf{x} = [x_1, x_2, x_3]^T = [a, 2, A]^T$$

 $\mathbf{y} = [y_1, y_2, y_3]^T = [a, 3, B]^T$

That is,
$$x_1 = a$$
, $y_1 = a$, $x_2 = 2$, $y_2 = 3$, $x_3 = A$, $y_3 = B$.

Thus

$$s_1(x_1, y_1) = s_1(a, a)$$

 $s_2(x_2, y_2) = s_2(2, 3)$
 $s_3(x_3, y_3) = s_3(A, B)$

and

$$s(\mathbf{x}, \mathbf{y}) = w_1 \cdot s_1(a, a) + w_2 \cdot s_2(2, 3) + w_3 \cdot s_3(A, B)$$

(C) Discrete-valued vectors – similarity & dissimilarity measures (SMs-DMs)

Let F_i be the **discrete** set of values the *i*-th (nominal/categorical) feature can

take and
$$n_i$$
 be its cardinality, $i=1,...,l$.

$$s(x,y) = \sum_{k=1}^{l} w_k s_k(x_k, y_k)$$

Recall that, in order to define s(x, y), we need to **define** $s_k(x_k, y_k)$.

Each $s_k(\cdot, \cdot)$ is completely **defined** by the associated similarity matrix.

If $F_k = \{1, 2, ..., q\}$, the similarity matrix associated with the k-th feature is

	1	2		\boldsymbol{q}
1	$s_k(1,1)$	$s_k(1,2)$		$s_k(1,q)$
2	$s_k(2,1)$	$s_k(2,2)$		$s_k(2,q)$
			••	
q	$s_k(q,1)$	$s_k(q,2)$		$s_k(q,q)$

NOTE: (a) The similarity matrix is completely defined if all of its entries are defined.

(b) Such a similarity matrix is

associated with a similarity measure for a single discrete-valued feature.

(C) Discrete-valued vectors – similarity & dissimilarity measures (SMs-DMs) There are plenty of similarity measures for single discrete-valued features.

Defining such a similarity measure ⇔ **filling** the entries of the similarity matrix.

- The entries filling may be carried out by utilizing:
- Simply 0 and 1 entries
- The size of the data set N
- The number of attributes n involved in the current problem
- The cardinality of F_q , n_q .
- The number of times, $f_k(j)$, the j-th symbol is encountered as k-th feature in the data set
- The frequency of occurrence of the j-th symbol as k-th feature in the data set, defined as $\hat{p}_k(j) = f_k(j)/N$, or, in some cases, $p_k^2(j) = \frac{f_k(j)(f_k(j)-1)}{N(N-1)}$

	1	2		q
1	$s_k(1,1)$	$s_k(1,2)$		$s_k(1,q)$
2	$s_k(2,1)$	$s_k(2,2)$		$s_k(2,q)$
			٠.	
q	$s_k(q,1)$	$s_k(q,2)$		$s_k(q,q)$

- (C) Discrete-valued vectors similarity & dissimilarity measures (SMs-DMs) These similarity measures can be categorized in terms of:
- ✓ The <u>way they fill the entries of the similarity matrix</u>
 - I. Fill the diagonal entries only
 - II. Fill the non-diagonal entries only
 - III. Fill both diagonal and non-diagonal entries
- ✓ The <u>arguments they use to define the measure</u> (information theoretic, probabilistic etc).

- (C) Discrete-valued vectors similarity & dissimilarity measures (SMs-DMs) Indicative measures from category I: Fill the diagonal entries only.

Goodall3 measure

$$s_{k}(x_{k}, y_{k}) = \begin{cases} 1 - p_{k}^{2}(x_{k}), & \text{if } x_{k} = y_{k} \\ 0, & \text{otherwise} \end{cases}, \ w_{k} = \frac{1}{l}$$

$$s_{k}(x_{k}, y_{k}) \in [0, 1 - \frac{2}{N(N-1)}]$$

Comment: It **assigns** a high similarity **if** the matching values are **infrequent** regardless of the frequencies of the other values.

(C) Discrete-valued vectors – similarity & dissimilarity measures (SMs-DMs) Indicative measures from category II: Fill the non-diagonal entries only.

 $s_{k}(x_{k}, y_{k}) = \begin{cases} 1, & \text{if } x_{k} = y_{k} \\ \frac{n_{k}^{2}}{n_{k}^{2} + 2}, & \text{otherwise} \end{cases}, \quad w_{k} = \frac{1}{l}$

Comments:

- It gives more weight to mismatches for attributes that take many values.
- It has been used for record-based network intrusion detection data.

Inverse Occurrence Frequency (IOF) measure
$$s_k(x_k, y_k) \in \left[\frac{1}{1 + (\log \frac{N}{2})^2}, 1\right]$$

$$s_k(x_k, y_k) = \begin{cases} 1, & \text{if } x_k = y_k \\ \frac{1}{1 + \log f_k(x_k) \cdot \log f_k(y_k)}, & \text{otherwise} \end{cases}, \quad w_k = \frac{1}{l}$$
Comments:

Comments:

- It assigns lower similarity to mismatches on more frequent values...
- It is related to the concept of inverse document frequency which comes from information retrieval, where it is used to signify the relative number of documents that contain a specific word. 29

- (C) Discrete-valued vectors similarity & dissimilarity measures (SMs-DMs) Indicative measures from category III: Fill both diagonal & non-diagonal entries
- Lin measure

$$\begin{split} s_k(x_k,y_k) &= \begin{cases} 2 \cdot log \hat{p}_k(x_k), & if \ x_k = y_k \\ 2 \cdot log (\hat{p}_k(x_k) + \hat{p}_k(y_k)), & otherwise \end{cases}, \\ w_k &= \frac{1}{\sum_{i=1}^l (log \, \hat{p}_i(x_i) + log \hat{p}_i(y_i))} \end{split}$$

 $s_k(x_k, y_k) \in [-2logN, 0]$ for match $s_k(x_k, y_k) \in [-2log\frac{N}{2}, 0]$ for mismatch

Comments:

It gives

- higher weight to matches on frequent values, and
- lower weight to mismatches on infrequent values.

It has been **used** in word similarity procedure.

(*) S. Boriah, V. Chandola, and V. Kumar, "Similarity measures for categorical data: A Comparative Evaluation," in *Proc. SDM*, pp. 243-254, 2008.

(C) Discrete-valued vectors – similarity & dissimilarity measures (SMs-DMs)

	Feat. 1	Feat. 2	Feat. 3
x_1	а	1	А
\boldsymbol{x}_2	b	4	В
\boldsymbol{x}_3	а	3	В
x_4	С	2	Α
x_5	а	2	Α
\boldsymbol{x}_6	а	2	В
x_7	b	1	В
x_8	С	1	Α
x_9	b	1	Α
x_{10}	а	3	В
x_{11}	а	4	А
<i>x</i> ₁₂	b	4	С
<i>x</i> ₁₃	b	3	А
x_{14}	С	2	Α
<i>x</i> ₁₅	а	2	С

Exercise 1: Consider the data set *X* given in the adjacent table.

Determine the similarity between the vectors

$$\mathbf{x} = [a, 2, A]^T$$
 and

$$\mathbf{y} = [a, 3, B]^T$$
 utilizing

- (a) The overlap measure
- (b) The Goodall3 measure
- (c) The Eskin measure
- (d) The IOF measure
- (e) The Lin measure.

Exercise 2: Define corresponding dissimilarity measures for the above defined similarity measures.