

Inversion

$f: B \subseteq \mathbb{R}^3 \rightarrow \mathbb{R}$ ενεχνις

B xy-αντίο i yx-αντίο i ... , αντίο

$\vec{\tau}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $\vec{\tau}(u, v, w) = (x(u, v, w), y(u, v, w), z(u, v, w))$ ηερασχηματισμός

1-1

$$\vec{\tau}(u, v, w) = \frac{\partial(x, y, z)}{\partial(u, v, w)}(u, v, w) = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{pmatrix}(u, v, w)$$

πιτ οπίζωντα $\left| \frac{\partial(x, y, z)}{\partial(u, v, w)}(u, v, w) \right| \neq 0$

ΤΩΤΕ

$$\iiint_B f(x, y, z) dxdydz = \iiint_{\vec{\tau}^{-1}(B)} L(x(u, v, w), y(u, v, w), z(u, v, w)) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)}(u, v, w) \right| du dv dw$$

dudv dw
αντίκρυς τύπος οπίζωντα

► $f \equiv 1$:

$$V(B) = \iiint_{\vec{\tau}^{-1}(B)} \left| \frac{\partial(x, y, z)}{\partial(u, v, w)}(u, v, w) \right| du dv dw, \text{ οχυρός στο } B$$

Άσυμμετρο II: (Αντίκρυς ηερασχημάτων σε οχυρισμένους)

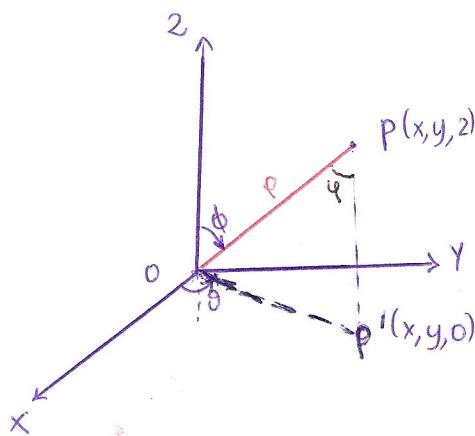
Ιντεινών: Χρησιμοποιήστε οχυρισμένες συνεπαγγελίες οπαν
στο πρόβλημα τας υπάρχαντης επιφέρειας ως προς

ΣΗΜΕΙΟ!



Ynewdilion: Հարթության նորմալներ

$$\varphi = \sqrt{x^2 + y^2 + z^2}$$



$$\theta = \angle (Ox, OP)$$

$$\varphi = \angle (Oz, OP)$$

$$x = OP' \cos \theta = \rho \cdot \sin \phi \cdot \cos \theta$$

$$y = OP' \sin \theta = \rho \cdot \sin \phi \cdot \sin \theta$$

$$z = \rho \cdot \sin \phi = \rho \cdot \sin \phi$$

]

Opi2awca: Հպ. Խեցախիռչեկա'

$$\vec{r}(\rho, \theta, \phi) = (\rho \cdot \sin \theta \cdot \cos \phi, \rho \cdot \sin \theta \cdot \sin \phi, \rho \cdot \cos \theta), \rho > 0, \theta \in [0, 2\pi], \phi \in [0, \pi]$$

$$\frac{\partial r(x, y, z)}{\partial (\rho, \theta, \phi)} = \begin{pmatrix} \sin \theta \cos \phi & -\rho \sin \theta \cdot \sin \phi & \rho \sin \theta \cos \phi \\ \sin \theta \sin \phi & \rho \sin \theta \cdot \cos \phi & \rho \cdot \cos \theta \cos \phi \\ \cos \theta & 0 & -\rho \sin \phi \end{pmatrix}$$

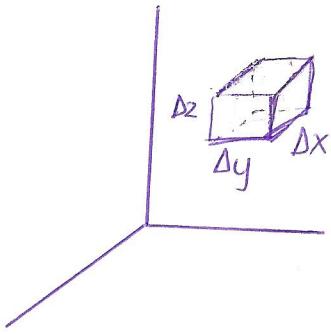
$$\text{op'i2awca} \Leftrightarrow \frac{\partial (x, y, z)}{\partial (\rho, \theta, \phi)} = \sin \theta (-\rho^2 \sin^2 \theta \cos \phi \cos \phi - \rho^2 \sin^2 \theta \sin \phi \cos \phi) - \rho \sin \theta \left(\rho \cdot \sin^2 \theta \sin^2 \phi + \frac{\rho \cdot \sin^2 \theta \cos^2 \phi}{\rho \cdot \sin^2 \theta \sin^2 \phi} \right)$$

$$= -\rho^2 \sin^2 \theta \cdot \sin \theta \cos \phi - \rho^2 \sin \theta \cdot \sin \theta \sin \phi = -\rho^2 \sin \theta \cos \phi$$

$$\cancel{\rho^2} \quad \left| \begin{array}{c} \cancel{\rho^2} \\ \frac{\partial (x, y, z)}{\partial (\rho, \theta, \phi)} \end{array} \right| \quad \left| \begin{array}{c} = \rho^2 \sin \theta \cos \phi \end{array} \right.$$

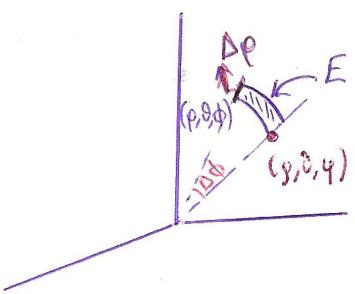


► Ηια υάνοια προσέχουν τω τίνα αλλαγής περιβάντων



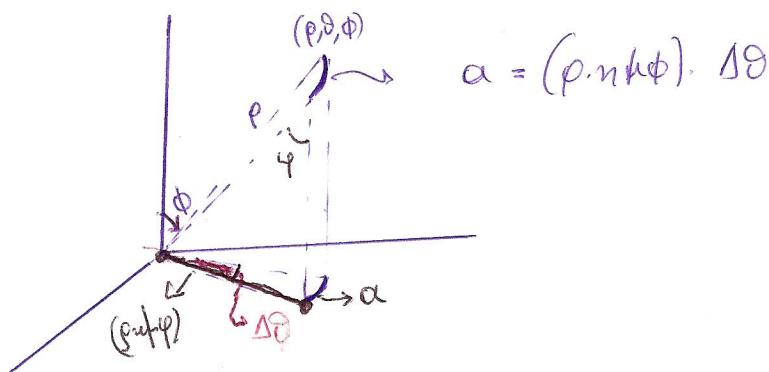
Tas παρεγκατευτές
ο στοιχειώδης όγκος είναι
 $\Delta x \Delta y \Delta z$. ($\Delta x, \Delta y, \Delta z$ σταθερά).

Den εξαρτάται κανό τις παρεγκατευτές
των προσεγκατευτών.



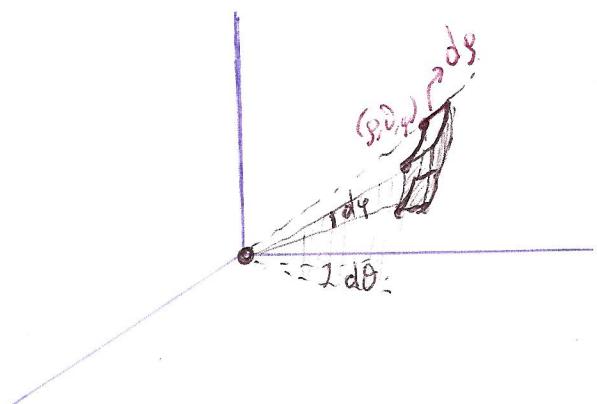
Δ=σταθερό

$$E = (\rho \cdot \Delta \phi) \cdot \Delta p \quad (E = \text{εφεδρόν})$$



$$\alpha = (\rho \cdot n \cdot \mu \cdot \phi) \cdot \Delta \theta$$

Στοιχειώδης όγκος είναι $E \cdot \alpha = \rho^2 \cdot n \cdot \mu \cdot \phi \cdot \Delta \rho \cdot \Delta \theta \cdot \Delta \phi$
 $\Delta x \Delta y \Delta z = \rho^2 \cdot n \cdot \mu \cdot \phi \cdot \Delta \rho \cdot \Delta \theta \cdot \Delta \phi$



www.tf.uni-kiel.de/~matwissamat/elmat_en/Kap3/basics/b3_2_2.html

Αριθμετικής (ευθύνεται ως προς την αριθμ.)

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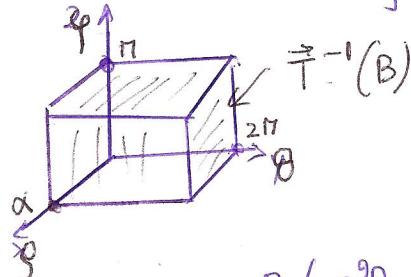
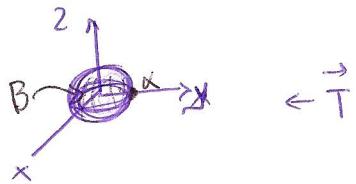
$$\iint_B \iiint f(x,y,z) dx dy dz = \iiint_{T^{-1}(B)} f(\rho \cdot \sin \theta \cos \phi, \rho \cdot \sin \theta \sin \phi, \rho \cdot \cos \theta) \rho^2 \sin \theta d\rho d\theta d\phi$$

$$V(B) = \iiint_{T^{-1}(B)} (\rho^2 \sin \theta) d\rho d\theta d\phi$$

1) Να βρεθεί ο όγκος των σφαιρών

$$B = \{ (x,y,z) \in \mathbb{R}^3, x^2 + y^2 + z^2 \leq a^2 \} \quad a > 0$$

$$T^{-1}(B) = \{ (\rho, \theta, \phi) : 0 \leq \rho \leq a, 0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi \}$$



$$V(B) = \int_0^\pi \left[\int_0^{2\pi} \left(\int_0^a (\rho^2 \sin \theta) d\rho \right) d\theta \right] d\phi = \int_0^\pi \left(\int_0^{2\pi} \frac{a^3}{3} \sin \theta d\theta \right) d\phi =$$

$$= \frac{2\pi a^3}{3} \left(\int_0^\pi \sin \theta d\theta \right) = \frac{2\pi a^3}{3} (6\pi) = \frac{2\pi a^3}{3} (1+1) = \frac{4\pi a^3}{3}$$

* Ηπορίων να γράψουν και το κυρτόδικό φτωτοχυτικό

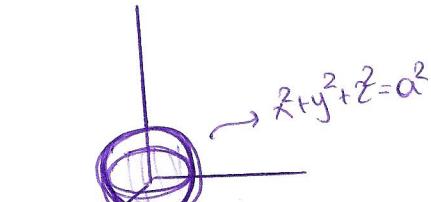
$$2) B = \left\{ (x, y, z) : x^2 + y^2 \leq z^2, x^2 + y^2 + z^2 \leq a^2, z \geq 0 \right\} \quad (a > 0)$$

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i) Na vnozognosi o ógros $V(B)$

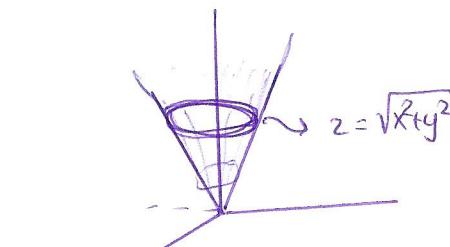
ii) $\Rightarrow \iiint_{B'} \sqrt{x^2 + y^2 + z^2} dx dy dz$, B' to nukfiai to B
Genni In crepeia juvia $(x, y, z \geq 0)$

i)



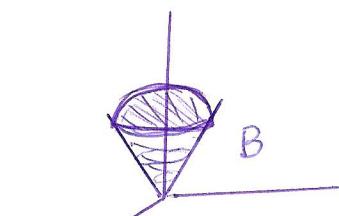
$\sum \text{6p. eurazifives:}$

$$\rho = a$$



$\sum \text{6p. eurazifives:}$

$$\varphi = \frac{\pi}{4}$$



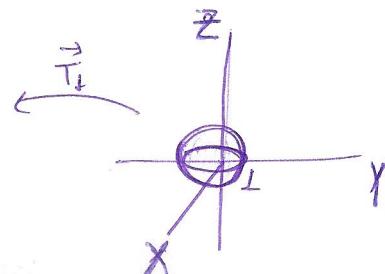
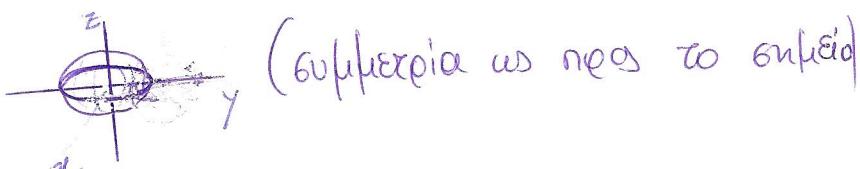
$$\vec{T}^{-1}(B) = \left\{ (\rho, \theta, \phi) : 0 \leq \rho \leq a, 0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi/4 \right\}$$

$$V(B) = \int_0^{n/4} \int_0^{2\pi} \left(\int_0^a (\rho^2 \sin \phi) d\rho \right) d\theta d\phi = \frac{2\pi}{3} a^3 \left(1 - \frac{\sqrt{2}}{2} \right)$$

$$ii) I = \int_0^{n/4} \int_0^{2\pi} \int_0^a \rho (\rho^2 \sin \phi) d\rho d\theta d\phi = \pi/8 \cdot a^4 \left(1 - \frac{\sqrt{2}}{2} \right)$$

$$3) B = \left\{ (x, y, z) : \left(\frac{x}{a} \right)^2 + \left(\frac{y}{b} \right)^2 + \left(\frac{z}{c} \right)^2 \leq 1 \right\}$$

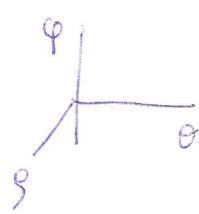
na vnozognosi o ógros $V(B)$



$$\vec{T}_1(X, Y, Z) = (aX, bY, cZ)$$

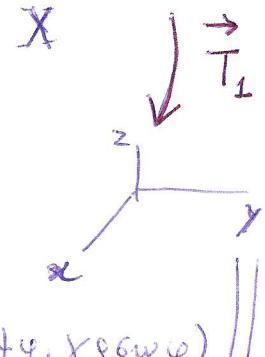
$$\vec{T}_1^{-1}(B) = \left\{ (X, Y, Z) : X^2 + Y^2 + Z^2 \leq 1 \right\}$$

$$\begin{array}{l|l} x = \frac{x}{a} & x = a \cdot X \\ y = \frac{y}{\beta} & y = \beta \cdot Y \\ z = \frac{z}{\gamma} & z = \gamma \cdot Z \end{array}$$



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$$\vec{T} = 6\varphi \cdot p_1 \cdot K_0 \cdot t \cdot \vec{z}$$



i) $T_{\text{eff}}(k)$
 $x = p \cdot \sin \vartheta \cdot n \mu \phi$
 $y = p \cdot n \mu \phi \cdot n \mu \phi$

$$(s, \vartheta, \varphi) \xrightarrow{\vec{T}} (s \sin \vartheta \cos \varphi, s \sin \vartheta \sin \varphi, s \cos \vartheta)$$

$$\downarrow \vec{T}_1 \xrightarrow{\vec{T}} (x \sin \vartheta \cos \varphi, x \sin \vartheta \sin \varphi, x \cos \vartheta)$$

$z = p \cdot \sin \phi$

$$x = a \cdot p \cdot \sin \vartheta \cdot n \mu \phi$$

$$y = \beta \cdot p \cdot n \mu \phi \cdot n \mu \phi$$

$$z = \gamma \cdot p \cdot \sin \phi$$

opisacca $\alpha \beta \gamma p^2 \cdot n \mu \phi$ zoj $\vec{T}_1 \circ \vec{T}$

$$V(B) = \int_0^n \int_0^{2\pi} \int_0^1 \alpha \beta \gamma p^2 \cdot n \mu \phi \cdot d\vartheta d\phi = \frac{4\pi}{3} \alpha \beta \gamma$$

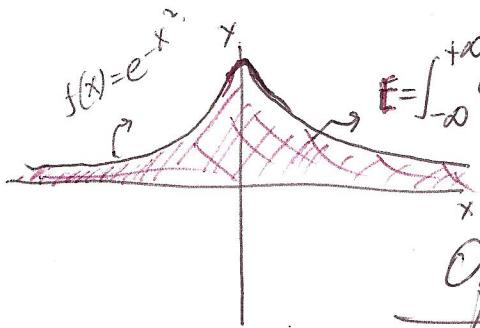
Ačunon (http://en.wikipedia.org/wiki/Gaussian_integral)

Na uoglyčiai

to daudmpūjata

$$ii) \iint_{\mathbb{R}^2} e^{-(x^2+y^2)} dx dy = \lim_{\alpha \rightarrow +\infty} \iint_{\{(x,y) : \sqrt{x^2+y^2} \leq \alpha\}} e^{-(x^2+y^2)} dx dy = \pi$$

$$ii) \text{ v.s.o. } \int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}, \quad \int_0^{+\infty} e^{-x^2} dx = \frac{\sqrt{\pi}}{2}$$



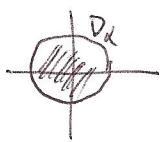
$$E = \int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}$$



Ojokūjūjukas Gauss

$$i) \iint e^{-(x^2+y^2)} dx dy = \int_0^{2\pi} \left(\int_0^a r e^{-r^2} dr \right) d\theta = 2\pi \left(-\frac{e^{-r^2}}{2} \Big|_0^a \right) = \pi (1 - e^{-a^2}) \quad [-188 -]$$

$$D_\alpha = \{(x, y) : \sqrt{x^2 + y^2} \leq a\}$$



'Apa $\iint_{\mathbb{R}^2} (e^{-(x^2+y^2)}) dx dy = \pi$ $\left(\lim_{x \rightarrow +\infty} (e^{-x^2}) = 0 \right)$

$$ii) \pi = \iint_{\mathbb{R}^2} e^{-(x^2+y^2)} dx dy = \int_{-\infty}^{+\infty} \left(\int_{-\infty}^{+\infty} e^{-x^2} dx \right) e^{-y^2} dy$$

$$= \left(\int_{-\infty}^{+\infty} e^{-x^2} dx \right) \cdot \left(\int_{-\infty}^{+\infty} e^{-y^2} dy \right) = \left(\int_{-\infty}^{+\infty} e^{-x^2} dx \right)^2 \Rightarrow \int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}$$

Σημ Το ανωτέρω ορόκλιψης συστήματα περιορίζονται στην Karavali και Gauss (και Karavali Karavali) και λεγούνται αναφέροντας στην "Νότο των Οργανισμών", η οποία πάγια στην Διεύθυνση Μετανομάσιων, γένους στην Κεντρική Οργάνωση Διευπιστήρων. Και δει τώρα.

Gaussian integral

From Wikipedia, the free encyclopedia

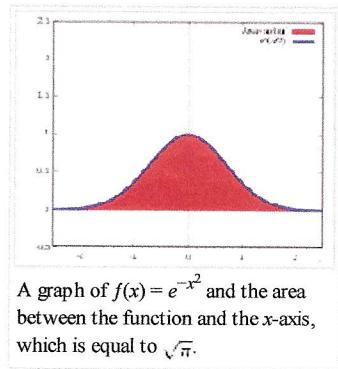
The **Gaussian integral**, also known as the **Euler-Poisson integral** or **Poisson integral**,^[1] is the integral of the Gaussian function e^{-x^2} over the entire real line. It is named after the German mathematician and physicist Carl Friedrich Gauss. The integral is:

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}.$$

This integral has wide applications. When normalized so that its value is 1, it is the density function of the normal distribution. It is closely related to the error function, which is the same integral with finite limits.

Although no elementary function exists for the error function, as can be proven by the Risch algorithm, the Gaussian integral can be solved analytically through the tools of calculus. That is, there is no elementary *indefinite integral* for $\int e^{-x^2} dx$, but the definite integral $\int_{-\infty}^{\infty} e^{-x^2} dx$ can be evaluated.

The Gaussian integral is encountered very often in physics and numerous generalizations of the integral are encountered in quantum field theory.



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Computation

By polar coordinates (Egyetérzés)

A standard way to compute the Gaussian integral is

- consider the function $e^{-(x^2 + y^2)} = e^{-r^2}$ on the plane \mathbf{R}^2 , and compute its integral two ways:
 - on the one hand, by double integration in the Cartesian coordinate system, its integral is a square:
 - on the other hand, by shell integration (a case of double integration in polar coordinates), its integral is computed to be π .

Comparing these two computations yields the integral, though one should take care about the improper integrals involved.

Brief proof

Briefly, using the method above, one computes that on the one hand,

On the other hand,

$$\begin{aligned}
 \int_{\mathbf{R}^2} e^{-(x^2+y^2)} dA &= \int_0^{2\pi} \int_0^\infty e^{-r^2} r dr d\theta \\
 &= 2\pi \int_0^\infty r e^{-r^2} dr \\
 &\equiv 2\pi \int_{-\infty}^0 \frac{1}{2} e^s ds = \pi \int_{-\infty}^0 e^s ds = \pi(e^0 - e^{-\infty}) \\
 &\equiv \pi(1 - 0) \equiv \pi,
 \end{aligned}$$

where the factor of r comes from the transform to polar coordinates ($r dr d\theta$ is the standard measure on the plane, expressed in polar coordinates), and the substitution involves taking $s = -r^2$, so $ds = -2r dr$.

Combining these yields

$$\left(\int_{-\infty}^\infty e^{-x^2} dx \right)^2 = \pi,$$

so

$$\int_{-\infty}^\infty e^{-x^2} dx = \sqrt{\pi}.$$

Careful proof

To justify the improper double integrals and equating the two expressions, we begin with an approximating function:

$$I(a) = \int_{-a}^a e^{-x^2} dx.$$

so that the integral may be found by

$$\lim_{a \rightarrow \infty} I(a) = \int_{-\infty}^\infty e^{-x^2} dx,$$

since

$$\int_{-\infty}^\infty e^{-x^2} dx < \int_{-\infty}^{-1} -xe^{-x^2} dx + \int_{-1}^1 e^{-x^2} dx + \int_1^\infty xe^{-x^2} dx < \infty.$$

Taking the square of $I(a)$ yields

$$\begin{aligned}
 I(a)^2 &= \left(\int_{-a}^a e^{-x^2} dx \right) \cdot \left(\int_{-a}^a e^{-y^2} dy \right) \\
 &= \int_{-a}^a \left(\int_{-a}^a e^{-y^2} dy \right) e^{-x^2} dx \\
 &= \int_{-a}^a \int_{-a}^a e^{-(x^2+y^2)} dx dy.
 \end{aligned}$$

Using Fubini's theorem, the above double integral can be seen as an area integral

taken over a square with vertices $\{(-a, a), (a, a), (a, -a), (-a, -a)\}$ on the xy -plane.

Since the exponential function is greater than 0 for all real numbers, it then follows that the integral taken over the square's incircle must be less than $I(a)^2$, and similarly the integral taken over the square's circumcircle must be greater than $I(a)^2$. The integrals over the two disks can easily be computed by switching from cartesian coordinates to polar coordinates:

(See to polar coordinates from Cartesian coordinates for help with polar transformation.)

Integrating,

By the squeeze theorem, this gives the Gaussian integral
en.wikipedia.org/wiki/Gaussian_integral

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}.$$

By Cartesian coordinates

Georgakis^[2] wrote that the following is "a better alternative to the usual method of reduction to polar coordinates".

Let (1994)

$$y = xs$$

$$dy = x ds.$$

Since the limits on s as y goes to $\pm\infty$ depend on the sign of x , it simplifies the calculation to use the fact that e^{-x^2} is an even function, and, therefore, the integral over all real numbers is just twice the integral from zero to infinity. That is, $\int_{-\infty}^{\infty} e^{-x^2} dx = 2 \int_0^{\infty} e^{-x^2} dx$. Thus, over the range of integration, $x \geq 0$, and the variables y and s have the same limits. This yields:

$$I^2 = 4 \int_0^{\infty} \int_0^{\infty} e^{-(x^2+y^2)} dy dx.$$

Then

$$\begin{aligned} \frac{I^2}{4} &= \int_0^{\infty} \left(\int_0^{\infty} e^{-(r^2+s^2)} dy \right) dx = \int_0^{\infty} \left(\int_0^{\infty} e^{-r^2(1+s^2)} x ds \right) dx \\ &= \int_0^{\infty} \left(\int_0^{\infty} e^{-r^2(1+s^2)} x dr \right) ds \\ &= \int_0^{\infty} \left[\frac{1}{-2(1+s^2)} e^{-r^2(1+s^2)} \right]_0^{\infty} ds - \frac{1}{2} \int_0^{\infty} \frac{ds}{1+s^2} \\ &= \frac{1}{2} \arctan s \Big|_0^{\infty} = \frac{\pi}{4}. \end{aligned}$$

Finally, $I = \sqrt{\pi}$, as expected.

Relation to the gamma function

The integrand is an even function,

$$\int_{-\infty}^{\infty} e^{-x^2} dx = 2 \int_0^{\infty} e^{-x^2} dx$$

Thus, after the change of variable $x = \sqrt{t}$, this turns into the Euler integral

$$2 \int_0^{\infty} e^{-x^2} dx = 2 \int_0^{\infty} \frac{1}{2} e^{-t} t^{-1/2} dt = \Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$$

where Γ is the gamma function. This shows why the factorial of a half-integer is a rational multiple of . More generally,